

The European School on Magnetism 2022

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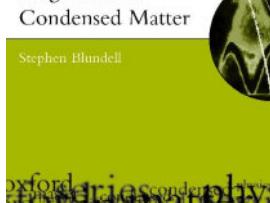
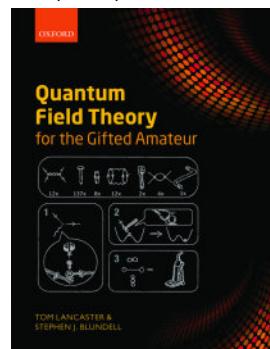
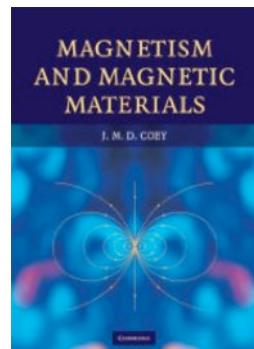
Fields, magnetostatics, units

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1

Books

Magnetism in Condensed Matter, S.J. Blundell, OUP (2001)
 Magnetism and Magnetic Materials, J.M.D. Coey, CUP (2009)
 Basic aspects of the quantum theory of magnetism, D.I. Khomskii, CUP(2010)
 Magnetism: A Very Short Introduction, S. J. Blundell, OUP (2012)

 <p>Magnetism in Condensed Matter Stephen Blundell amazon.de</p>	 <p>Stephen J. Blundell MAGNETISM A Very Short Introduction OXFORD</p>	 <p>Quantum Field Theory for the Gifted Amateur TOM LANCASTER & STEPHEN J. BLUNDELL</p>	 <p>MAGNETISM AND MAGNETIC MATERIALS J. M. D. COEY</p>
<p>Magnetism in Condensed Matter, S.J. Blundell, 32 Euros from amazon.de</p>	<p>Magnetism: VSI S.J. Blundell, 11 Euros</p>	<p>Quantum Field Theory for the Gifted Amateur T. Lancaster and S.J. Blundell, 35 Euros</p>	<p>Magnetism and Magnetic Materials J. M. D. Coey, 52 Euros from amazon.de</p>

2

Fields, magnetostatics, units

Lecture 1

1. Maxwell's equations
2. Poisson's equation and the Biot-Savart Law
3. Multipoles
4. Current loop and dipoles
5. Spin precession

Lecture 2

6. Field from a box of dipoles: B and H
7. Linear materials
8. Susceptibility and field calculations
9. Demagnetizing fields
10. Units

3

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4

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5

Maxwell's equations:

$$(1) \quad \vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \Rightarrow \int_S \vec{E} \cdot d\vec{S} = \frac{Q}{\epsilon_0} \quad \text{with } \int_V e^{d\tau}$$

$$(2) \quad \vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \int_S \vec{B} \cdot d\vec{S} = 0$$

$$(3) \quad \vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \Rightarrow \oint \vec{E} \cdot d\vec{l} = - \frac{d}{dt} \int_S \vec{B} \cdot d\vec{S}$$

$$(4) \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

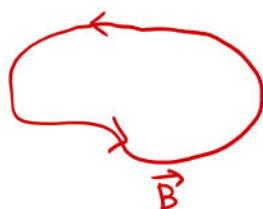
$$\Rightarrow \oint \vec{B} \cdot d\vec{l} = \underbrace{\mu_0 \int_S \vec{J} \cdot d\vec{S}}_{I_{\text{enclosed}}} + \mu_0 \epsilon_0 \frac{d}{dt} \int_S \vec{E} \cdot d\vec{S}$$

9

First two laws \Rightarrow



Electric field starts and stops on charges



Magnetic field only goes round in loops. It doesn't start or stop on anything.

10

B is the magnetic flux density or magnetic induction (officially), but it is often just the "magnetic field" or the "B-field".

Measured in tesla (T) A BIG UNIT

e.g.	interstellar space	$\sim nT$
	Earth's surface	$\sim 50 \mu T$
	strong electromagnet	$\sim 1T$
	superconducting magnet	$\sim 1-20T$
	pulsed field	$\sim 50-100T$
	explosive flux compression	$\sim 2000T$
	neutron star/magnetar	$\sim 10^9 - 10^{12}T$

11

EXPIRED

Old-fashioned units: B measured in Gauss.

$$[10^4 \text{ G} \equiv 1 \text{ T.}]$$

In free space, we can also use the H field (magnetic field strength) given by $\vec{B} = \mu_0 \vec{H}$ where $\mu_0^* \equiv 4\pi \times 10^{-7} \text{ H m}^{-1}$ so that H is measured in A m^{-1} .

EXPIRED

Old-fashioned units: H measured in Oersted, and $B = \mu_0 H$ becomes $B = H$, so $1 \text{ G} = 1 \text{ Oe}$.

* Since 2018, this has no longer been definitional. But very close!

12

What's the difference between B and H ?

Answer #1: In free space, nothing!

There is just a scale factor between them.

$$\vec{B} = \mu_0 \vec{H}$$

13

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14

Electrostatics:

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \quad \rightarrow \quad \nabla \cdot (-\nabla V) = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \times \vec{E} = 0 \quad \rightarrow \quad \vec{E} = -\nabla V \quad \Rightarrow \quad \boxed{\nabla^2 V = -\frac{\rho}{\epsilon_0}}$$

$\frac{\partial \vec{B}}{\partial t} = 0$ because statics

Poisson's Equation

Magnetostatics:

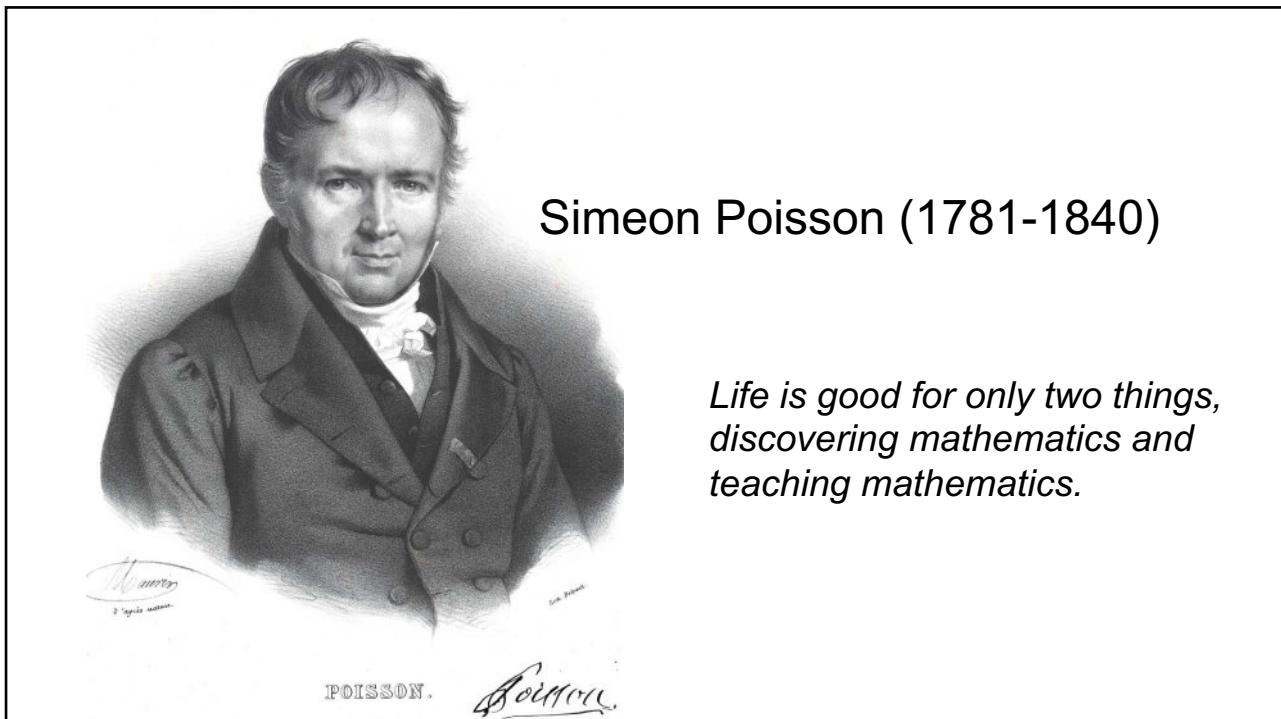
$$\vec{\nabla} \cdot \vec{B} = 0 \quad \Rightarrow \quad \vec{B} = \nabla \times \vec{A} \quad \text{MAGNETIC VECTOR POTENTIAL}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \quad \Rightarrow \quad \underbrace{\vec{\nabla} \times (\vec{\nabla} \times \vec{A})}_{-\nabla^2 \vec{A} + \nabla(\nabla \cdot \vec{A})} = \mu_0 \vec{J}$$

choose $\vec{\nabla} \cdot \vec{A} = 0$ (can do this because $\vec{A} \rightarrow \vec{A} + \vec{\nabla} \chi$ gives same \vec{B} , so $\vec{\nabla} \cdot \vec{A} \rightarrow \vec{\nabla} \cdot \vec{A} + \nabla^2 \chi$)

$$\Rightarrow \boxed{\nabla^2 \vec{A} = -\mu_0 \vec{J}}$$

15



16

Electrostatic Poisson equation

$$\nabla^2 V = -\frac{\rho}{\epsilon_0} \Rightarrow V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}') d\tau'}{|\vec{r}' - \vec{r}|}$$

Magnetostatic Poisson equation

$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

think of as 3 independent
Poisson equations

$$\nabla^2 A_x = -\mu_0 J_x \text{ etc}$$

$$\Rightarrow \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') d\tau'}{|\vec{r}' - \vec{r}|}$$

17

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') d\tau'}{|\vec{r}' - \vec{r}|}$$

confine the volume to a line

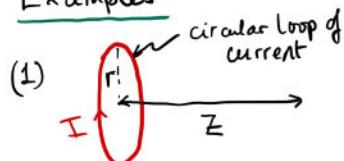
$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{I}(\vec{r}') d\ell'}{|\vec{r}' - \vec{r}|}$$

$$\begin{aligned}\vec{B}(\vec{r}) &= \nabla \times \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{I} \times (\vec{r}' - \vec{r}) d\ell'}{|\vec{r}' - \vec{r}|^3} \\ &= \frac{\mu_0}{4\pi} I \int \frac{d\ell' \times (\vec{r}' - \vec{r})}{|\vec{r}' - \vec{r}|^3}\end{aligned}$$

The Biot-Savart law.

18

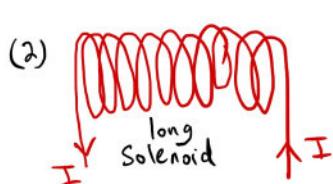
Examples



$$B(z) = \frac{\mu_0 I r^2}{2(r^2 + z^2)^{3/2}}$$

Proof: $\sin \theta = \frac{z}{(r^2 + z^2)^{1/2}}$

Biot-Savart: $B = \frac{\mu_0}{4\pi} \cdot \frac{2\pi a I}{(r^2 + z^2)} \sin \theta \rightarrow \text{result}$



Field inside $B = \mu_0 n I$

NUMBER OF
TURNS PER
UNIT LENGTH

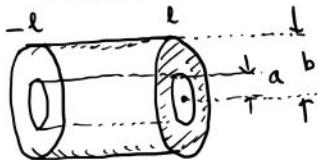
by direct integration of previous result
or (quicker) by Ampère's theorem

$$\nabla \times \vec{B} = \mu_0 \vec{J}$$

19

Hard examples

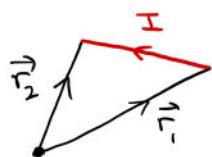
(3)



(fill in the gaps, if keen!)

$$\begin{aligned} B \text{ at centre} &= \frac{\mu_0 J}{2} \int_a^b r^2 dr \int_{-l}^l \frac{dz}{(r^2 + z^2)^{3/2}} \\ &= \mu_0 J l \ln \left(\frac{\alpha + \sqrt{\alpha^2 + \beta^2}}{1 + \sqrt{1 + \beta^2}} \right) \quad \alpha = \frac{b}{a}, \beta = \frac{l}{a} \end{aligned}$$

(4)

straight-line section $\vec{r} = \vec{r}_1 + \lambda (\vec{r}_2 - \vec{r}_1)$

$$\begin{aligned} \vec{B} &= \frac{\mu_0 I}{4\pi} \vec{r}_1 \times \vec{r}_2 \int_0^1 \frac{d\lambda}{r^2} \quad \text{from } 0 \text{ to } 1 \\ &= \frac{\mu_0 I}{4\pi} \frac{\vec{r}_1 \times \vec{r}_2}{r_1 r_2} \frac{\vec{r}_1 + \vec{r}_2}{(\vec{r}_1 \cdot \vec{r}_2 + \vec{r}_1 \cdot \vec{r}_2)} \end{aligned}$$

20

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21

Legendre polynomials

$$P_0(x) = 1$$

$$P_2(x) = \frac{1}{2}(3x^2 - 1)$$

$$P_4(x) = \frac{1}{8}(35x^4 - 30x^2 + 3)$$

$$P_1(x) = x$$

$$P_3(x) = \frac{1}{2}(5x^3 - 3x)$$

$$P_5(x) = \frac{1}{8}(63x^5 - 70x^3 + 15x)$$



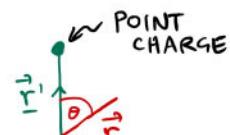
Adrien Marie-Legendre (1752-1833)

22

Point charge at \vec{r}'

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{1}{|\vec{r}' - \vec{r}|}$$

Put $\vec{r}' \parallel \hat{z}$



Solution to Laplace's equation

$$\Rightarrow V(\vec{r}) = \sum_{l=0}^{\infty} \left(A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos \theta).$$

Match them, and put \vec{r}' up the z -axis too so $\theta = 0$

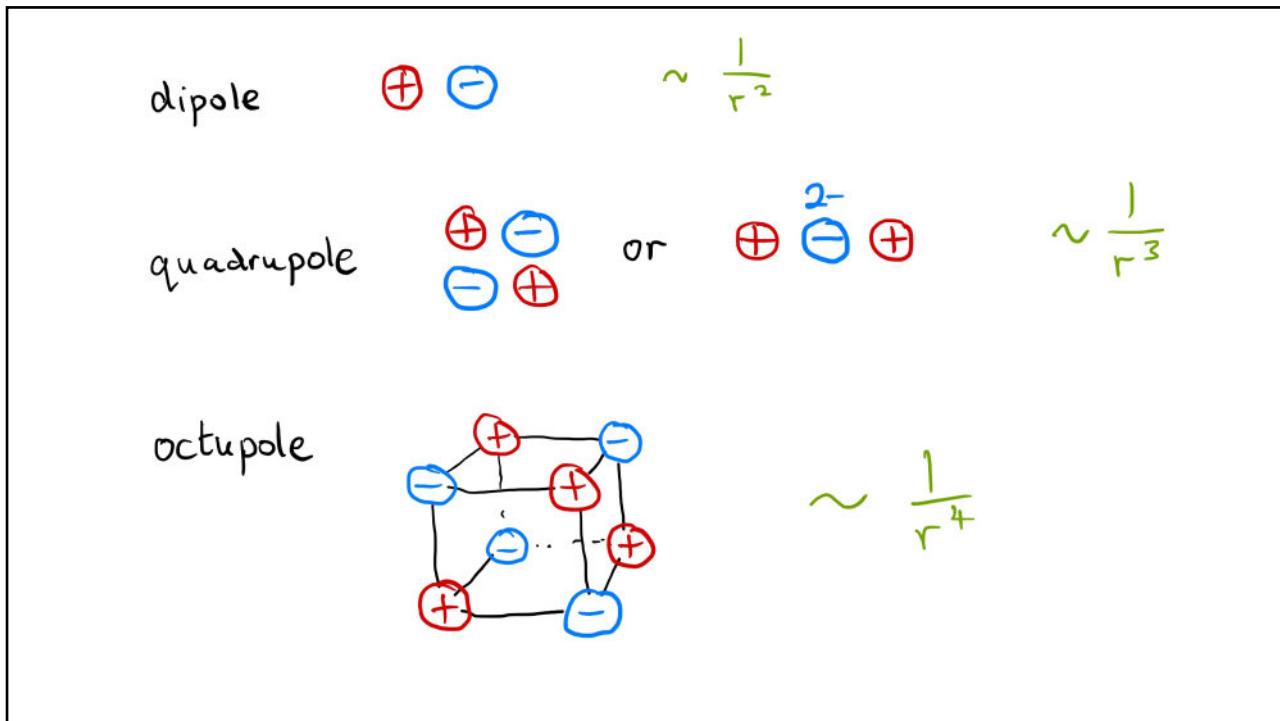
$$\Rightarrow \frac{1}{4\pi\epsilon_0} \frac{1}{|\vec{r}' - \vec{r}|} = \sum_{l=0}^{\infty} A_l r^l + \frac{B_l}{r^{l+1}}$$

$$\text{but } \frac{1}{|\vec{r}' - \vec{r}|} = \frac{1}{r} \sum_{l=0}^{\infty} \left(\frac{r'}{r} \right)^l \text{ for } r' < r$$

$$\Rightarrow \text{in general } V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \frac{1}{r} \left(\frac{r'}{r} \right)^l P_l(\cos \theta) \quad r' < r$$

MULTIPOLE EXPANSION

23



24

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25

Here is the proof of a useful vector identity. First recall Stokes' theorem which states that

$$\int \nabla \times \mathbf{A} \cdot d\mathbf{S} = \oint \mathbf{A} \cdot d\mathbf{l}. \quad (1)$$

Now put $\mathbf{A}(\mathbf{r}) = f(\mathbf{r})\mathbf{c}$ where $\mathbf{c} \neq \mathbf{c}(\mathbf{r})$ is a constant vector. Hence we have

$$\nabla \times \mathbf{A} = f \nabla \times \mathbf{c} - \mathbf{c} \times \nabla f = -\mathbf{c} \times \nabla f \quad (2)$$

since $\nabla \times \mathbf{c} = 0$ (because \mathbf{c} is a constant vector, its derivative vanishes). Stokes' theorem then gives us

$$\oint \mathbf{A} \cdot d\mathbf{l} = \mathbf{c} \cdot \oint f d\mathbf{l} = - \int \mathbf{c} \times \nabla f \cdot d\mathbf{S} = -\mathbf{c} \cdot \int \nabla f \times d\mathbf{S}, \quad (3)$$

but this is true for any \mathbf{c} and so

$$\boxed{\oint f d\mathbf{l} = - \int \nabla f \times d\mathbf{S}.} \quad (4)$$

Now let us choose $f = \hat{\mathbf{r}} \cdot \mathbf{r}'$ and take the gradient and integral around a closed loop in the primed coordinates:

$$\oint (\hat{\mathbf{r}} \cdot \mathbf{r}') d\mathbf{l}' = - \int \nabla' (\hat{\mathbf{r}} \cdot \mathbf{r}') \times d\mathbf{S}' = -\hat{\mathbf{r}} \times \int d\mathbf{S}' \quad (5)$$

which works because $\nabla' (\hat{\mathbf{r}} \cdot \mathbf{r}') = \hat{\mathbf{r}}$. In summary:

$$\boxed{\oint \hat{\mathbf{r}} \cdot \mathbf{r}' d\mathbf{l}' = \left(\int d\mathbf{S}' \right) \times \hat{\mathbf{r}}.} \quad (6)$$

26

Current loop

$$\begin{aligned} \vec{A}(\vec{r}) &= \frac{\mu_0 I}{4\pi} \oint \frac{d\vec{l}'}{|\vec{r} - \vec{r}'|} \\ &= \frac{\mu_0 I}{4\pi} \sum_{n=0}^{\infty} \frac{1}{r^{n+1}} \oint \left(\frac{\vec{r}'}{r} \right)^n P_n(\cos \theta) \vec{d}\vec{l}' \\ &\text{n=0 term is zero} \\ A_0(\vec{r}) &= \underbrace{\frac{\mu_0 I}{4\pi r} \oint \vec{d}\vec{l}'}_0 = 0 \end{aligned}$$

$n=1$ term next most significant:

$$A_1(\vec{r}) = \frac{\mu_0 I}{4\pi r^2} \oint \underbrace{\vec{r}' \cos \theta'}_{\vec{r}' \cdot \hat{\vec{r}}} \frac{\vec{d}\vec{l}'}{|\vec{r}'|} = \frac{\mu_0}{4\pi r^2} \vec{m} \times \hat{\vec{r}}$$

where the magnetic dipole moment $\vec{m} = I \int d\mathbf{S}' = I \vec{S}$
vector area of loop

27

Magnetic moment = current \times area

Units: A m^2

Example: Intrinsic magnetic moment of an electron is 1 Bohr magneton

$$\mu_B = \frac{e\hbar}{2m_e} = 9.274 \times 10^{-24} \text{ A m}^2.$$

NB $1 \text{ A m}^2 = 1 \text{ JT}^{-1}$.

EXPIRED In cgs, use erg G^{-1} and $1 \text{ erg G}^{-1} = 10^3 \text{ JT}^{-1}$.

28

Put $\vec{m} \parallel z$ in spherical polar:

$$\vec{A}_1(\vec{r}) = \frac{\mu_0 m}{4\pi r^2} m \sin\theta \hat{\phi}$$

$$\begin{aligned} \vec{B}_1(\vec{r}) &= \nabla \times \vec{A}_1(\vec{r}) = \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial \theta} (r \sin\theta A_\phi) \hat{r} \\ &\quad - \frac{1}{r \sin\theta} \frac{\partial}{\partial r} (r \sin\theta A_\phi) \hat{\theta} \end{aligned}$$

$$(A_r = A_\theta = 0)$$

$$= \frac{\mu_0 m}{4\pi} \left(\frac{2 \cos\theta}{r^3} \hat{r} + \frac{\sin\theta}{r^3} \hat{\theta} \right)$$

Exactly the same as for an electric dipole at sufficiently large r .

29

We will use this to show that the magnetic vector potential from a magnetic dipole by

$$\mathbf{A} = \frac{\mu_0}{4\pi r^2} \mathbf{m} \times \hat{\mathbf{r}},$$

where \mathbf{m} is the magnetic dipole moment.

For example, if we put \mathbf{m} parallel to z and use spherical polars, we have that

$$\mathbf{A} = \frac{\mu_0}{4\pi r^2} m \sin \theta \hat{\phi},$$

and so

$$\mathbf{B} = \nabla \times \mathbf{A}(\mathbf{r}) = \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (r \sin \theta A_\phi) \hat{\mathbf{r}} - \frac{1}{r \sin \theta} \frac{\partial}{\partial r} (r \sin \theta A_\phi) \hat{\theta},$$

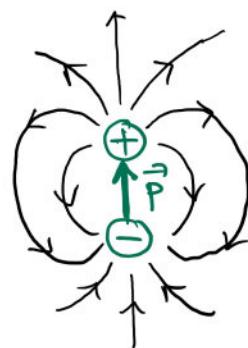
because $A_r = A_\theta = 0$ and hence

$$\mathbf{B} = \frac{\mu_0 m}{4\pi} \left(\frac{2 \cos \theta}{r^3} \hat{\mathbf{r}} + \frac{\sin \theta}{r^3} \hat{\theta} \right),$$

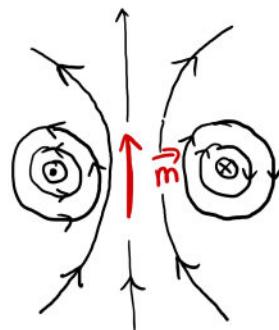
which is the same form as an electric dipole.

30

ELECTRIC



MAGNETIC



Field patterns look the same at large r
but not at small r .

31

Magnetizable materials: in a field \vec{B}
 acquire a magnetization $\vec{M} = \underline{\text{magnetic}} \underline{\text{dipole moment per unit volume}}$

$$\text{e.g. } \vec{M} = n \vec{m}$$


 magnetic moment of one
 atom/molecule
 number of magnetic atoms / molecules
 per unit volume

32

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33

State of the system described by $|\psi\rangle$



$$\begin{array}{c} |\psi\rangle = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \vdots \\ \psi_N \end{pmatrix} \\ \text{ket} \end{array} \quad \langle\psi| = (\psi_1^* \quad \psi_2^* \quad \dots \quad \psi_N^*) \quad \text{bra}$$

$$\langle\phi|\psi\rangle = (\phi_1^* \quad \phi_2^* \quad \dots \quad \phi_N^*) \begin{pmatrix} \psi_1 \\ \psi_2 \\ \vdots \\ \psi_N \end{pmatrix} = \phi_1^*\psi_1 + \dots + \phi_N^*\psi_N = \text{complex number}$$

bra-c-ket

34

Magnetic moment and angular momentum

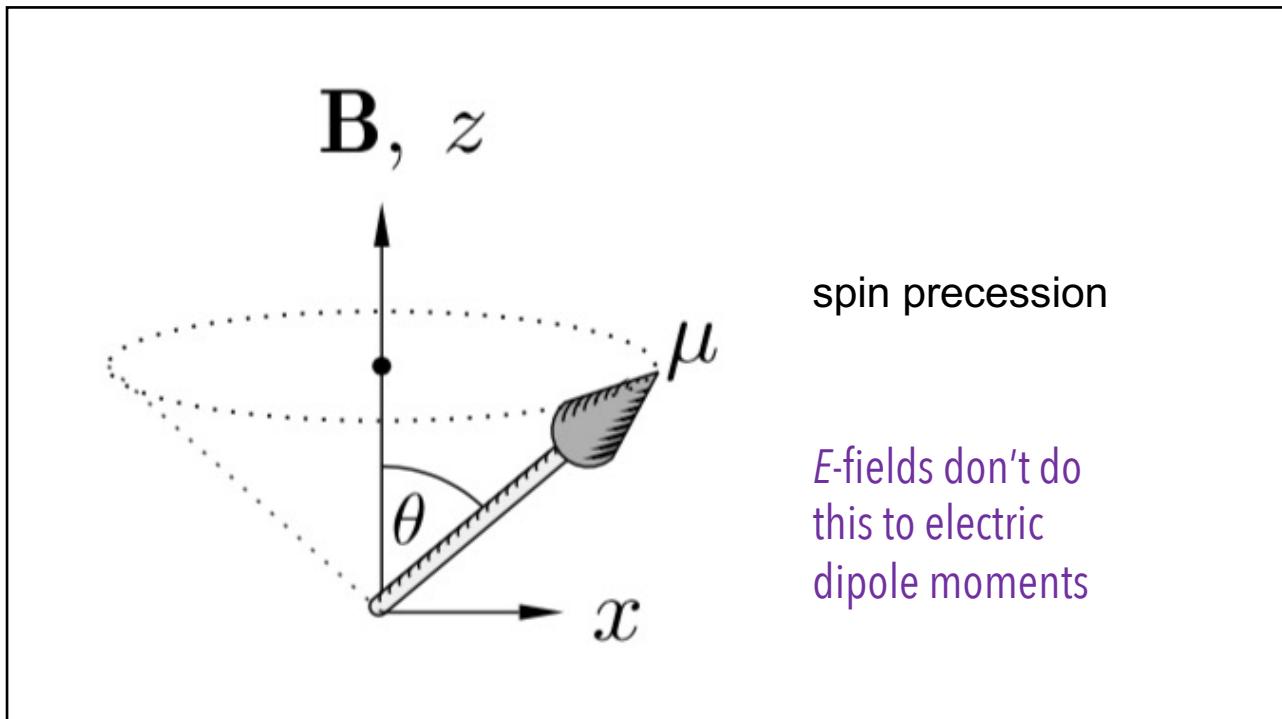
$$\vec{\mu} = \gamma \vec{L}$$

magnetic moment *angular momentum*



$$\text{gyromagnetic ratio} = \frac{gq}{2m}$$

35



36

Classical treatment of spin precession

$$\left. \begin{array}{l} \text{energy} \\ E = -\vec{\mu} \cdot \vec{B} \\ \vec{G}_t = \vec{\mu} \times \vec{B} \end{array} \right\} \quad \frac{d\vec{\mu}}{dt} = \gamma \vec{\mu} \times \vec{B}$$

torque

\vec{z}

\vec{B}

$\vec{\mu}$

$\dot{\left(\begin{array}{c} \mu_x \\ \mu_y \\ \mu_z \end{array} \right)} = \left(\begin{array}{c} \gamma B \mu_y \\ -\gamma B \mu_x \\ 0 \end{array} \right) \Rightarrow \begin{array}{l} \mu_x(t) = |\vec{\mu}| \sin \theta \cos \omega t \\ \mu_y(t) = -|\vec{\mu}| \sin \theta \sin \omega t \\ \mu_z(t) = |\vec{\mu}| \cos \theta \end{array}$

SPIN PRECESSION $\omega = \gamma \mu B$

37

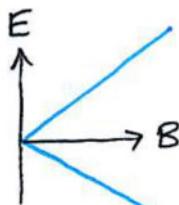
Quantum mechanics of spin- $\frac{1}{2}$

$$|4\rangle = a|1\uparrow\rangle + b|1\downarrow\rangle = \begin{pmatrix} a \\ b \end{pmatrix} \leftarrow \text{SPINOR}$$

$$|1\uparrow\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad |1\downarrow\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\hat{H} = -\vec{\mu} \cdot \vec{B} = -\frac{\hbar}{2} \gamma B \sigma_z = -\frac{\hbar\omega}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\vec{S} = \frac{\hbar}{2} \vec{\sigma}$$



$$E = \frac{\hbar\omega}{2}$$

$$E = -\frac{\hbar\omega}{2}$$

Zeeman splitting

38

Pauli spin matrices

$$\vec{\sigma} = (\sigma_x, \sigma_y, \sigma_z)$$

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$\sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$



For a general direction \hat{n}

$$\hat{n} \cdot \vec{\sigma} = \begin{pmatrix} n_z & n_x - i n_y \\ n_x + i n_y & -n_z \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta e^{-i\phi} \\ \sin \theta e^{i\phi} & -\cos \theta \end{pmatrix}$$

Eigenstates are $|+\rangle = \begin{pmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} e^{i\phi} \end{pmatrix} \quad |- \rangle = \begin{pmatrix} \sin \frac{\theta}{2} \\ \cos \frac{\theta}{2} e^{i\phi} \end{pmatrix}$

39



Pauli spin matrices									
σ_x	σ_y	σ_z	Eigenstates						
$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$	$ \uparrow_x\rangle$	$ \downarrow_x\rangle$	$ \uparrow_y\rangle$	$ \downarrow_y\rangle$	$ \uparrow_z\rangle$	$ \downarrow_z\rangle$	
$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$	$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$	$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$	$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix}$		$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$	$\begin{pmatrix} 0 \\ 1 \end{pmatrix}$			

40

Quantum mechanical treatment of spin precession (1)

$B \parallel z$ Initial muon polarization

$$|4(0)\rangle = \begin{pmatrix} \cos \theta/2 \\ \sin \theta/2 \end{pmatrix} = \cos \frac{\theta}{2} |\uparrow\rangle + \sin \frac{\theta}{2} |\downarrow\rangle$$

Time-dependence : $\hat{H}|4\rangle = i\hbar \frac{d}{dt}|4\rangle$

$$|4(t)\rangle = e^{i\omega t/2} \cos \frac{\theta}{2} |\uparrow\rangle + e^{-i\omega t/2} \sin \frac{\theta}{2} |\downarrow\rangle$$

$$\begin{aligned} \langle 4(t) | \sigma_x | 4(t) \rangle &= \sin \theta \cos \omega t \\ \langle 4(t) | \sigma_y | 4(t) \rangle &= -\sin \theta \sin \omega t \\ \langle 4(t) | \sigma_z | 4(t) \rangle &= \cos \theta \end{aligned} \left. \right\} \text{spin precession}$$

41

Quantum mechanical treatment of spin precession (2)

Time-evolution operator $\hat{H} = -\frac{\hbar\omega}{2} \vec{n} \cdot \vec{\sigma}$

$$\hat{U}(t) = e^{-i\hat{H}t/\hbar} = \cos \frac{\omega t}{2} I + i \sin \frac{\omega t}{2} \underbrace{\hat{n} \cdot \vec{\sigma}}_{\sigma_z}$$

$$|\psi(t)\rangle = \hat{U}(t)|\psi(0)\rangle = \begin{pmatrix} \cos \frac{\omega t}{2} + i \sin \frac{\omega t}{2} & 0 \\ 0 & \cos \frac{\omega t}{2} - i \sin \frac{\omega t}{2} \end{pmatrix} \begin{pmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{pmatrix}$$

$$= \begin{pmatrix} e^{i\omega t/2} \cos \frac{\theta}{2} \\ e^{-i\omega t/2} \sin \frac{\theta}{2} \end{pmatrix} \quad \rightarrow \text{same result}$$

42

Fields, magnetostatics, units

Lecture 1

1. Maxwell's equations
2. Poisson's equation and the Biot-Savart Law
3. Multipoles
4. Current loop and dipoles
5. Spin precession

Lecture 2

6. Field from a box of dipoles: B and H
7. Linear materials
8. Susceptibility and field calculations
9. Demagnetizing fields
10. Units

43