

# The European School on Magnetism 2022

UNIVERSITE DE LA GRANDE REGION  
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## Fields, magnetostatics, units

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## Fields, magnetostatics, units

### Lecture 1

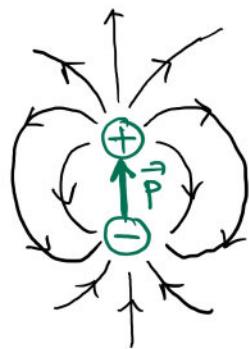
1. Maxwell's equations
2. Poisson's equation and the Biot-Savart Law
3. Multipoles
4. Current loop and dipoles
5. Spin precession

### Lecture 2

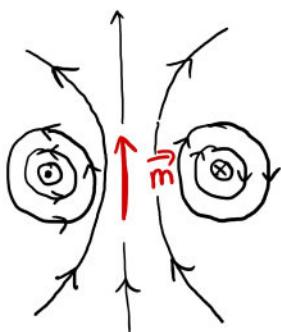
6. Field from a box of dipoles: B and H
7. Linear materials
8. Susceptibility and field calculations
9. Demagnetizing fields
10. Units

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ELECTRIC



MAGNETIC



Field patterns look the same at large  $r$   
but not at small  $r$ .

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Magnetizable materials: in a field  $\vec{B}$   
acquire a magnetization  $\vec{M} = \underline{\text{magnetic}}$   
dipole moment per unit volume

$$\text{e.g. } \vec{M} = n \vec{m}$$

↗ magnetic moment of one  
atom/molecule  
 ↗ number of magnetic atoms/molecules  
per unit volume

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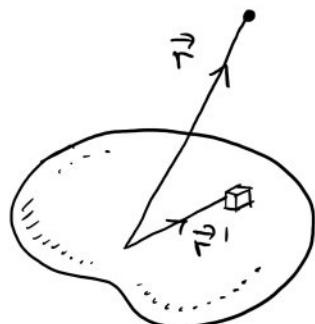
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Field due to a box of magnetic dipole moments



$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{M}(\vec{r}') \times (\vec{r} - \vec{r}') d\tau'}{|\vec{r} - \vec{r}'|^3}$$

$$= \frac{\mu_0}{4\pi} \int \vec{M}(\vec{r}') \times \nabla' \left( \frac{1}{|\vec{r} - \vec{r}'|} \right) d\tau'$$

$$\nabla' \times \frac{\vec{M}}{|\vec{r} - \vec{r}'|} = \frac{1}{|\vec{r} - \vec{r}'|} \nabla' \times \vec{M} - \vec{M} \times \nabla' \frac{1}{|\vec{r} - \vec{r}'|}$$

hence ...

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$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \nabla' \times \frac{\vec{M}(\vec{r}')}{|\vec{r} - \vec{r}'|} d\tau' - \frac{\mu_0}{4\pi} \int \nabla' \times \frac{\vec{M}(\vec{r}')}{|\vec{r} - \vec{r}'|} d\tau'$$

$$\underbrace{\frac{\mu_0}{4\pi} \int_S \frac{\vec{M}(\vec{r}') \times d\vec{S}'}{|\vec{r} - \vec{r}'|}}$$

$$\int_S \vec{A} \cdot d\vec{S} = \int_C \vec{v} \cdot \vec{A} d\tau \quad \text{Put } \vec{A} = \vec{v} \times \vec{c} \quad \text{CONSTANT VECTOR}$$

$$\int_S \vec{v} \times \vec{c} \cdot d\vec{S} = - \vec{c} \cdot \int_S \vec{v} \times d\vec{S} \quad ①$$

$$\int_C \vec{v} \cdot (\vec{v} \times \vec{c}) d\tau = \vec{c} \cdot \int_C \vec{v} \times \vec{v} d\tau - \int_C \vec{v} \cdot (\vec{v} \times \vec{c}) d\tau \quad ②$$

$$\boxed{- \int_S \vec{v} \times d\vec{S} = \int_C \nabla \times \vec{v} d\tau}$$

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$$\Rightarrow \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}_b(\vec{r}') d\tau'}{|\vec{r} - \vec{r}'|} + \frac{\mu_0}{4\pi} \oint \frac{\vec{K}_b(\vec{r}') dS'}{|\vec{r} - \vec{r}'|}$$

where

$$\vec{J}_b = \vec{\nabla} \times \vec{M} \quad \text{bulk, bound current density}$$

$$\vec{K}_b = \vec{M} \times \hat{\vec{n}} \quad \text{surface, bound current density}$$

Logic:  $\vec{M} \Rightarrow \begin{matrix} \vec{J}_b \\ \vec{K}_b \end{matrix} \Rightarrow \vec{A} \Rightarrow \vec{B}$

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Fix up Ampère's law:

$$\vec{\nabla} \times \vec{B} = \mu_0 (\vec{J}_f + \vec{J}_b)$$

$\downarrow \vec{\nabla} \times \vec{M}$

$$\Rightarrow \vec{\nabla} \times \left( \underbrace{\frac{\vec{B}}{\mu_0} - \vec{M}}_{\text{call this } \vec{H}} \right) = \vec{J}_f$$

$$\Rightarrow \vec{\nabla} \times \vec{H} = \vec{J}_f \quad \text{only depends on free currents}$$

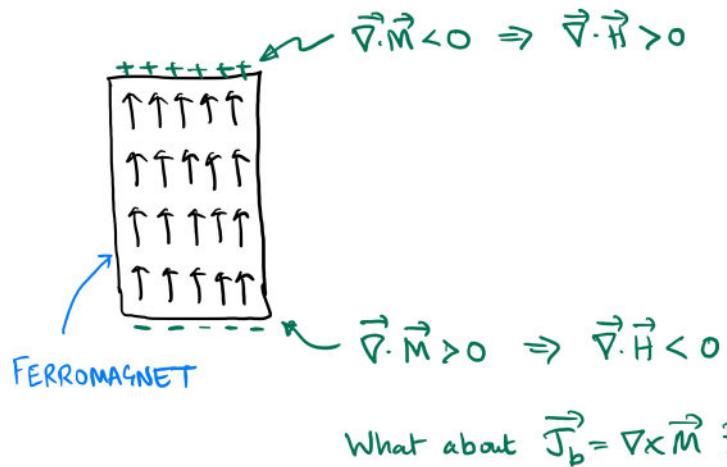
$$\boxed{\vec{B} = \mu_0 (\vec{H} + \vec{M})}$$

in cgs:  $B = H + 4\pi M$  EXPIRED

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BUT other Maxwell equation is worse.

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \vec{\nabla} \cdot \vec{H} = -\vec{\nabla} \cdot \vec{M}$$



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What's the difference between  $B$  and  $H$ ?

Answer #2: Because  $H$  is related to free currents by  $\vec{\nabla} \times \vec{H} = \vec{J}_f$ , it's easy to compute for electromagnets, even with magnetizable materials present

The diagram shows a solenoid with a circular cross-section. It has  $N$  turns of wire and a length  $l$ . A current  $I$  flows through the wire. The magnetic field  $\vec{H}$  is shown as red arrows pointing to the right, parallel to the axis of the solenoid. To the right of the solenoid, the equation  $\oint_c \vec{H} \cdot d\ell = NI$  is written, followed by  $Hl \approx NI$  and  $H = \frac{NI}{l}$ .

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For linear materials,  $\vec{M} \propto \vec{B}$ .

Convention is to write  $\vec{M} = \chi \vec{H}$

magnetic susceptibility (dimensionless)

$$\vec{B} = \mu_0 (\vec{H} + \vec{M}) = \mu_0 (1 + \chi) \vec{H} = \mu \vec{H}$$

permeability

$$\mu = \mu_0 \mu_r = \mu_0 (1 + \chi)$$

relative permeability (dimensionless)

Note, materials are only ever linear within certain limits, and sometimes never linear. e.g.



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$\chi = \frac{M}{H}$  is dimensionless

**EXPIRED** (also in cgs, but there often  $\text{emu cm}^{-3}$ )

Also, mass susceptibility  $\chi_g = \frac{\chi}{\rho}$  ( $\text{m}^3 \text{kg}^{-1}$ )

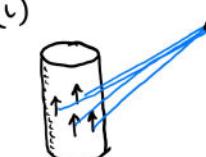
and molar susceptibility  $\chi_m = \chi V_m$  ( $\text{m}^3 \text{mol}^{-1}$ )

**EXPIRED** (in cgs,  $\chi_m$  is in  $\text{emu mol}^{-1}$   
and  $1 \text{ emu mol}^{-1} = 4\pi \times 10^{-6} \text{ m}^3 \text{ mol}^{-1}$ .

The  $4\pi$  comes from  $B = H + 4\pi M$   
and the  $10^{-6}$  comes from  $\text{cm}^3 \leftrightarrow \text{m}^3$ )

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Field calculations

(i)  sum up dipoles  $\vec{B} = \frac{\mu_0}{4\pi} \left[ \frac{3(\vec{m} \cdot \hat{r})\hat{r}}{r^3} - \vec{m} \right]$

(ii)  sum up currents  $\vec{J}_b = \vec{r} \times \vec{M}$  and  $\vec{K}_b = \vec{M} \times \hat{n}$   

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}_b \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} d^3 r' + \frac{\mu_0}{4\pi} \int_S \frac{\vec{K}_b \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} d^2 r'$$

(iii)  sum up "charges"  $\rho_m = -\nabla \cdot \vec{M}$   $\sigma_m = \vec{M} \cdot \hat{n}$   

$$\vec{H}(\vec{r}) = \frac{1}{4\pi} \int_V \frac{\rho_m (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} d^3 r' + \frac{1}{4\pi} \int_S \frac{\sigma_m (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} d^2 r'$$

Last bit:  $\nabla \times \vec{H} = 0 \Rightarrow \vec{H} = -\vec{\nabla} \phi_m$  magnetic scalar potential

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What's the difference between  $B$  and  $H$ ?

Answer #3: It's a bit more complicated!

$B_{\perp}$  is continuous (because  $\vec{\nabla} \cdot \vec{B} = 0$ )

$H_{\parallel}$  is continuous (because  $\vec{\nabla} \times \vec{H} = \vec{J}_f$ )

and so what field is inside your sample depends on the sample shape

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Inside a magnet: DEMAGNETIZING FIELD

$$\vec{H}_d = -\underbrace{\vec{N}(\vec{r})}_{\text{demagnetizing tensor}} \vec{M}$$

(function of position inside the magnet)

Maxwell showed that for an ellipsoid,  $\vec{N}(\vec{r}) = \vec{N}$ .

Also  $\text{Tr } \vec{N} = 1$ .

So put axes along principal axes of the ellipsoid:

$$\vec{N} = \begin{pmatrix} N_{xx} & 0 & 0 \\ 0 & N_{yy} & 0 \\ 0 & 0 & N_{zz} \end{pmatrix} \quad \text{with } N_{xx} + N_{yy} + N_{zz} = 1$$

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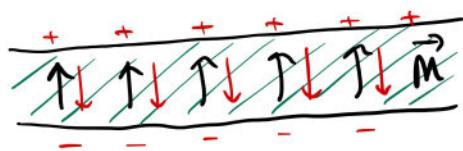
Examples

(i) Thin film ( $xy$  plane)

$$\vec{N} = \begin{pmatrix} 0 & 0 \\ 1 & \end{pmatrix}$$



$$\vec{H}_d = 0$$



$$\vec{H}_d = -\vec{M}$$

**EXPIRED**

NB All demagnetizing factors multiply by  $4\pi$  if using cgs units

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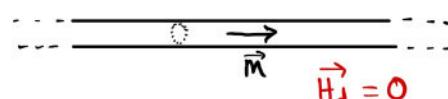
(ii) Sphere



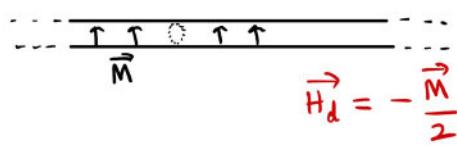
$$\vec{N} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{pmatrix}$$

$$\vec{H}_d = -\frac{\vec{M}}{3}$$

(iii) long rod  $\parallel z$



$$\vec{N} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \end{pmatrix}$$



$$\vec{H}_d = -\frac{\vec{M}}{2}$$

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$$\vec{B} = \mu_0 (\vec{H} + \vec{M}): \quad \vec{H}_d = -\vec{N} \vec{M} \quad \therefore \quad \vec{B}_d = \mu_0 (1-\vec{N}) \vec{M}$$

$$\chi_{\text{experimental}} = \frac{M}{H_{\text{applied}}} \quad \chi_{\text{intrinsic}} = \frac{M}{H_{\text{internal}}}$$

$$H_{\text{internal}} = H_{\text{applied}} - NM$$

$$\Rightarrow \chi_{\text{experimental}} = \frac{M}{H_{\text{internal}} + NM} = \frac{\chi_{\text{intrinsic}}}{1 + N \chi_{\text{intrinsic}}}$$

$$\text{If } \chi_{\text{intrinsic}} \ll 1, \quad \chi_{\text{experimental}} = \chi_{\text{intrinsic}}$$

$$\text{But near } T_c, \quad \chi_{\text{intrinsic}} \rightarrow \infty, \quad \chi_{\text{experimental}} \rightarrow \frac{1}{N}.$$

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### Calculation of demagnetizing field using Fourier transforms

$$D(\mathbf{r}) = \begin{cases} 1 & \mathbf{r} \text{ inside} \\ 0 & \mathbf{r} \text{ outside} \end{cases}$$

$$\mathbf{M}(\mathbf{r}) = M_0 \hat{\mathbf{m}} D(\mathbf{r})$$

$$\mathbf{B}(\mathbf{k}) = \frac{\mu_0 M_0}{k^2} D(\mathbf{k}) (\mathbf{k} \times \hat{\mathbf{m}} \times \mathbf{k})$$

$$B_i = \mu_0 (M_i - \mathcal{N}_{ij} M_j)$$

$$\mathcal{N}_{ij}(\mathbf{k}) = D(\mathbf{k}) \frac{k_i k_j}{k^2}$$

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \mathbf{M}(\mathbf{r}') \times \frac{\mathbf{r} - \mathbf{r}'}{|\mathbf{r} - \mathbf{r}'|^3} d^3 r'$$

$$\mathbf{A}(\mathbf{k}) = \frac{\mu_0}{4\pi} \mathbf{M}(\mathbf{k}) \times \mathcal{F}\left(\frac{\mathbf{r}}{r^3}\right) = -\frac{i\mu_0}{k^2} \mathbf{M}(\mathbf{k}) \times \mathbf{k}.$$

$$\mathbf{A}(\mathbf{k}) = -\frac{iB_0}{k^2} D(\mathbf{k}) (\hat{\mathbf{m}} \times \mathbf{k}),$$

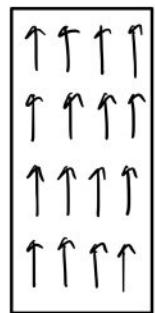
$$\mathbf{B}(\mathbf{k}) = i\mathbf{k} \times \mathbf{A}(\mathbf{k}) = \frac{B_0}{k^2} D(\mathbf{k}) (\mathbf{k} \times \hat{\mathbf{m}} \times \mathbf{k}),$$

$$\mathbf{B} = \mu_0 \mathbf{M} = \frac{B_0}{8\pi^3} \int d^3 \mathbf{k} \frac{D(\mathbf{k})}{k^2} \mathbf{k} (\hat{\mathbf{m}} \cdot \mathbf{k}) \exp(i\mathbf{k} \cdot \mathbf{r}).$$

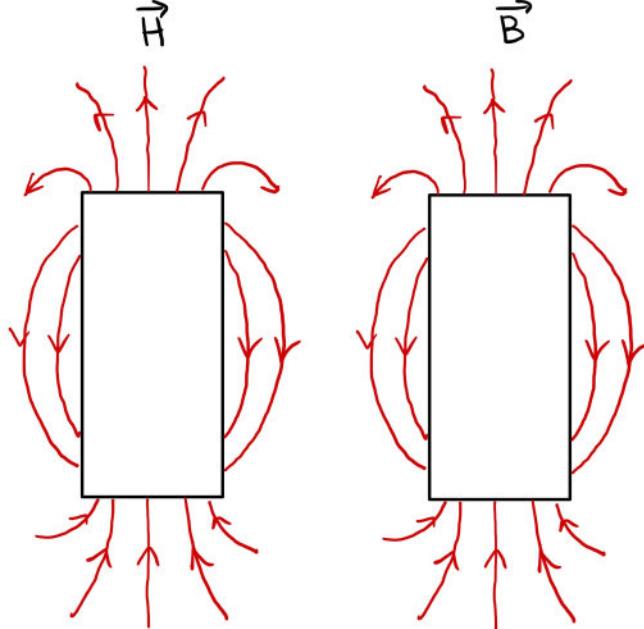
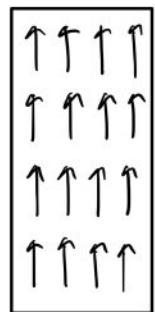
$$\text{Tr}[\mathcal{N}_{ij}(\mathbf{r})] = D(\mathbf{r})$$

M.Beleggia, M.DeGraef, JMMM **263**, L1 (2003); M. Beleggia and Y. Zhu, Phil. Mag. **83**, 1045 (2003); M. Beleggia et al. JMMM **278**, 270 (2004).

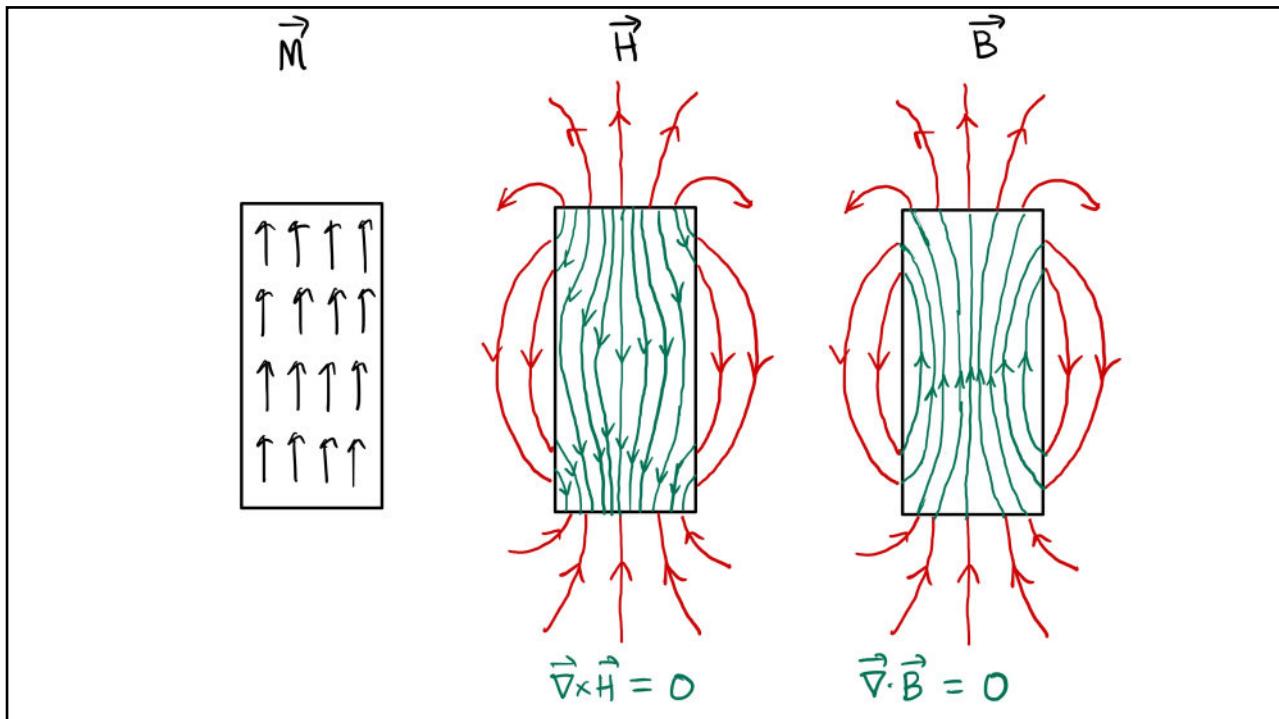
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$\vec{M}$ 

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 $\vec{M}$  $\vec{H}$  $\vec{B}$ 

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What's the difference between B and H?

Answer #4 : The two fields are related by

$$\vec{B} = \mu_0 (\vec{H} + \vec{M}) \text{ and we need both!}$$

- $\vec{B}$  is more fundamental, and has the "pleasing" divergence equation.  $\vec{\nabla} \cdot \vec{B} = 0$  ( $\vec{\nabla} \cdot \vec{H} = -\vec{\nabla} \cdot \vec{M}$ )
- $\vec{H}$  has the nicer curl equation  $\vec{\nabla} \times \vec{H} = \vec{J}_f$  ( $\frac{\vec{\nabla} \times \vec{B}}{\mu_0} = \vec{J}_f + \vec{J}_b$ )

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### Unit conversion (SI to cgs)

Table A.1: Units in the SI system and the cgs system. The abbreviations are m = metre, g = gramme, N = Newton, J = Joule, T = Tesla, G = Gauss, A = Amp, Oe = Oersted, Wb = Weber, Mx = Maxwell. The term emu is short for electromagnetic unit. Note that magnetic susceptibility is dimensionless in SI units.

Quantity	symbol	SI unit	cgs unit
Length	$x$	$10^{-2}$ m	= 1 cm
Mass	$m$	$10^{-3}$ kg	= 1 g
Force	$F$	$10^{-5}$ N	= 1 dyne
Energy	$E$	$10^{-7}$ J	= 1 erg
Magnetic induction	$B$	$10^{-4}$ T	= 1 G
Magnetic field strength	$H$	$10^3/4\pi$ A m $^{-1}$	= 1 Oe
Magnetic moment	$\mu$	$10^{-3}$ JT $^{-1}$ or A m $^2$	= 1 erg G $^{-1}$
Magnetization (= moment per volume)	$M$	$10^3$ A m $^{-1}$ or JT $^{-1}$ m $^{-3}$	= 1 Oe
Magnetic susceptibility	$\chi$	$4\pi$	= 1 emu cm $^{-3}$
Molar susceptibility	$\chi_m$	$4\pi \times 10^{-6}$ m $^3$ mol $^{-1}$	= 1 emu mol $^{-1}$
Mass susceptibility	$\chi_g$	$4\pi \times 10^{-3}$ m $^3$ kg $^{-1}$	= 1 emu g $^{-1}$
Magnetic flux	$\phi$	$10^{-8}$ Tm $^2$ or Wb	= 1 G cm $^{-2}$ or Mx
Demagnetization factor	$N$	$0 < N < 1$	$0 < N < 4\pi$

EXPIRED

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