



THE EUROPEAN SCHOOL ON  
**MAGNETISM**

# **MAGNETIC ENERGY AND CIRCUITS**

R&D and Large Volume Production of Electrical Drives Systems

AE Group; Industrieweg 78; 5145PW Waalwijk; The Netherlands ; [www.ae-grp.nl](http://www.ae-grp.nl); [info@ae-grp.nl](mailto:info@ae-grp.nl)

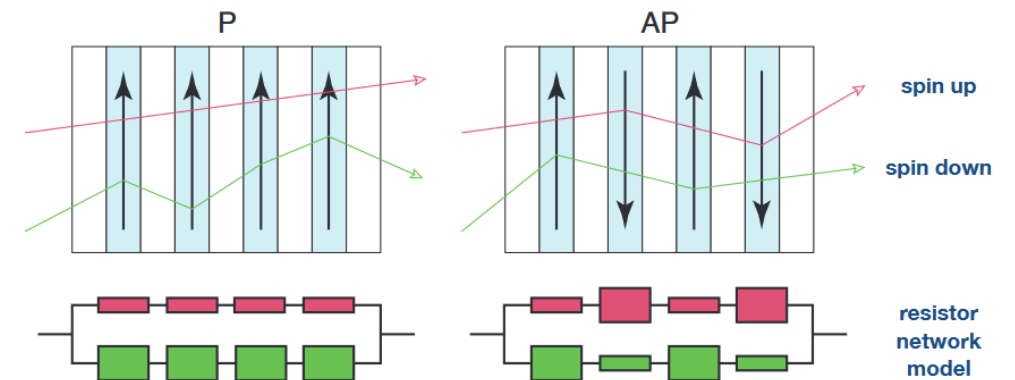
# BACKGROUND MATERIAL

- Resistor network....
  - It is actually an electrical equivalent circuit
- Lecture 1
  - Explanation of magnetic equivalent circuit
  - Energy from electrical via magnetic to electrical, while producing torque
  - Some basics about flux (or better said equipotential contours)



## Phenomenological model

- How can we understand the giant magnetoresistance based on what we've learnt about spin-dependent transport?
- Consider how electrons propagate through parallel and antiparallel alignment of magnetization in a superlattice structure



- Basic resistor model tells us that there ought to be a difference in the overall resistance of the two configurations

# PERSONAL INFO



Family owned businessman, third generation. Established in 1938.

MPhil and PhD in electric machine and drives group from Sheffield, a large and highly ranked university group on electrical drives in the world. Followed by 12.5 years in various roles at Eindhoven University of Technology, subject more sustainable society (includes automotive).

Owner of AE Group a number of companies related to design and manufacturing of electrical drives. Author of more than 150 papers and numerous patents, organizer and invited speaker at a variety of conferences related to electrical machines and drives, from medical, robotics to automotive topics.



- Johan Paulides
  - Johannes Jacobus Hubertus Paulides
  - Owner of the AE Group; Industrieweg 78; 5145PW Waalwijk; [www.ae-grp.nl](http://www.ae-grp.nl); [info@ae-grp.nl](mailto:info@ae-grp.nl)



# 80+ YEARS EXPERIENCE - FIRST VEHICLE CONVERSION (1968)

**RIJKSDIENST VOOR HET WEGVERKEER**

**ONTVANGBEWIJS**

Betreft kenteken-/registratiebewijs **SV-36-49**

afgegeven voor personenauto, motorfiets, bedrijfsauto, oplegger, aanhangwagen

Mark **Citroen**

chassis-/tracment. **110066**

Bovengenoemd bewijs moet worden gewijzigd/aangevuld en is in verband hiermede door ondergetekende in ontvangst genomen.

Bovengenoemd bewijs is **NA VORDERING** ingevolge art. 13 lid 1 van de Wagenverkeerswet aan ondergetekende overgegeven.

**REDEN VAN VORDERING:**

Het voertuig is niet overeenkomstig de in het bewijs vermelde gegevens.

Het voertuig voldoet niet aan bij of krachtens de Wagenverkeerswet gestelde eisen.

Aan krachtens art. 94 van het Wagenverkeersreglement in het bewijs vermelde voorwaarde(n) is niet voldaan.

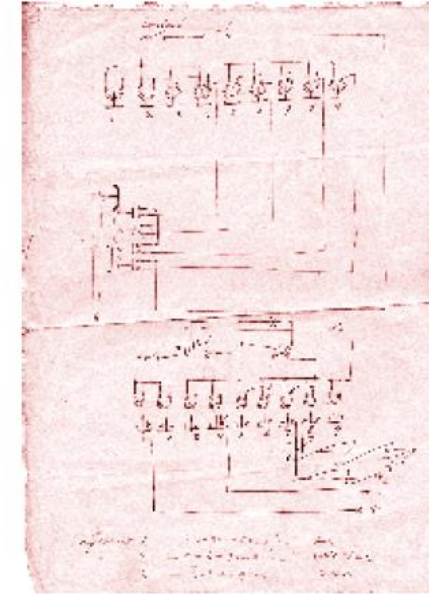
In ontvangst genomen dd. **21-2-1968**

de daartoe bevoegde ambtenaar: *[Signature]*

Verdere afhandeling door het Hoofdkantoor te

**DIT BEWIJS ZORGVULDIG B**

Model R.D.W. nr. 312 - 6240 - 60



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**DIT BEWIJS ZORGVULDIG B**

Model R.D.W. nr. 312 - 6240 - 60

## Elektrische auto

Op dit moment is er een steeds grotere commerciële vraag naar zuinige hybride voertuigen (b.v. Toyota Prius, Honda Civic, etc.), maar al in de zeventiger jaren reed er in Sprang-Capelle een omgebouwde Citroën met een 48VDC motor. Hierin waren vier vrachtwagen accu's ingebouwd welke allemaal in parallel (12VDC), serie-parallel (24VDC) of in serie (48VDC) geschakeld konden worden d.m.v. start relais. Deze werden ingeschakeld door een driestanden gaspedaal. Ook de versnellingsbak was nog aanwezig, daardoor er vooraf gekozen kon worden hoe snel men wilde rijden (max 70km/uur) al kostte dat dan wel actieradius.

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# E-MACHINES R&D AND PRODUCTION

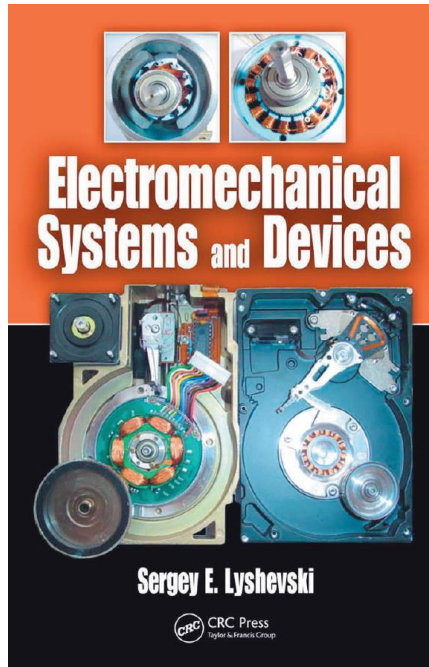
**Electric Drives  
From deep-sea  
to the sky**



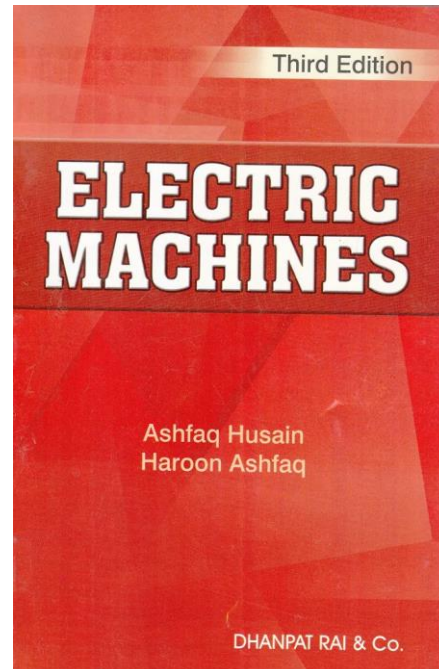
# USED MATERIAL

Various slides: Yang Tang, Helm Jansen, and others  
All from Eindhoven University of Technology

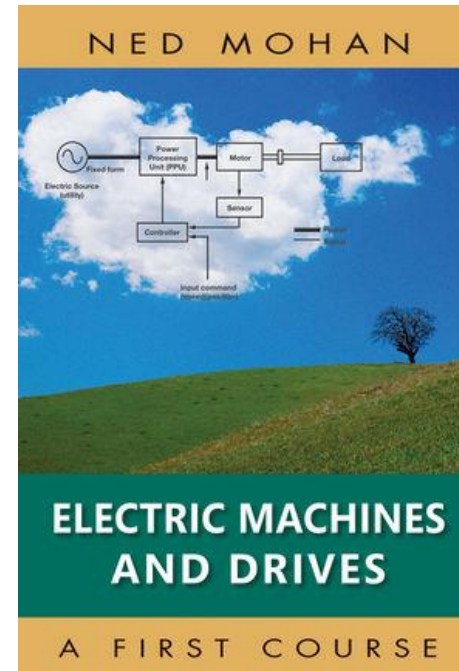
ISBN 0122699513



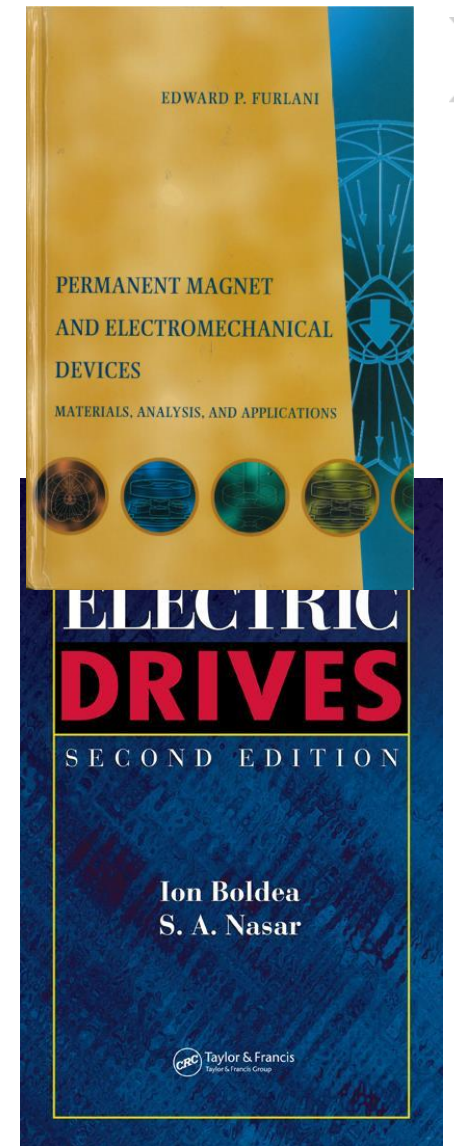
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ISBN 9788177001662



ISBN 9781118074817



ISBN 0849342201





# NOT NEW - 1907 — EV MARKET SHARE 30%





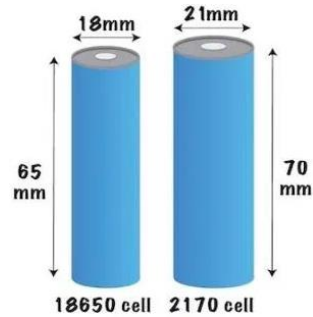
# ELECTRIC MOBILITY IS NOW ALL AROUND (LONGEST RANGE VEHICLES)







# BATTERIES ARE TO DATE (THE) KEY FOR ALL ELECTRIC MOBILITY



## Model 3 2170 Cell

70 grams  
970 cubic mm  
4.8 Ah  
17.3 Wh  
247 Wh/Kg

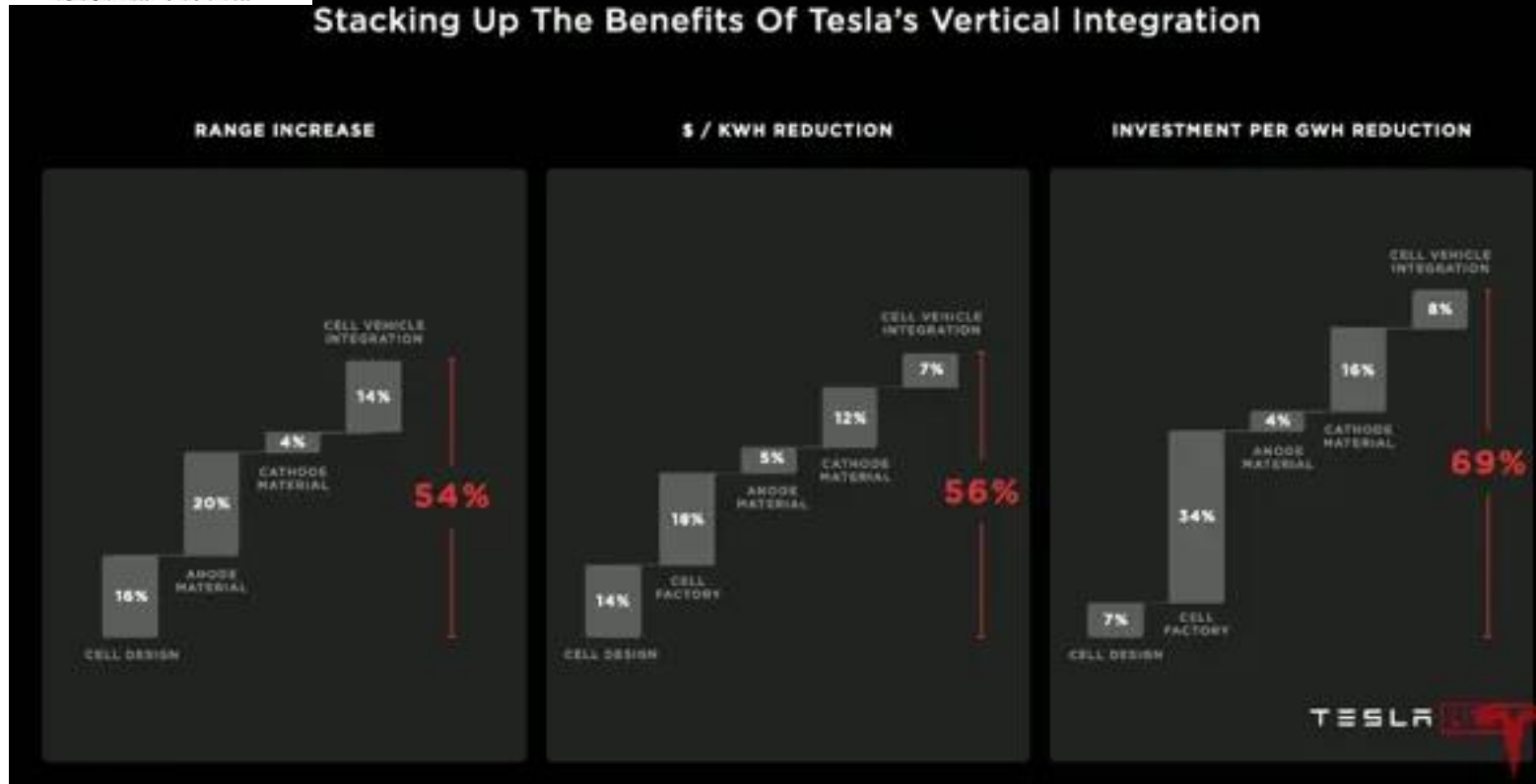
479 kg 76397 159.5 Wh/Kg pack



## What to expect 2022 to 2023

- Especially for small mass and volume critical vehicles
- 250 Wh/kg to 400 Wh/kg
- 5x more capacity per cell
- 6x more power output from 4680 cell (diameter 46 mm, length 80 mm instead of 2170 cell, 21 mm diameter, length 70 mm)
- Costs per kWh "tank content" reduced with 50%

## Stacking Up The Benefits Of Tesla's Vertical Integration





# BATTERIES ARE TO DATE (THE) KEY FOR ALL ELECTRIC MOBILITY





# BATTERIES ARE TO DATE (THE) KEY FOR ALL ELECTRIC MOBILITY





# BATTERIES SWAPPING OR CHARGING







# FUTURE CHARGING INFRASTRUCTURE ... IS THIS THE FUTURE...



# ON ROAD CHARGING... LIKE TRAINS







# CHARGING WILL BE KEY FOR FUTURE CITIES





# ELECTRIC POWERTRAIN WITH MAGNETIC COMPONENTS



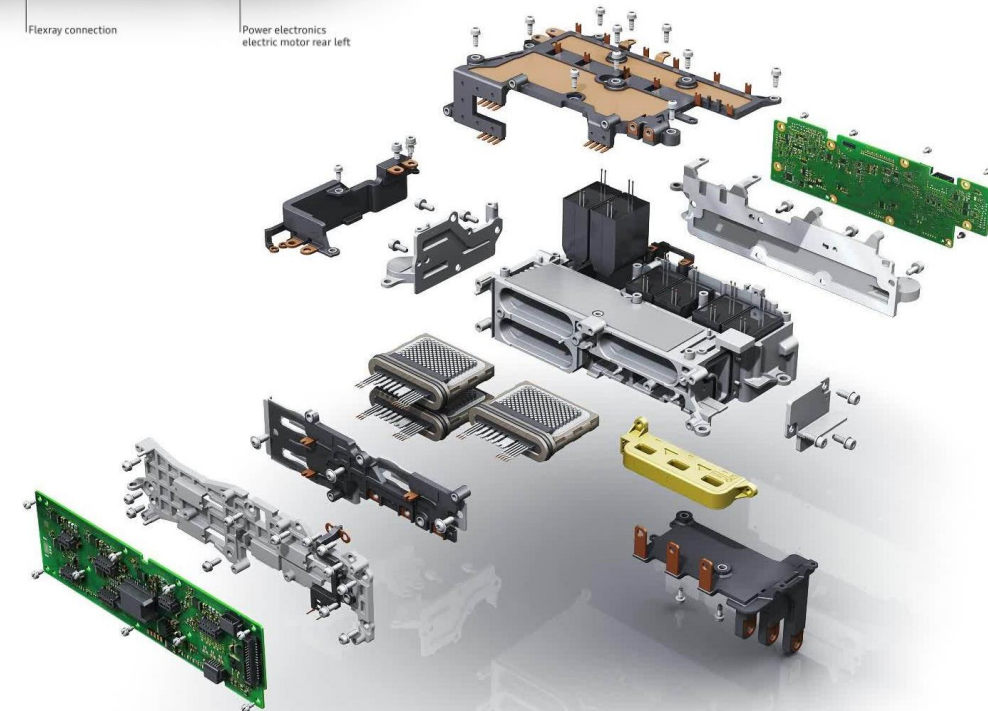
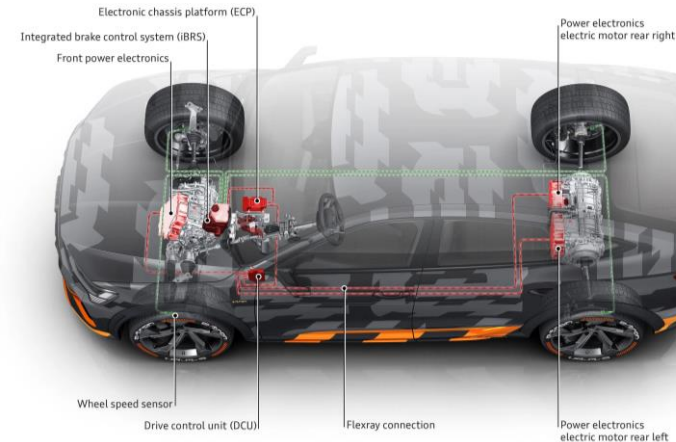
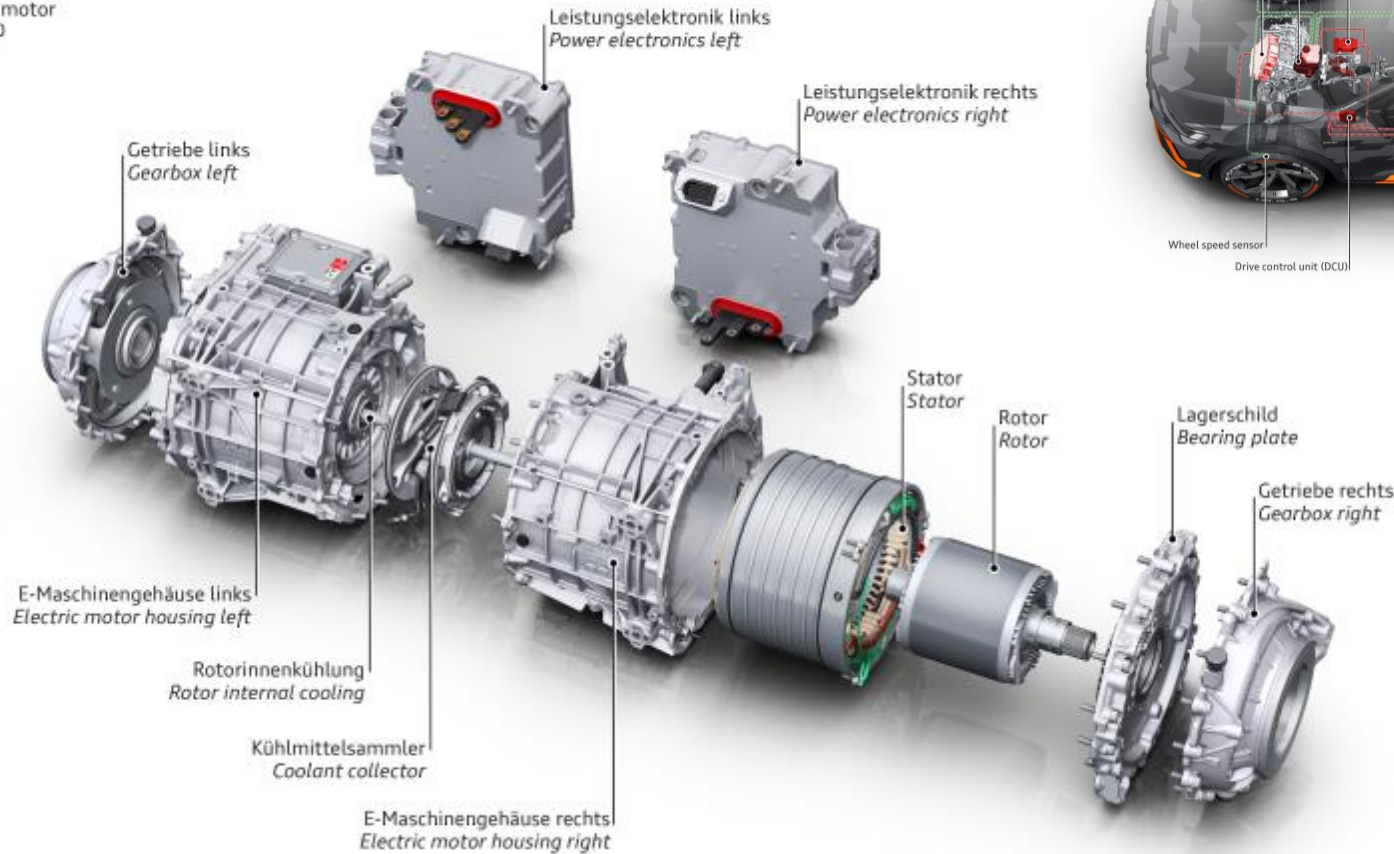




# ELECTRIC DRIVE (POWERTRAIN) WITH MAGNETIC COMPONENTS

## Audi e-tron S Sportback

Twin-Motor  
Twin motor  
02/20





# ELECTRIC DRIVE (POWERTRAIN) WITH MAGNETIC COMPONENTS

- ✓ High torque
- ✓ Wide speed range
- ✓ Light, robust, cheap

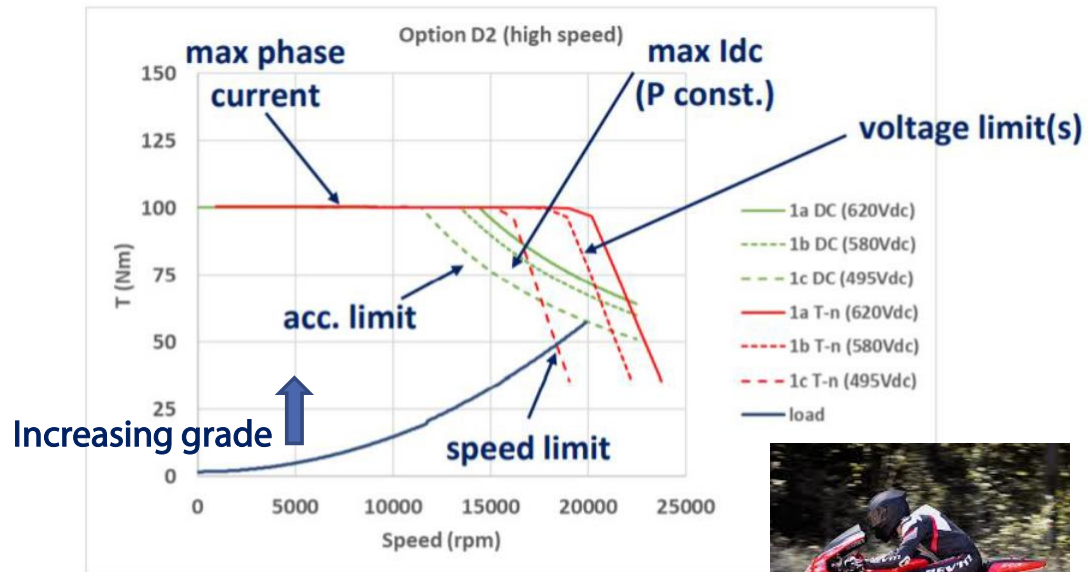
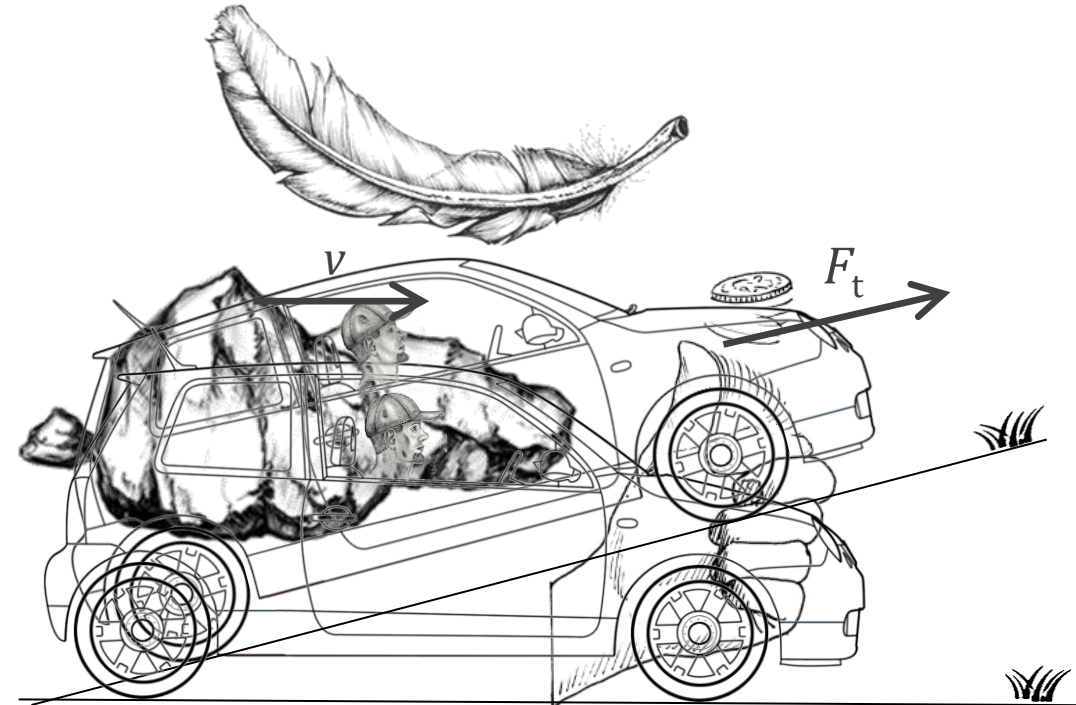


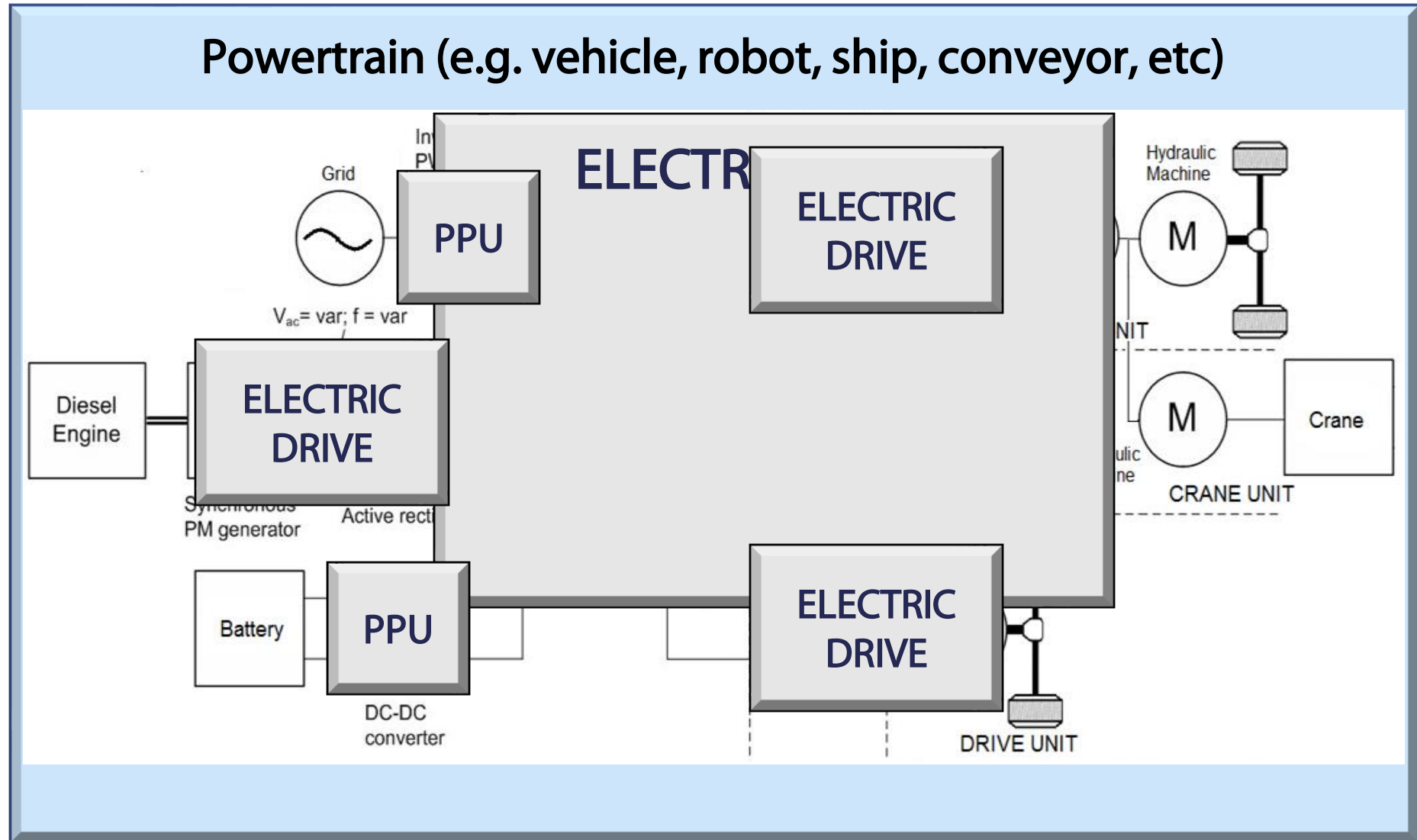
Figure 1: expected motor behavior



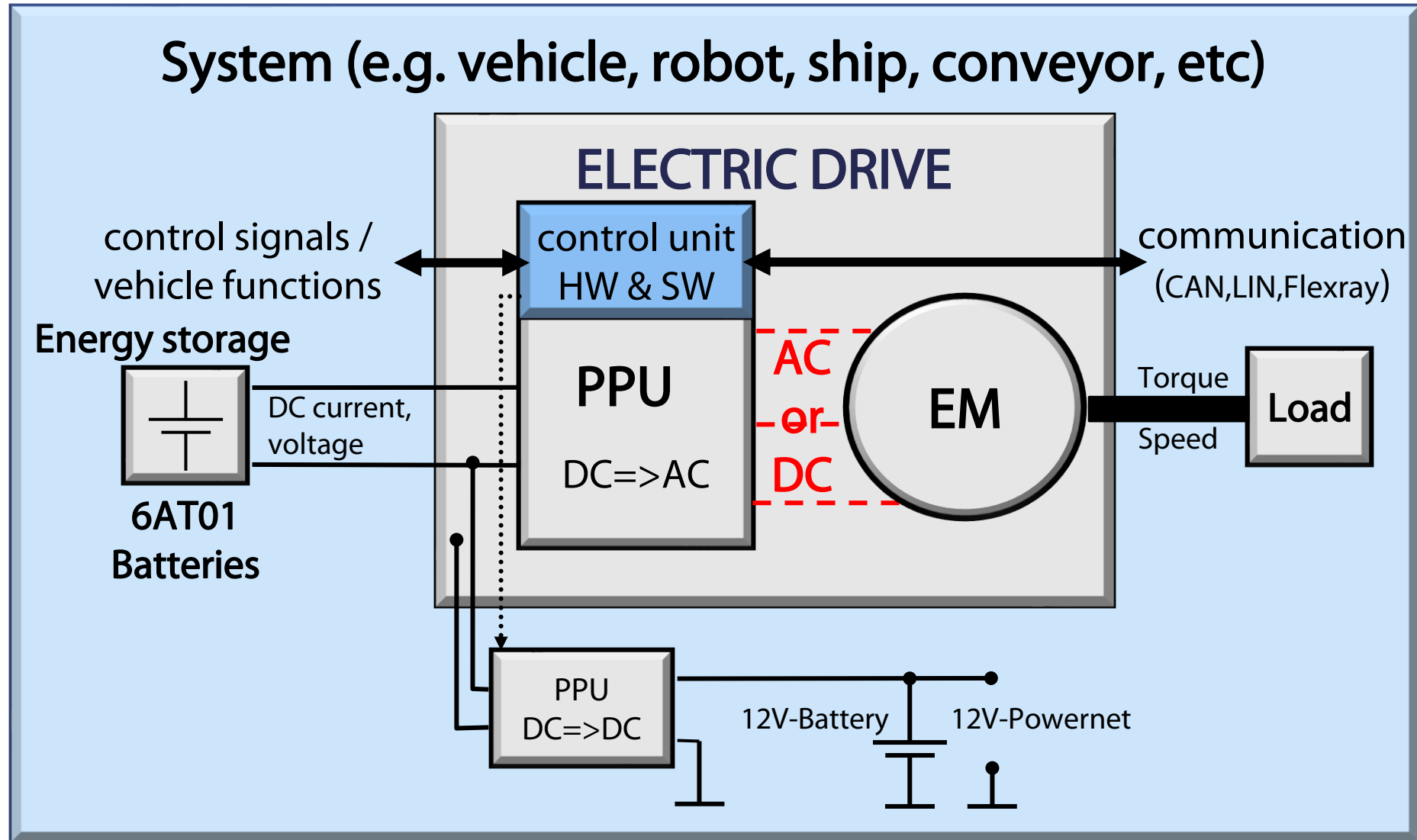




# ELECTROMAGNETISM IN ROTATING EQUIPMENT



# ADJUSTABLE/VARIABLE SPEED DRIVES







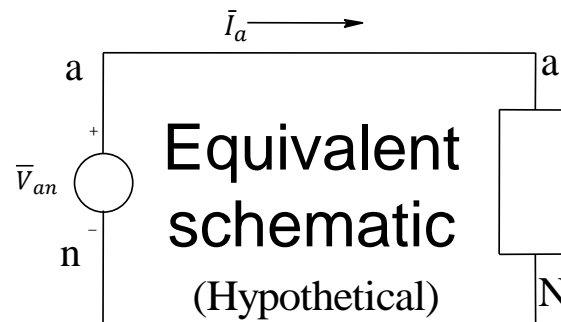
# 3-PHASE AC CURRENT AND SINGLE PHASE EQUIVALENT

## Conditions:

- Balanced set of source voltages,
- Equal impedances in each of the phases.

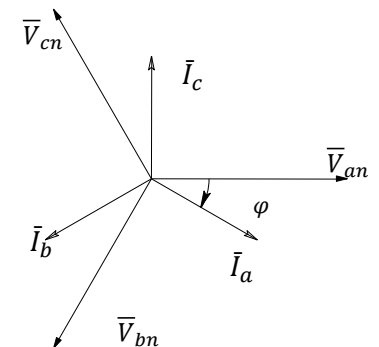
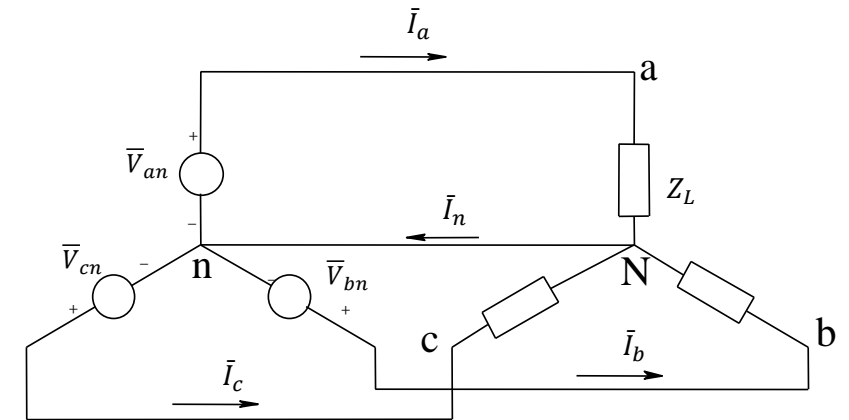
$$\begin{aligned}\bar{I}_a &= \frac{\bar{V}_{an}}{|Z_L|} = \frac{\hat{V}_s}{|Z_L|} \angle -\varphi \\ \bar{I}_b &= \frac{\bar{V}_{bn}}{|Z_L|} = \frac{\hat{V}_s}{|Z_L|} \angle -\frac{2\pi}{3} - \varphi \\ \bar{I}_c &= \frac{\bar{V}_{cn}}{|Z_L|} = \frac{\hat{V}_s}{|Z_L|} \angle -\frac{4\pi}{3} - \varphi\end{aligned}$$

$$\bar{I}_n = (\bar{I}_a + \bar{I}_b + \bar{I}_c) = 0 \Rightarrow i_n(t) = [i_a(t) + i_b(t) + i_c(t)] = 0$$



## Result:

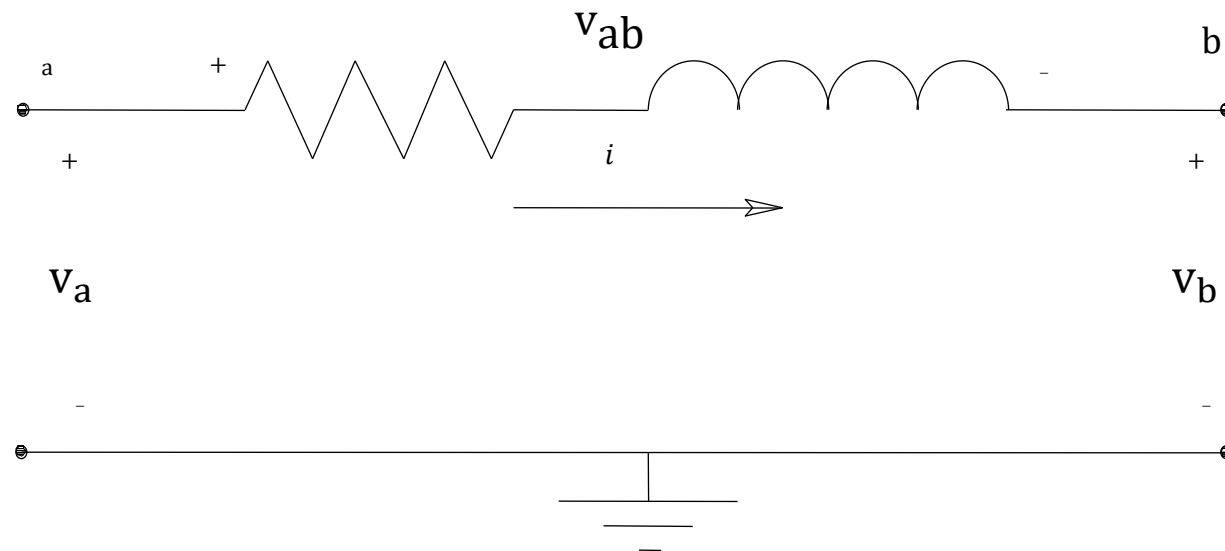
Source neutral "n" and load neutral "N" are at the same potential.





# ADJUSTABLE/VARIABLE SPEED DRIVES

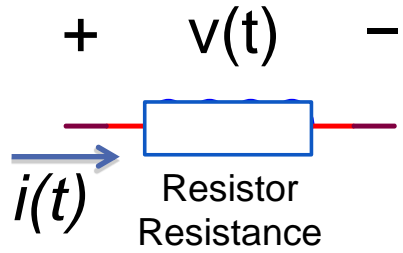

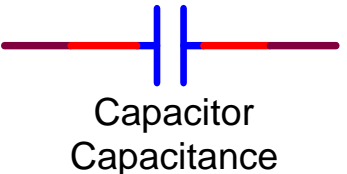
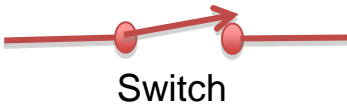
- SI Units
  - Lower case  $v$  and  $i$  for instantaneous quantities
  - Upper case  $V$  and  $I$  for average and rms
  - Voltage and current subscripts
  - Voltage polarities and current directions
1. Know sinusoidal waveforms.
  2. AC circuit analysis deals with phasors and impedances
  3. Do you know CIVIL ?
  4. Instantaneous Power





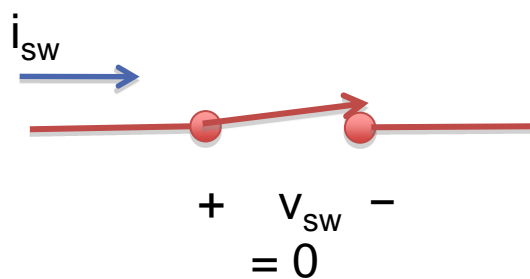


# ELECTRICAL NETWORK ELEMENTS

	Time	Phasors	Network characteristics
 <p>Resistor Resistance</p>	$v(t) = R \cdot i(t)$	$\bar{V} = R \cdot \bar{I}$	$\bar{V} \neq 0 \quad \bar{I} \neq 0 \quad P \neq 0$
 <p>Inductor Inductance</p>	$v(t) = L \cdot \frac{di(t)}{dt}$	$\bar{V} = jX_L \bar{I} = j\omega L \bar{I}$	$\bar{V} = 0 \quad \bar{I} \neq 0 \quad P = 0$
 <p>Capacitor Capacitance</p>	$i(t) = C \cdot \frac{dv(t)}{dt}$	$\bar{V} = -X_C \bar{I} = j \frac{1}{\omega C} \bar{I}$	$\bar{V} \neq 0 \quad \bar{I} = 0 \quad P = 0$
 <p>Switch</p>	$v(t) \begin{cases} 0 \\ v(t) \end{cases}$ $i(t) \begin{cases} 0 \\ i(t) \end{cases}$	$\bar{V} \begin{cases} 0 \\ \bar{V} \end{cases}$ $\bar{I} \begin{cases} 0 \\ \bar{I} \end{cases}$	$\bar{V} \neq 0 \quad \bar{I} \neq 0 \quad P = 0$

# ELECTRICAL NETWORK ELEMENTS

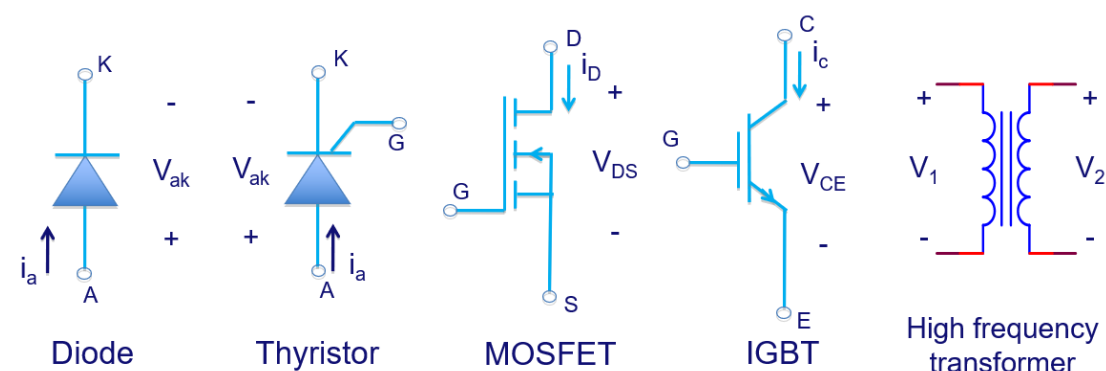
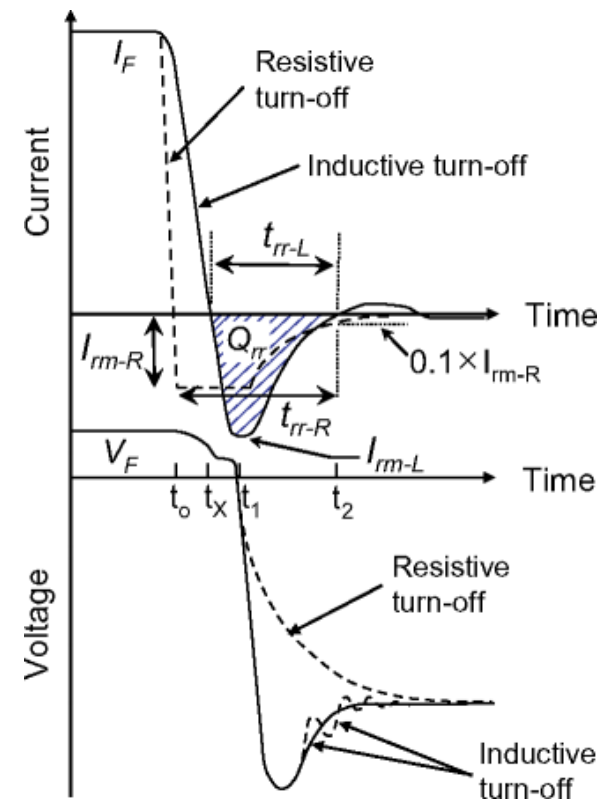
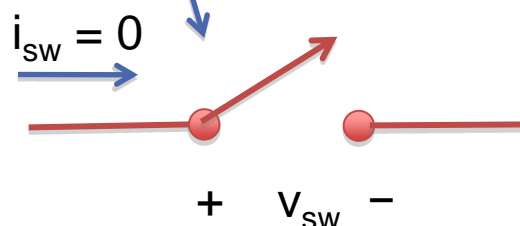
Power semiconductor devices ↔ Power switches



$$P_{\text{loss}} = v_{\text{sw}} \times i_{\text{sw}} = 0$$

Losses ideally ZERO !

ON or OFF

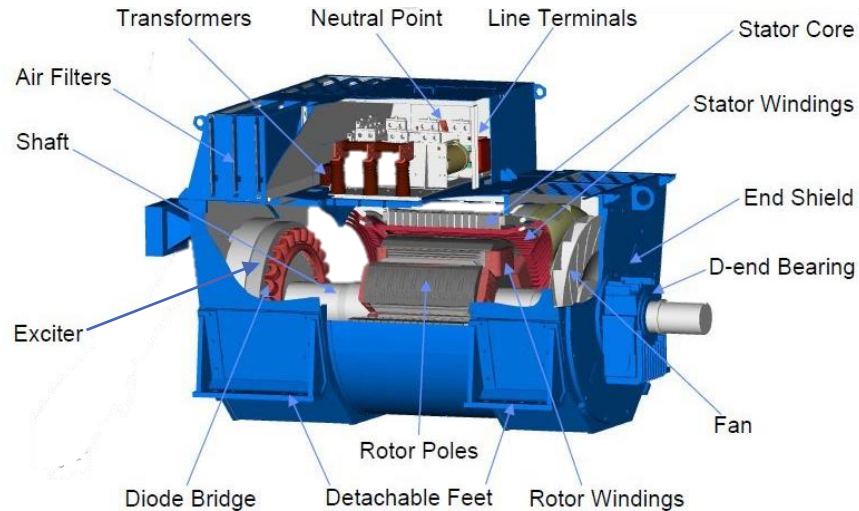
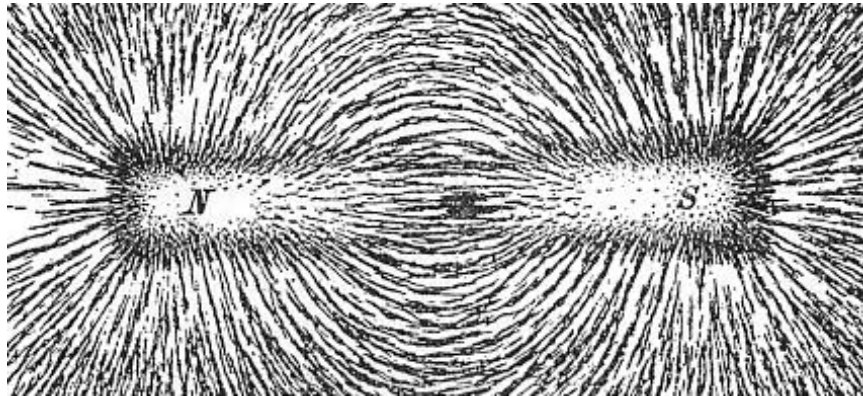


\*Loss simulation results during PWM inverter drive.

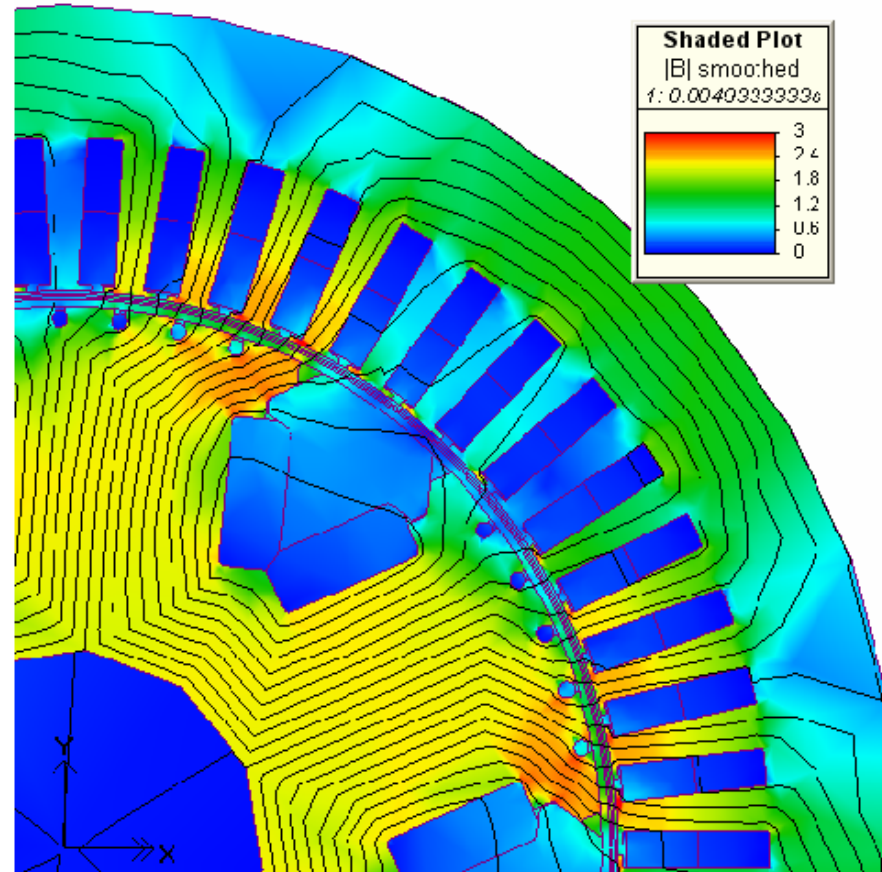




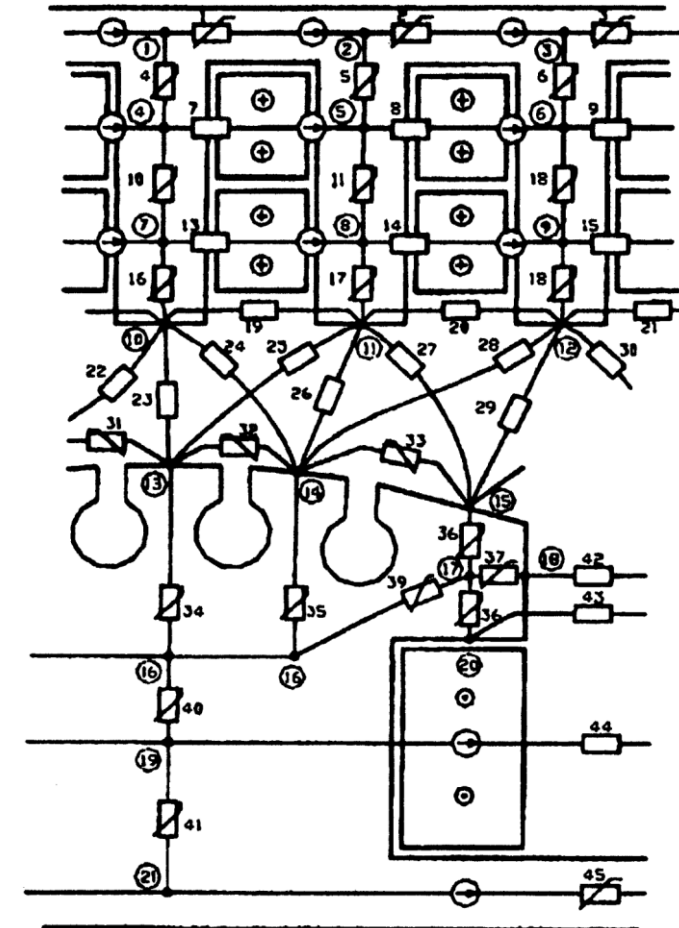
# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)



Synchronous Generator



2D cross-section with "Flux lines"



Magnetic Equivalent Circuit



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

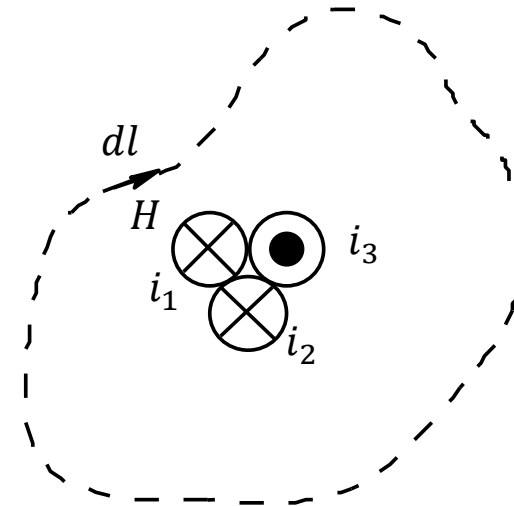
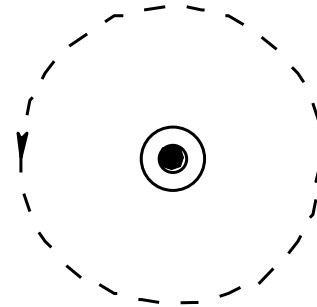
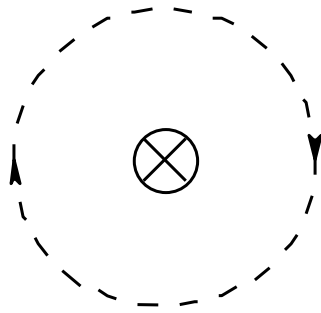
Magnetic field,  $H$ , produced by current carrying conductor

Ampere's Law

$$\oint_{\text{closed path}} H d\ell = \sum i \quad (5-1)$$

Scalar  $H$  is the component of the vector in the direction of the length  $d\ell$  along the closed path.

$H$  has the units of  $\left[ \frac{A}{m} \right]$



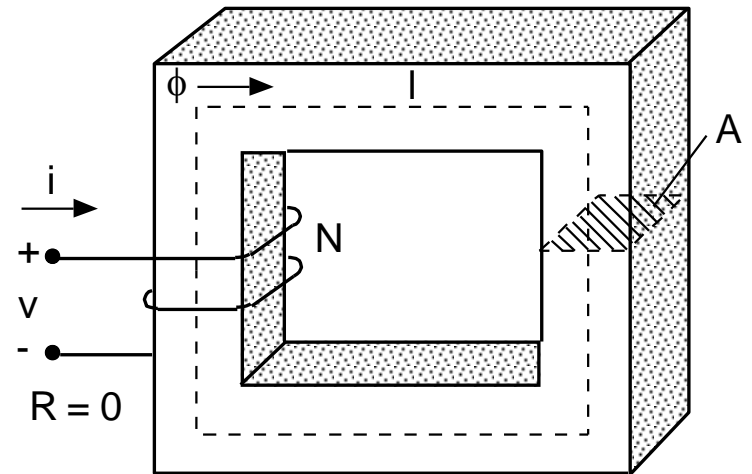
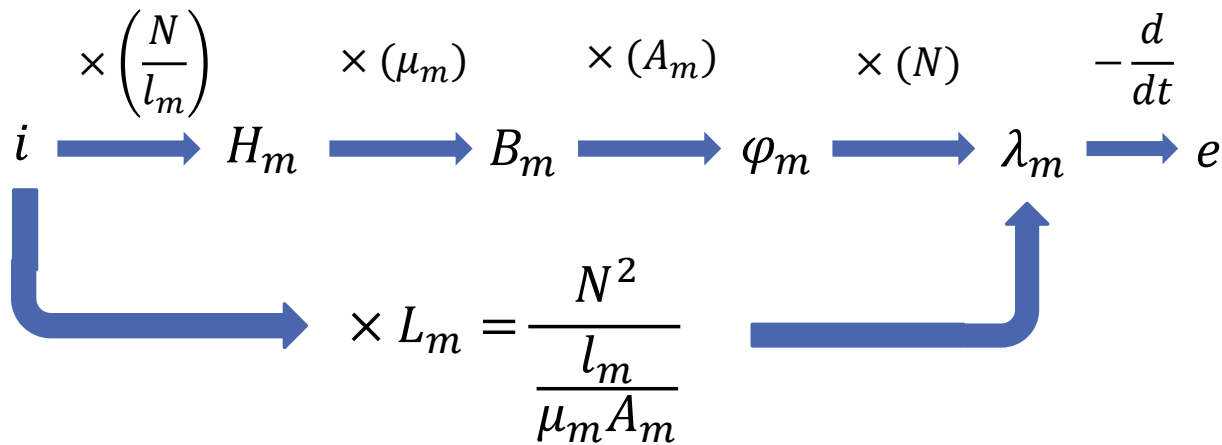
Magnetic field and Ampere's law





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

- Energy an Important Unit :
  - Theoretically energy can be converted from electrical form to magnetic form and vice versa with 100% efficiency
  - The electrical energy supplied to a lossless coil as the current increases must be equal to the energy stored in the magnetic field of the ferromagnetic core

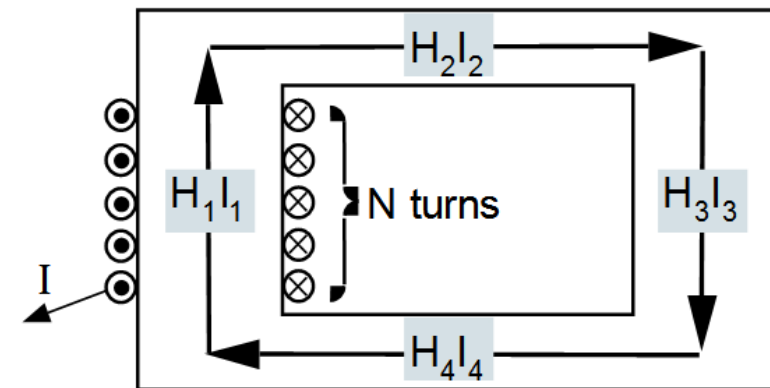
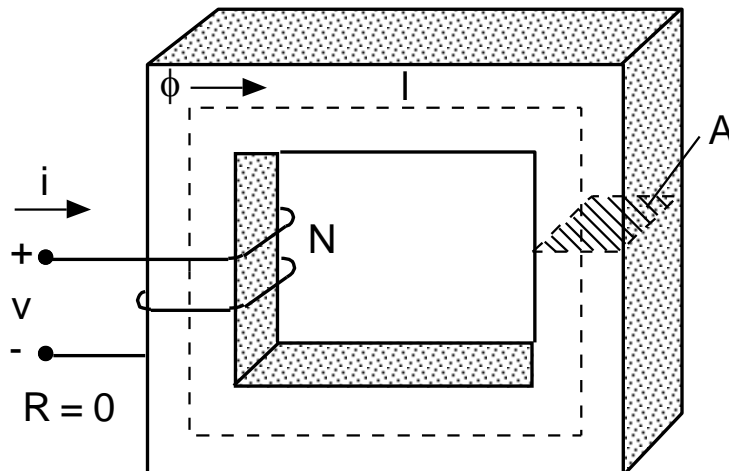




# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

Isomorphism between electric and magnetic circuits

Electric circuits		Magnetic circuits	
Current	$I$	Magnetic flux	$\varphi_m$
Voltage	$V$	MMF	$F$
Resistance	$R_e$	Reluctance	$\mathfrak{R}_m$





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

1. Magnetic equivalent circuits (MEC) are sometimes used to model devices composed from highly permeable materials, e.g., ferromagnetic core
2. Magnetic flux is confined to the highly permeable material  $\Rightarrow$  flux paths (tubes) can be “easily” identified
3. Air gap flux paths have to be approximated, i.e., the fringing effect has to be considered
4. Leakage paths have to be approximated
5. A-priori knowledge (“expert” understanding) of the magnetic flux distribution is necessary in order to define any Magnetic Equivalent Circuit !!!



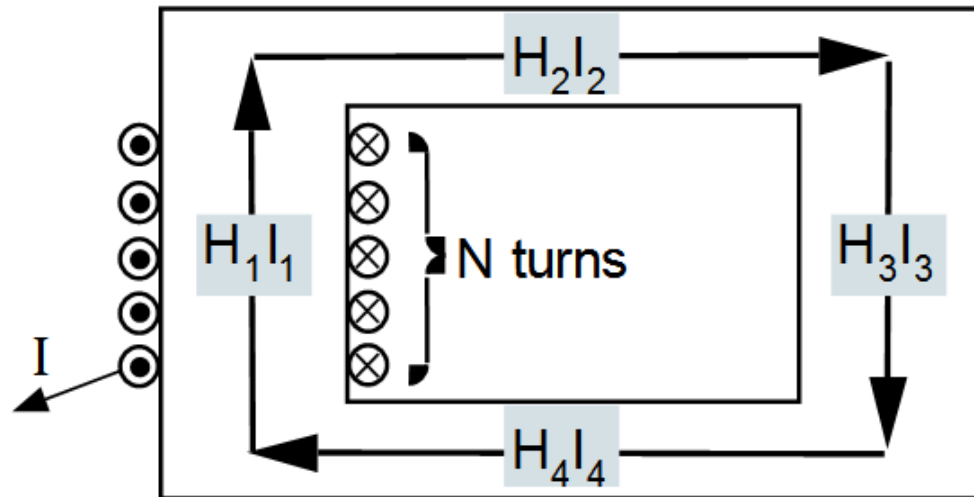


# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

$$\oint_{\text{closed path}} H d\ell = \sum i \quad (5-1)$$

$$i \xrightarrow{\times \left(\frac{N}{l_m}\right)} H_m \xrightarrow{\times (\mu_m)} B_m \xrightarrow{\times (A_m)} \phi_m \xrightarrow{\times (N)} \lambda_m \xrightarrow{-\frac{d}{dt}} e$$
$$\times L_m = \frac{N^2}{\frac{l_m}{\mu_m A_m}}$$

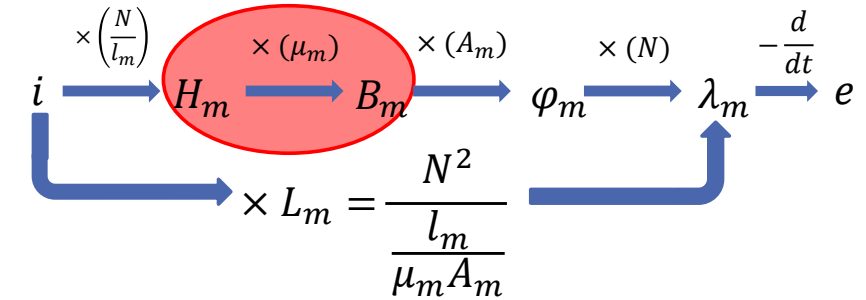
$$\sum_k H_k l_k = \sum_k \mathcal{F}_k = \int_C \mathbf{H} \cdot d\mathbf{l} = H_1 l_1 + H_2 l_2 + H_3 l_3 + H_4 l_4 = N_1 I_1 = \mathcal{F}_1$$





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

For a given H-field, the density of flux lines, called the flux density B, depends on the permeability  $\mu$  of the material on which this H-field is acting.



Units of flux density B:  $\frac{\text{Weber}}{\text{meter}^2} \left[ \frac{\text{Wb}}{\text{m}^2} \right]$  or *Tesla* [T]

In air:  $B = \mu_o H$        $\mu_o = 4\pi \times 10^{-7} \left[ \frac{\text{henries}}{\text{m}} \right]$  or  $\left[ \frac{\text{H}}{\text{m}} \right]$       (5-3)

where  $\mu_o$  is the permeability of air or free space.



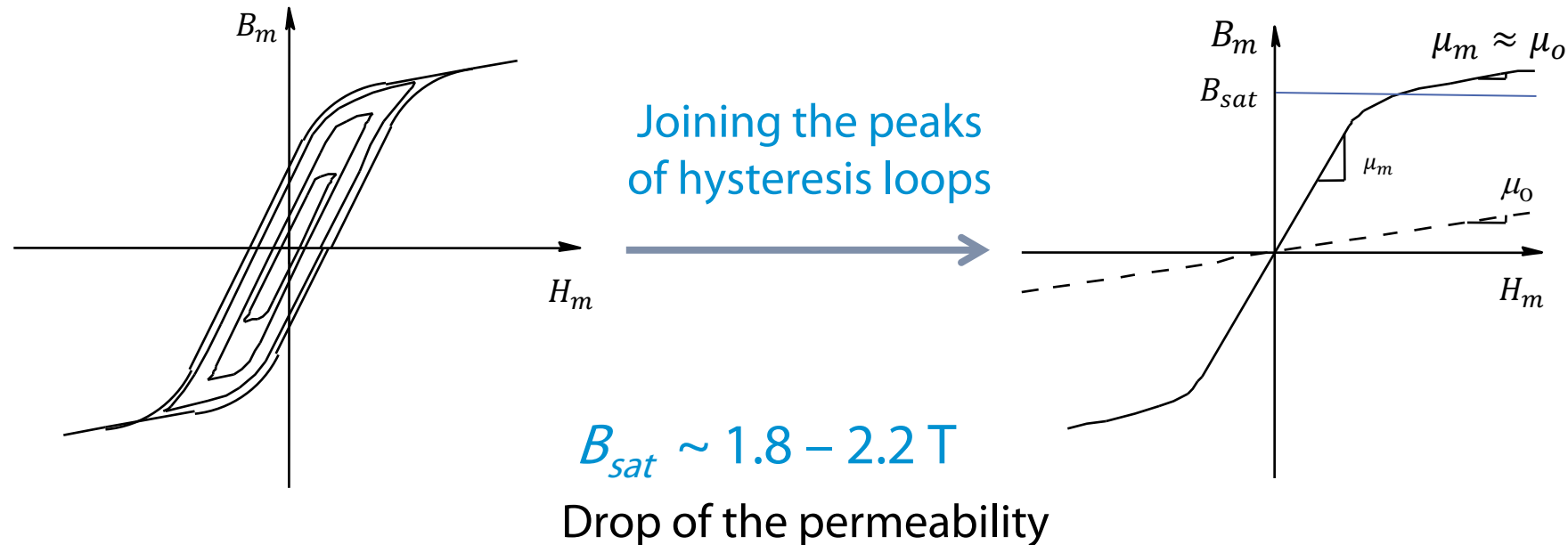
# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

High magnetic permeability

$$B_m = \mu_m H_m = \mu_r \mu_o H_m$$

Required B can be achieved with much lower values of H field than in the air => lower ampere-turns required

Multi valued nonlinear behavior







# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

Magnetic flux lines form closed paths.

Area  $A_m$  in a plane perpendicular to the direction of the flux lines.

Uniform  $H_m$ , hence uniform  $B_m$  over  $A_m$ :

$$B_m = \mu_m H_m = \mu_m \frac{Ni}{\ell_m} \quad (5-5)$$

$$\varphi_m = B_m A_m \quad (5-6)$$

$$\therefore \varphi_m = A_m \left( \mu_m \frac{Ni}{\ell_m} \right) = \frac{Ni}{\left( \frac{\ell_m}{\mu_m A_m} \right)} = \frac{F}{\mathfrak{R}_m} \quad (5-7)$$

Reluctance:  $\mathfrak{R}_m = \frac{\ell_m}{\mu_m A_m} \left[ \frac{A}{Wb} \right] \quad (5-8)$

MMF:  $F = Ni$   $\longleftrightarrow$  Ohm's law:  $I = \frac{V}{R_e}$

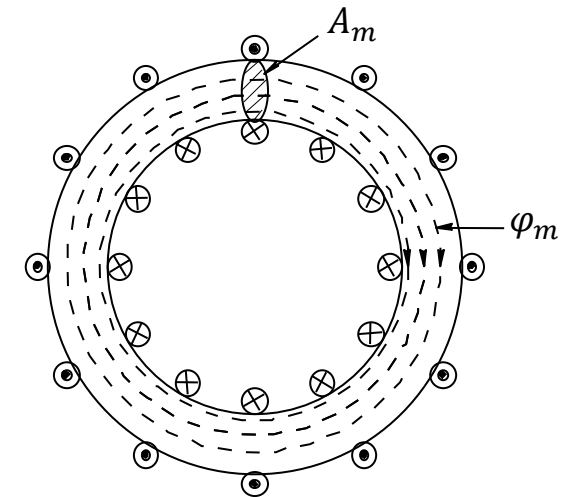
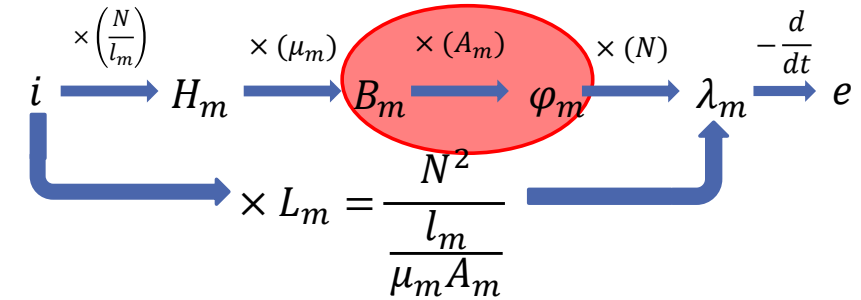


Fig. 5.4 Toroid with flux



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

## Flux linkage

If all turns  $N$  of a coil are linked with the same flux  $\varphi_m$ , then the coil has a flux linkage  $\lambda_m$ , where

$$\lambda_m = N\varphi_m \quad (5-9)$$

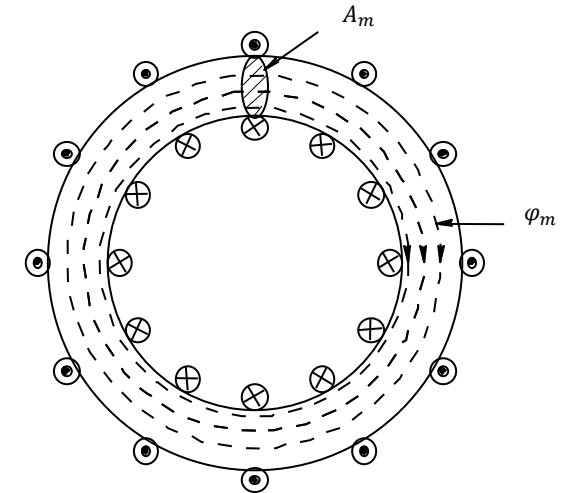
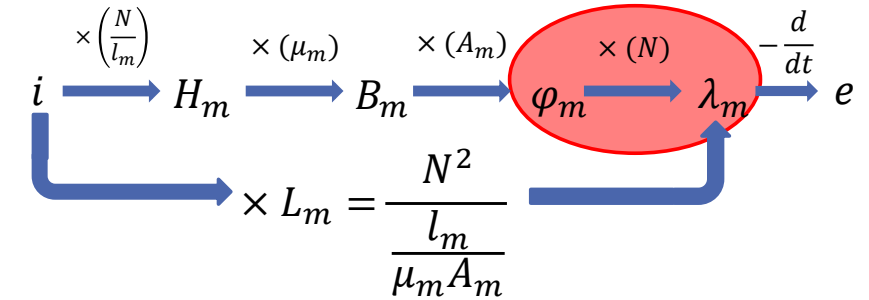
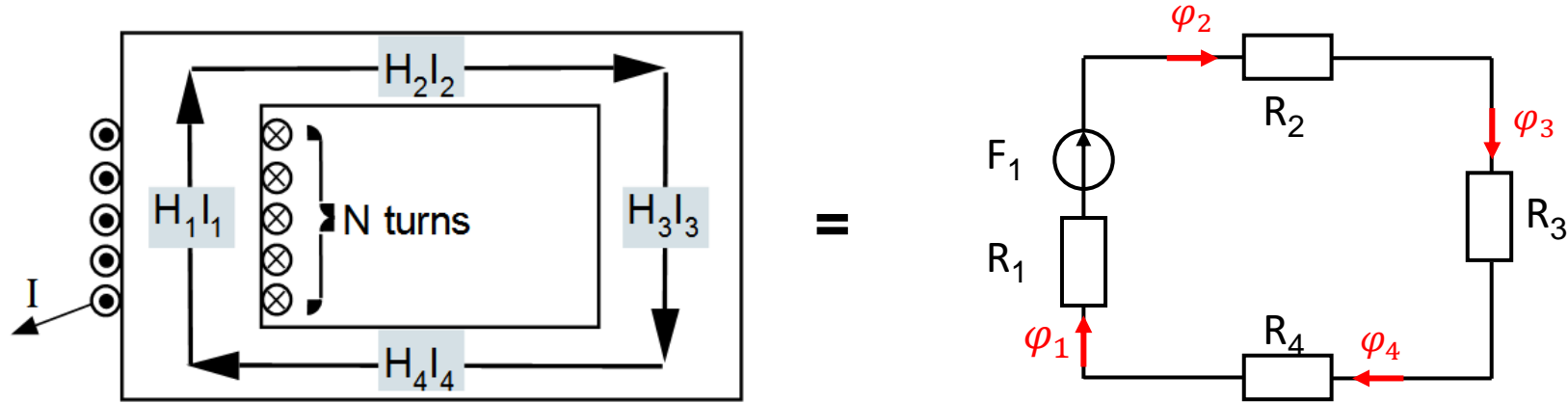


Fig. 5.4 Toroid with flux  $\varphi_m$



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)



$$\sum_m H_m l_m = \sum_m \mathcal{F}_m \Rightarrow \sum_m \Phi_m \mathcal{R}_m = \sum_m \mathcal{F}_m$$

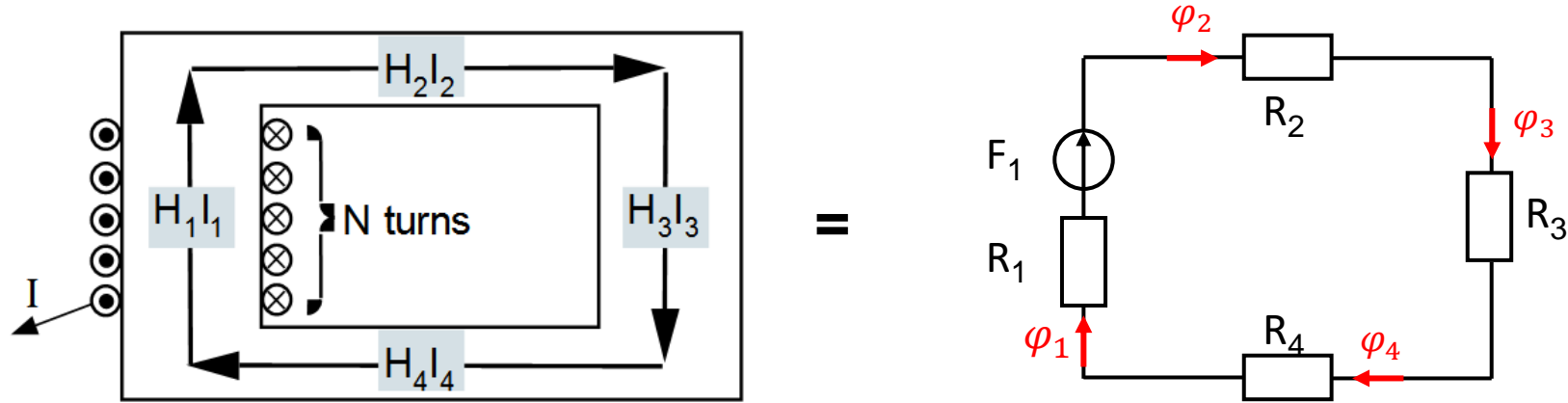
$$\varphi_1 = \varphi_2 = \varphi_3 = \varphi_4 = \varphi \quad \text{conservation of magnetic flux}$$

$$\varphi \sum_m \mathcal{R}_m = \mathcal{F}_1 \Rightarrow \varphi = \frac{\mathcal{F}_1}{\sum_m \mathcal{R}_m}$$





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)



$$\varphi \sum_m \mathcal{R}_m = \mathcal{F}_1 \Rightarrow \varphi = \frac{\mathcal{F}_1}{\sum_m \mathcal{R}_m}$$

$$\mathcal{R}_m = \oint_{C_m} \frac{dl}{\mu_m A_m} \Rightarrow \mathcal{R}_m = \frac{l_m}{\mu_m A_m} \text{ if } A_m \text{ constant}$$



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

The flux linkage  $\lambda_m$  of the coil is related to the  $i$  current by a parameter defined as the inductance  $L_m$

$$\lambda_m = L_m i \quad (5-19)$$

$$L_m = \frac{\lambda_m}{i} = \left( \frac{N}{l_m} \right) \mu_m A_m N = \frac{N^2}{\left( \frac{l_m}{\mu_m A_m} \right)} = \frac{N^2}{\mathfrak{R}} \quad (5-20)$$

For linear magnetic conditions the inductance is constant and depends only on the magnetic circuit.

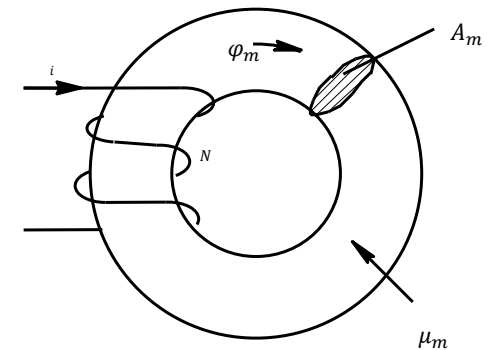
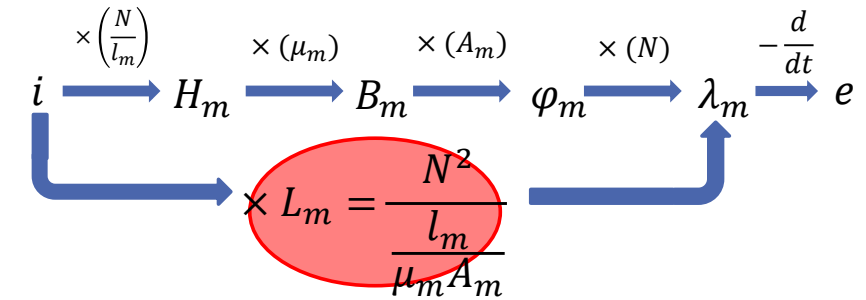


Figure 5-6 Coil inductance



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

Energy in an inductor is stored in its magnetic field.

(5-21)

$$W_m = \frac{1}{2} L_m i^2 [J]$$

Assuming a structure without air gap (Fig. 5-6a)

(5-22a)

$$W_m = \frac{1}{2} \frac{N^2}{\frac{l_m}{\mu_m A_m}} (H_m l_m / N)^2 = \frac{1}{2} \frac{(H_m l_m)^2}{\frac{l_m}{\mu_m A_m}} = \frac{1}{2} \frac{B_m^2}{\mu_m} \underbrace{A_m l_m}_{\text{volume}} [J]$$

The energy density in the core is

(5-22b)

$$w_m = \frac{W_m}{\text{volume}} = \frac{1}{2} \frac{B_m^2}{\mu_m} \left[ \frac{J}{m^3} \right]$$

The energy density in any medium is

(5-23)

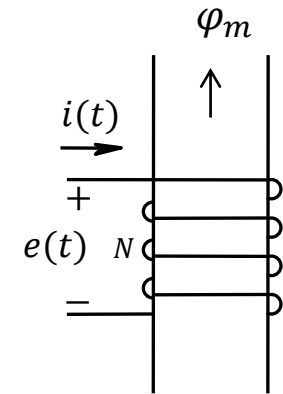
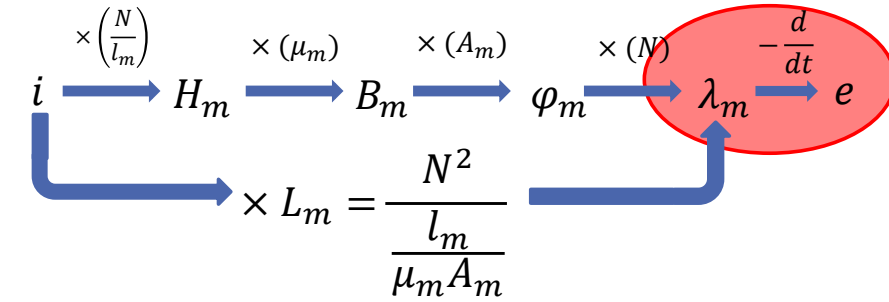
$$w = \frac{1}{2} \frac{B^2}{\mu} \left[ \frac{J}{m^3} \right]$$





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

- Induced voltage 
$$e = -\frac{d\lambda}{dt} = -N \frac{d\varphi}{dt}$$
- Current direction is into positive polarity voltage  $\rightarrow$  flux direction
- Lenz's law: Polarity of induced voltage



When current and flux directions are consistent: A current as indicated would create a flux as indicated  $\Rightarrow$  voltage should be labeled positive where the current enters the coil.



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

The relationships between the electrical quantity  $\varphi$  and  $i$  and the magnetic quantities  $H$ ,  $B$ ,  $\lambda$  and are valid under dc (static) conditions, as well as at any instant when these quantities are varying with time.

Faraday's law:

A coil of  $N$  turns linked by a changing magnetic flux  $\varphi$  has a voltage  $e$  induced behind the terminals of that coil with a magnitude:

$$e = \frac{d}{dt} \lambda(t) = N \frac{d}{dt} \varphi(t) \quad (5-24)$$

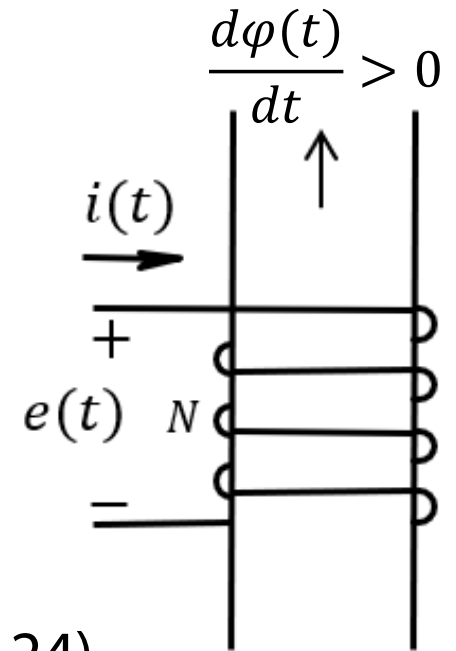


Figure 5-8

The voltage  $e$  induced in a coil by a changing flux is of such polarity that if a current could flow as a result of that induced voltage, the flux established by that current would oppose the causing or original flux change (**Lenz's rule**).



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

Relating  $e(t)$ ,  $\varphi(t)$  and  $i(t)$ : coil in sinusoidal steady state

$$\varphi(t) = \hat{\varphi} \sin(\omega t)$$

$$e(t) = N \frac{d\varphi}{dt} = N \hat{\varphi} \omega \cos \omega t$$

Relating  $e(t)$ ,  $\varphi(t)$ , and  $i(t)$   $\Rightarrow L = \frac{\lambda}{i} = \frac{N\varphi}{i}$

$$\left. \begin{aligned} \Rightarrow i(t) &= \frac{N}{L} \varphi(t) \\ \& e(t) &= N \frac{d\varphi(t)}{dt} \end{aligned} \right\} \Rightarrow e(t) = L \frac{di(t)}{dt} \quad (5-28)$$

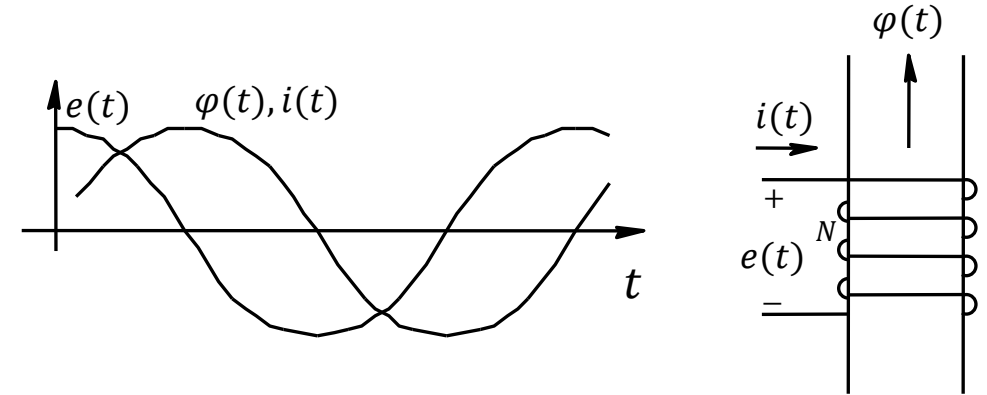


Figure 5-10 Voltage, current, and flux





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

Objective: establish  $B_g$  in  $\ell_g$  by controlling  $i$

$$H_m \ell_m + H_g \ell_g = Ni \quad (5-10)$$

$$B_m = \mu_m H_m, \quad B_g = \mu_o H_g \quad (5-11)$$

$$\frac{B_m}{\mu_m} \ell_m + \frac{B_g}{\mu_o} \ell_g = Ni \quad (5-12)$$

$$\phi_m = A_m B_m = A_g B_g \quad (5-13)$$

$$B_m = \frac{\phi_m}{A_m} B_g = \frac{\phi_m}{A_g} \quad (5-14)$$

$$A_g = (w + \ell_g)(d + \ell_g) \quad (5-15) \text{ account for fringing}$$

$$\phi_m \left( \underbrace{\frac{\ell_m}{A_m \mu_m}}_{\mathfrak{R}_m} + \underbrace{\frac{\ell_g}{A_g \mu_o}}_{\mathfrak{R}_g} \right) = Ni \quad (5-16)$$

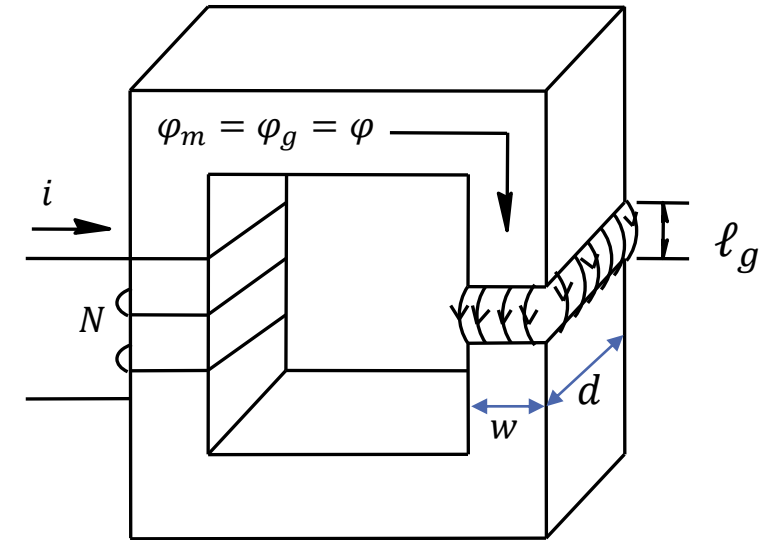


Figure 5-5 Magnetic structure with air gap

$$\mathfrak{R} = \mathfrak{R}_m + \mathfrak{R}_g \quad (5-17)$$

$$\phi_m = \frac{F}{\mathfrak{R}} \quad (5-18)$$



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

Negligible leakage current:  $\sigma_{e\text{Cu}} \approx 10^{20} \sigma_{e\text{air}}$

Not-negligible leakage flux:  $\mu_{\text{magn.mat.}} \approx 10^4 \mu_o$

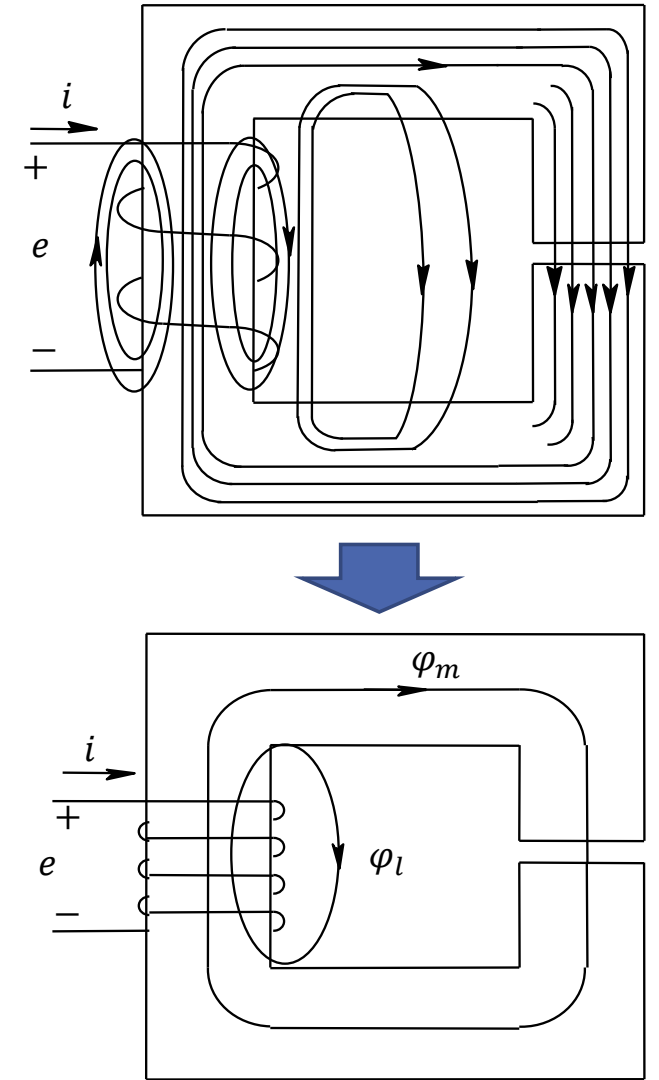
Approximations

The total flux  $\varphi$  is divided in two parts:

The magnetic flux  $\varphi_m$ , completely confined to the core and linking all N turns;

The leakage flux  $\varphi_\ell$ , partially in the air and also linking all N turns.

$$\varphi = \varphi_m + \varphi_\ell \quad (5-29)$$





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

$$\varphi = \varphi_m + \varphi_\ell \quad (5-29)$$

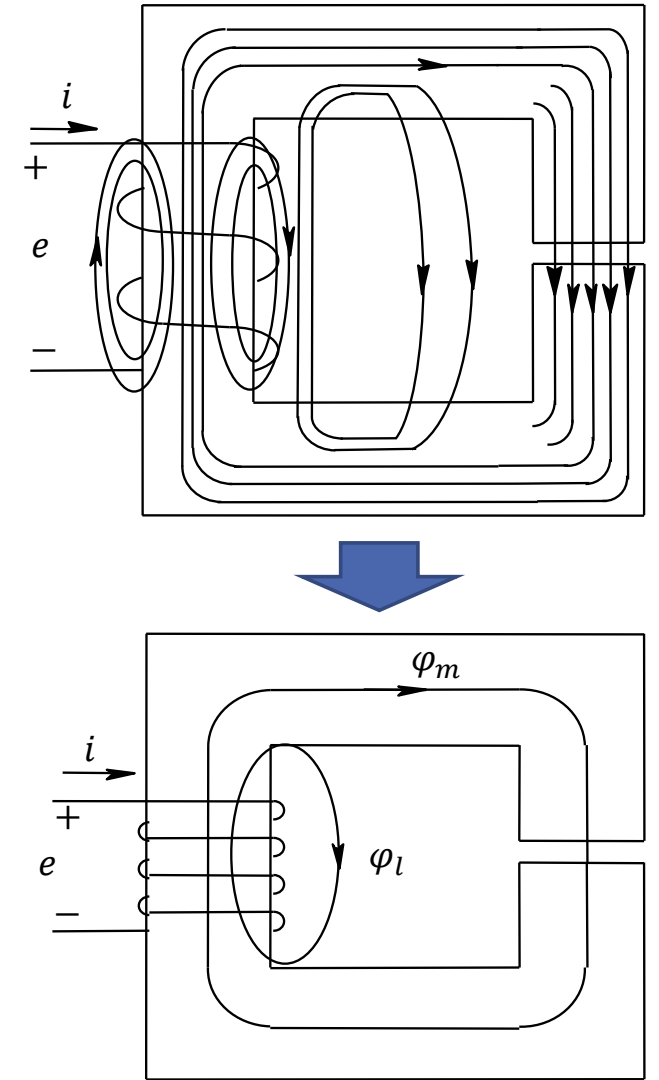
$$\lambda = N\varphi = \underbrace{N\varphi_m}_{\lambda_m} + \underbrace{N\varphi_\ell}_{\lambda_\ell} \quad (5-30)$$

$$\frac{\lambda}{i} = \frac{\lambda_m}{i} + \frac{\lambda_\ell}{i} \quad (5-31)$$

$$L_{self} = L_m + L_\ell \quad (5-32)$$

$$\lambda = L_{self}i = L_mi + L_\ell i \quad (5-33)$$

Total inductance or self-inductance  $L_{self}$  is sum of magnetizing inductance  $L_m$  due to  $\varphi_m$ , and leakage inductance  $L_\ell$  due to  $\varphi_\ell$ .





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

From Faraday's law:

$$e = \underbrace{L_m \frac{di}{dt}}_{e_m} + \underbrace{L_\ell \frac{di}{dt}}_{e_\ell} = e_m + L_\ell \frac{di}{dt} \quad (5-34)$$

The voltage drop due to the leakage flux can be shown separately, so that the voltage induced in the coil is solely due to the magnetizing flux.

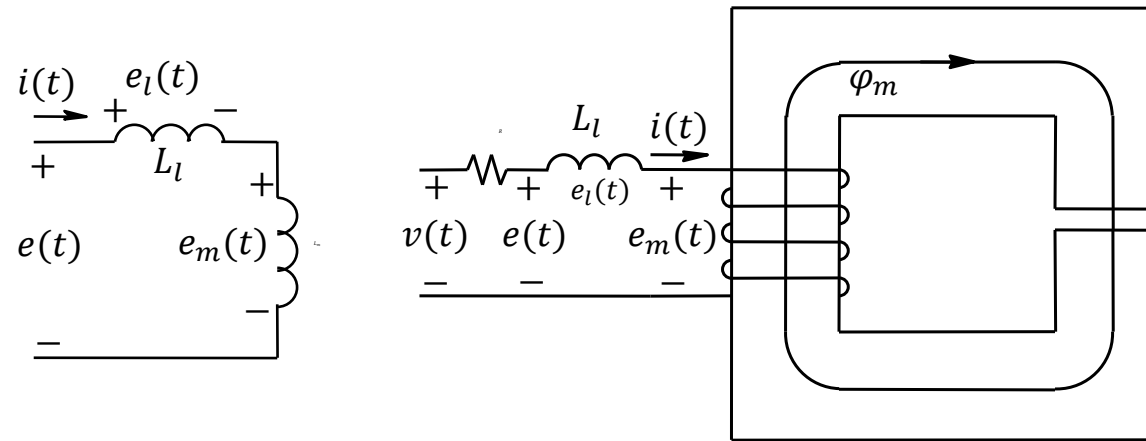


Figure 5-12 (a) Circuit representation; (b) leakage inductance separated from the core





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

- Most magnetic circuits consist of multiple coils.
- In such circuits, the flux established by the current in one coil partially links the other coil or coils.
- This phenomenon can mathematically be described by means of mutual inductances.

Concentrated

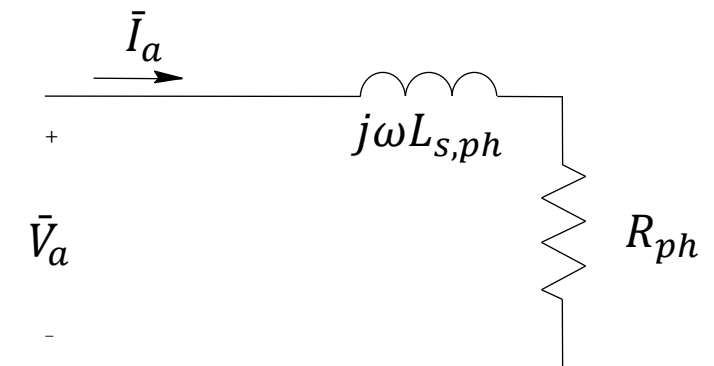


Distributed



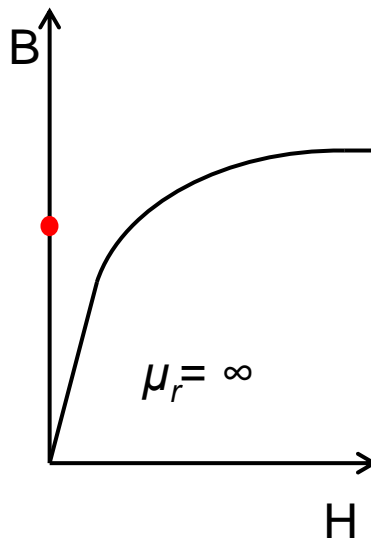
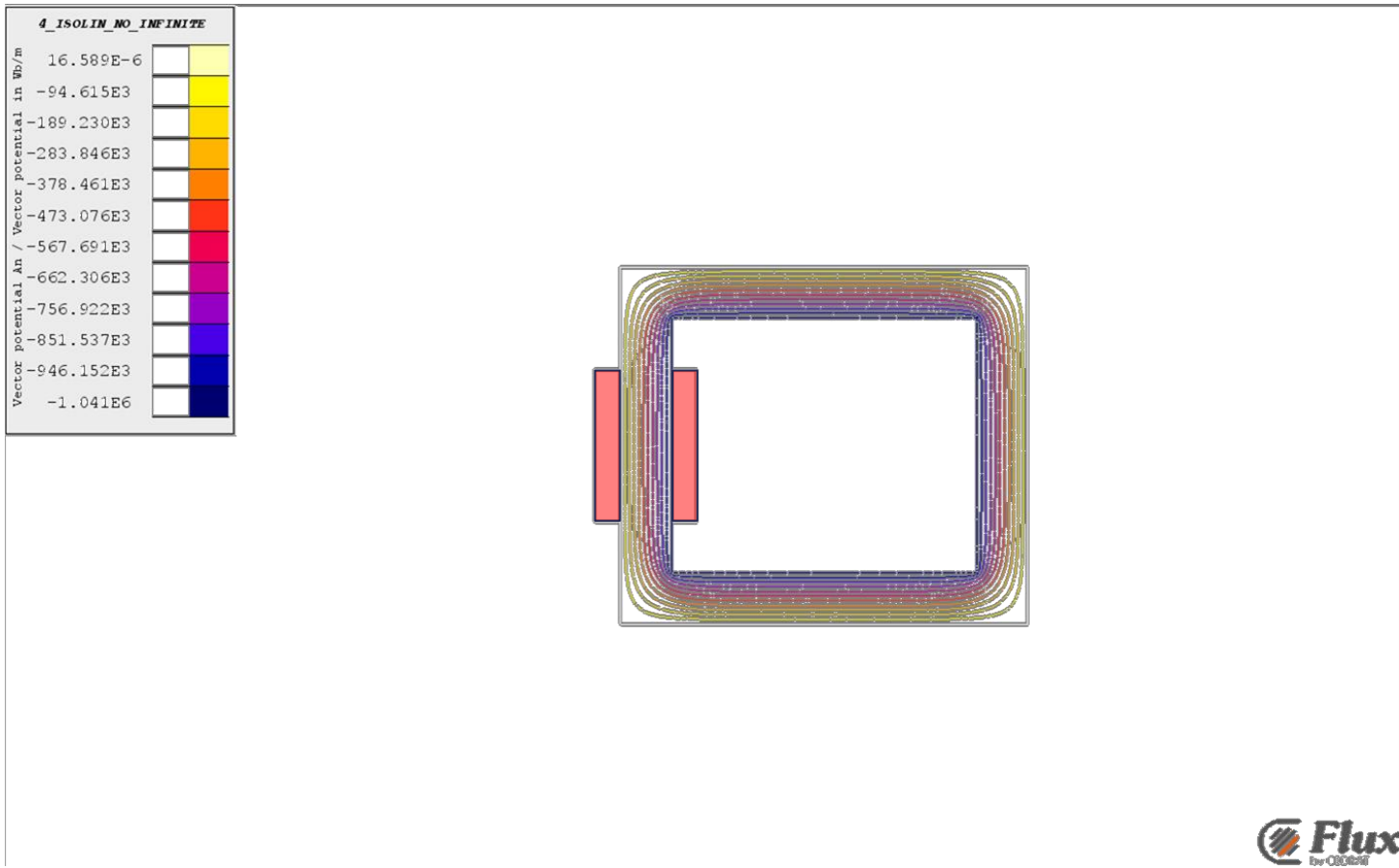
What you need to know is Synchronous inductance:

$$L_{s,ph} = L_{ph} + M_{ph}$$



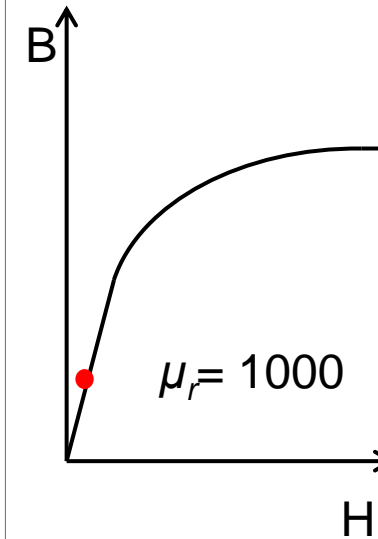
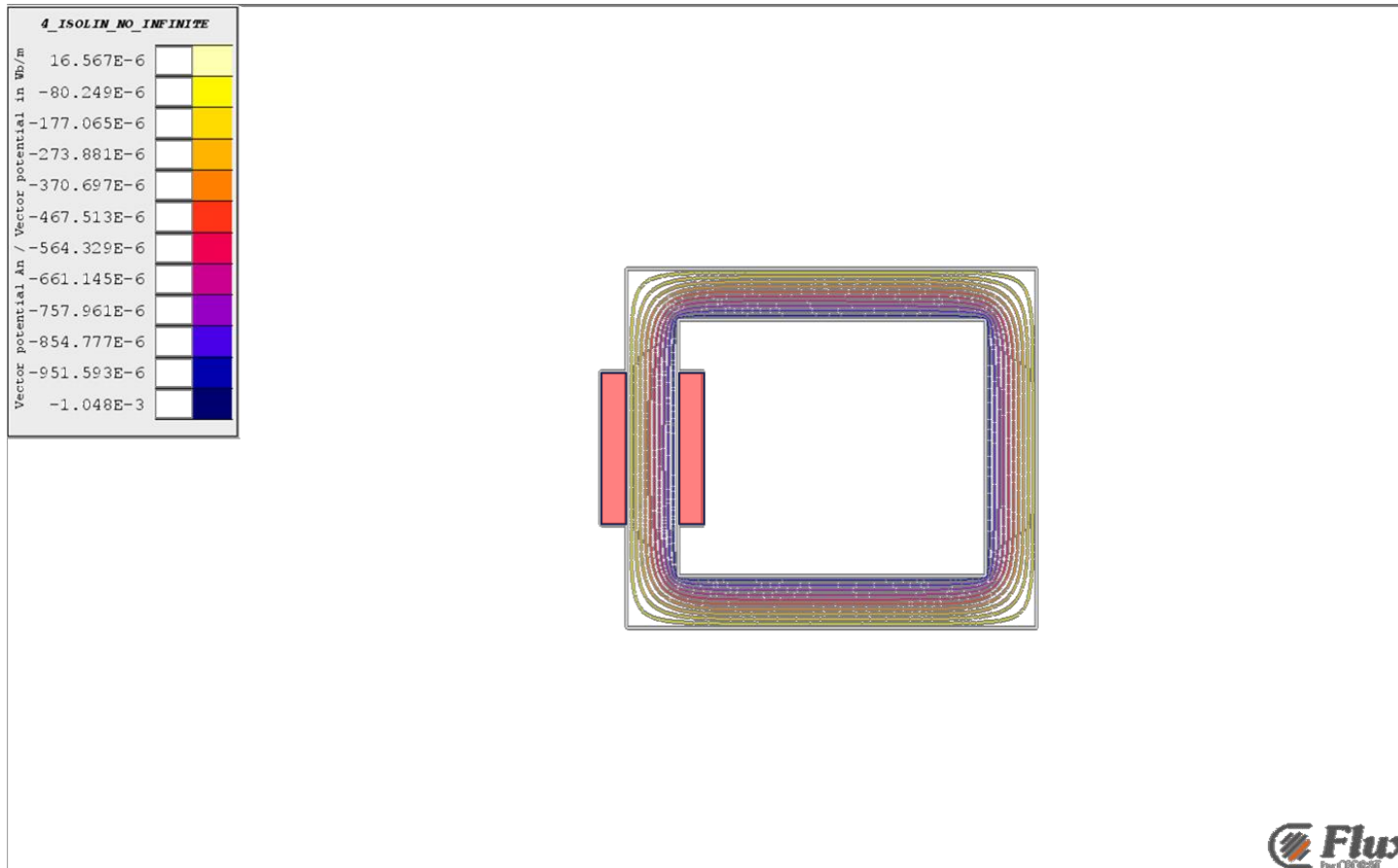


# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)



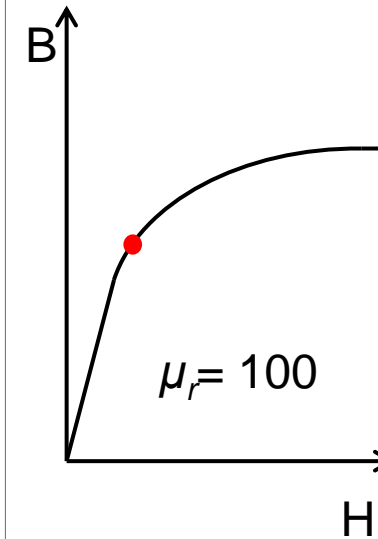
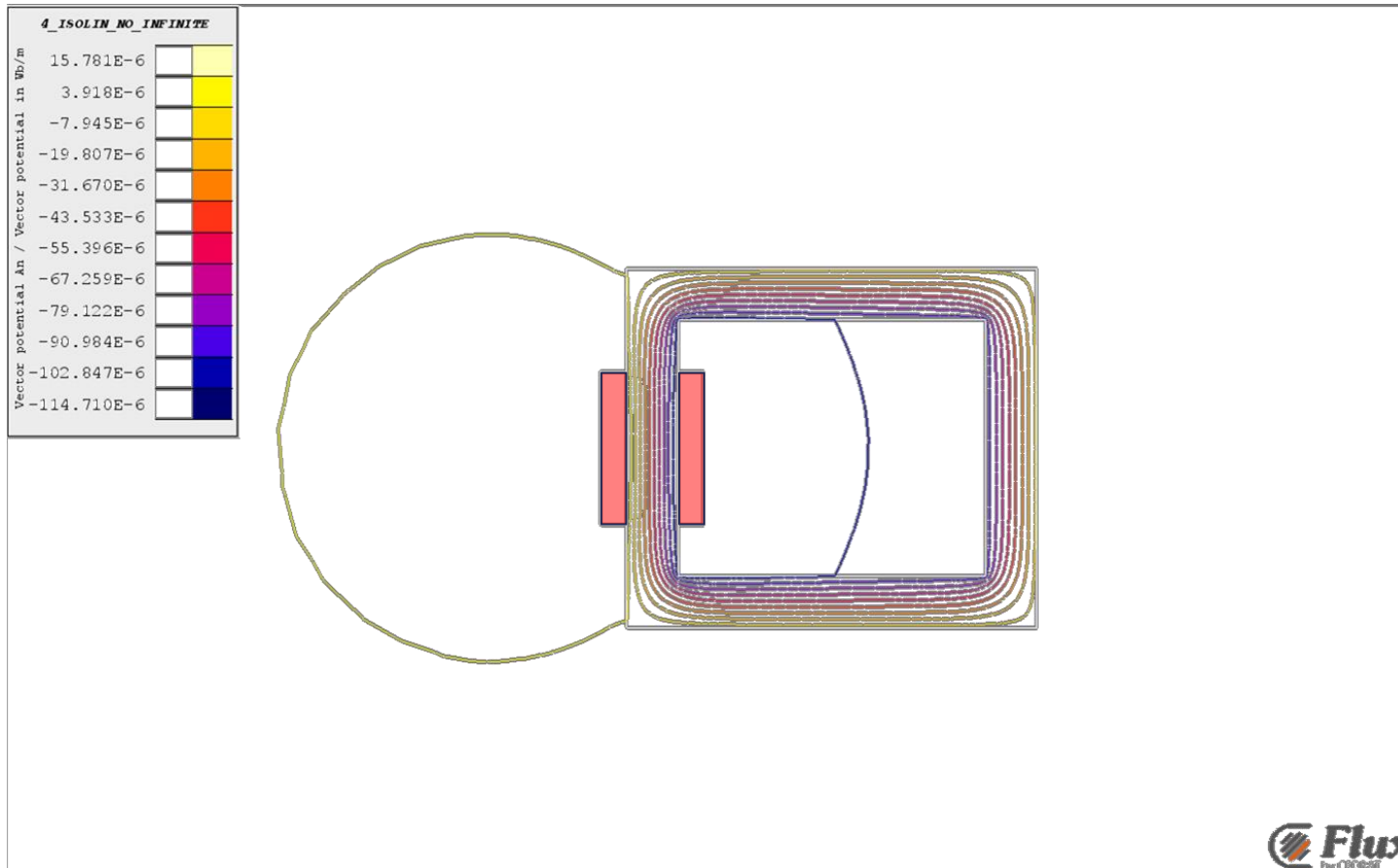


# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)





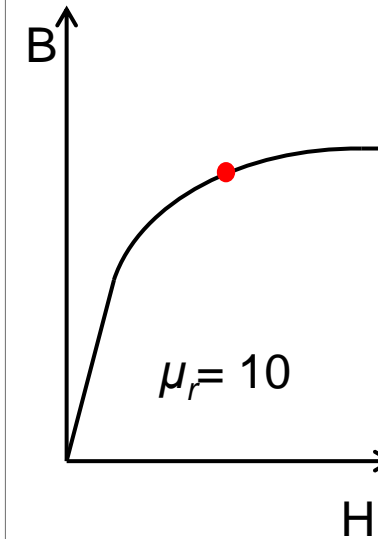
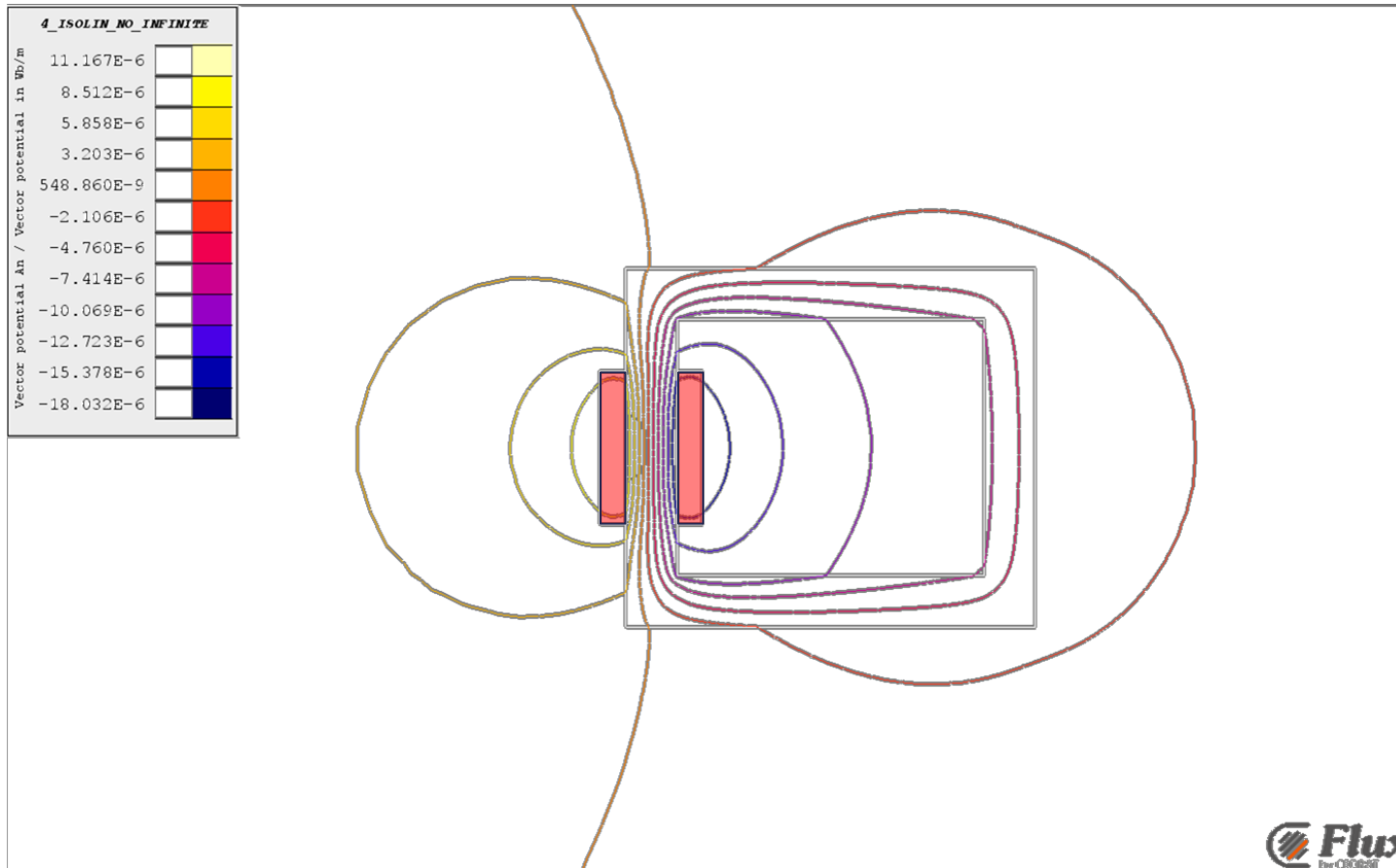
# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)





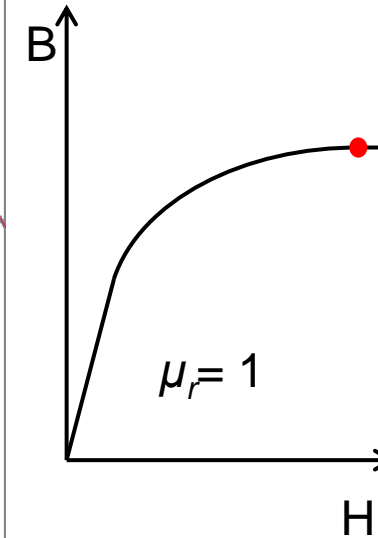
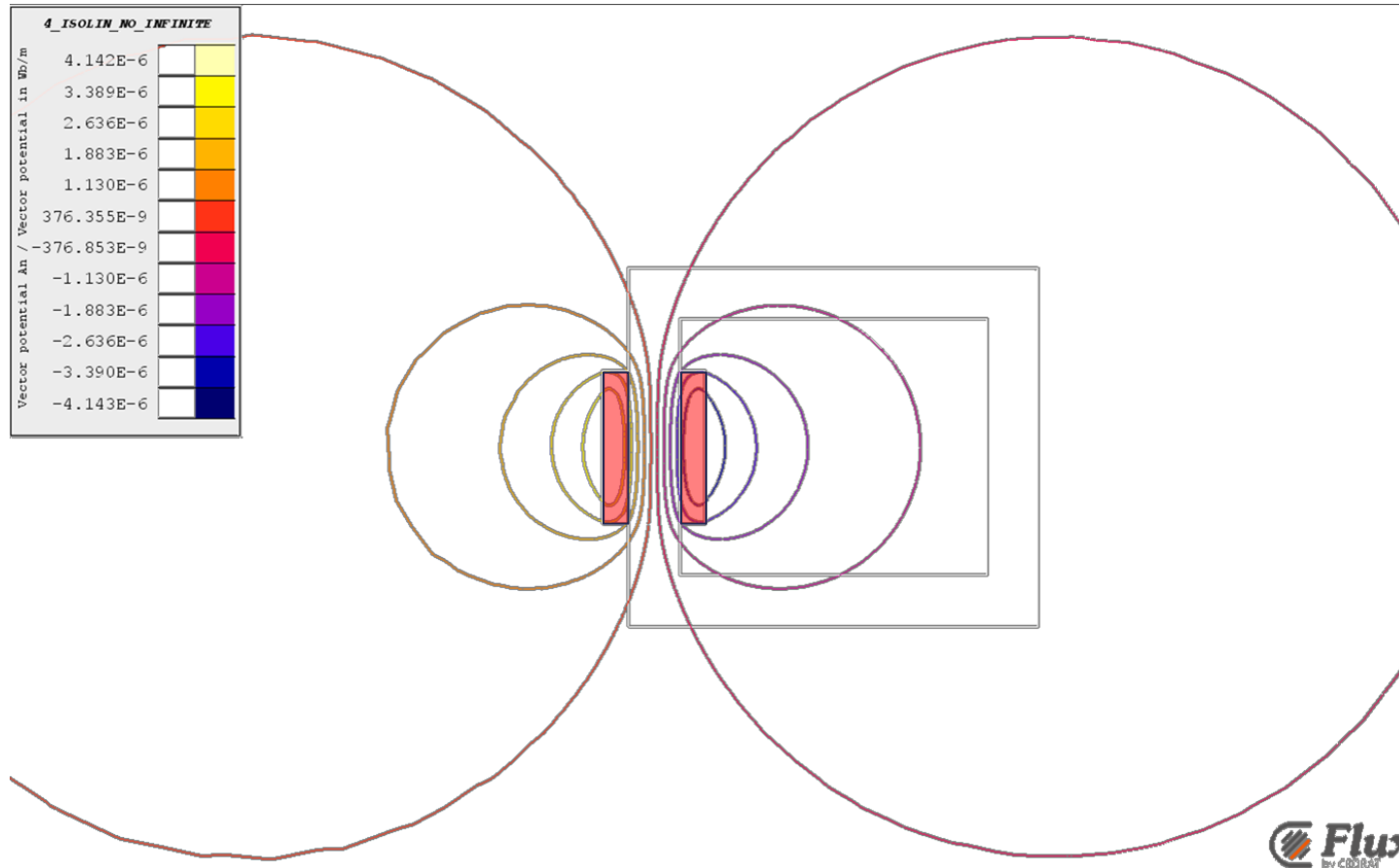


# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)





# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

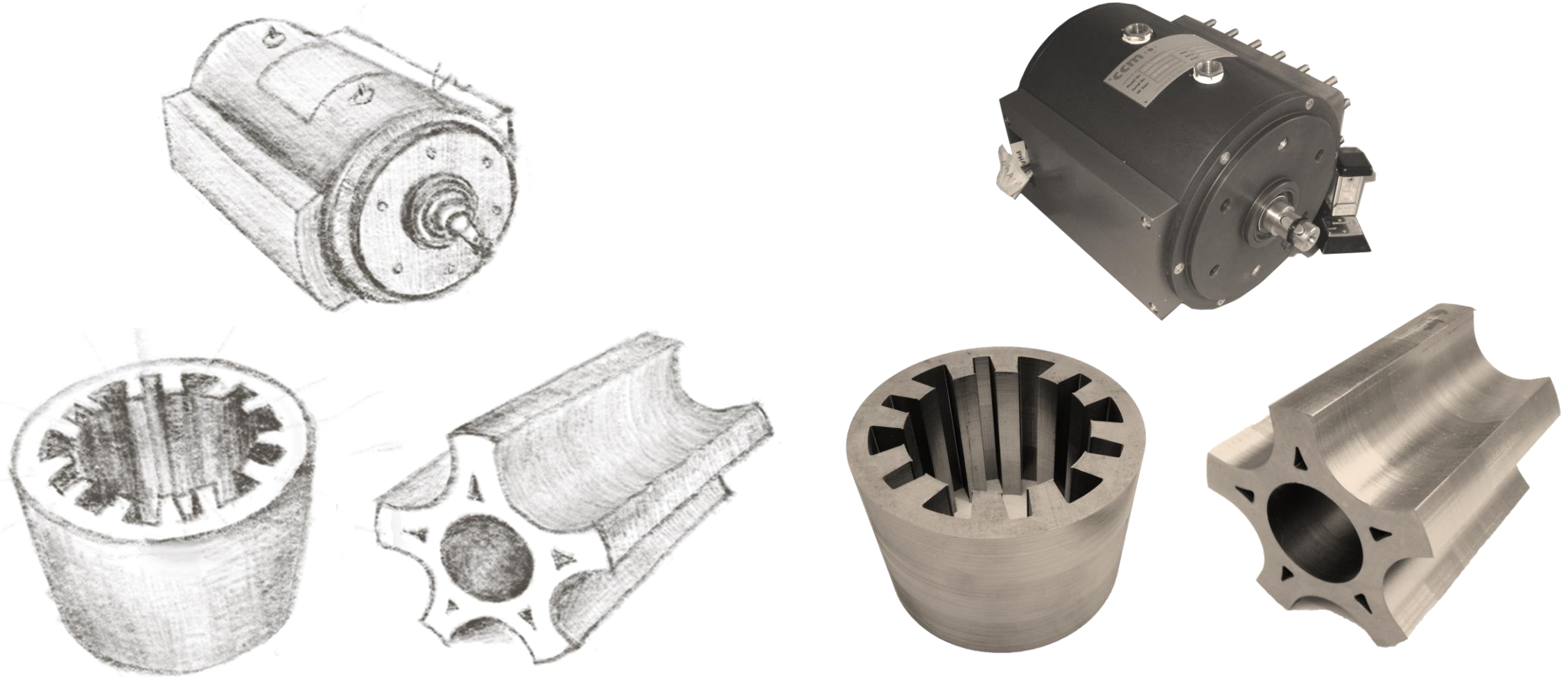




# ELECTRICAL MACHINE EXAMPLE WITHOUT PERMANENT MAGNETS >>



# ELECTRICAL NETWORK: MAGNETIC EQUIVALENT CIRCUIT (MEC)

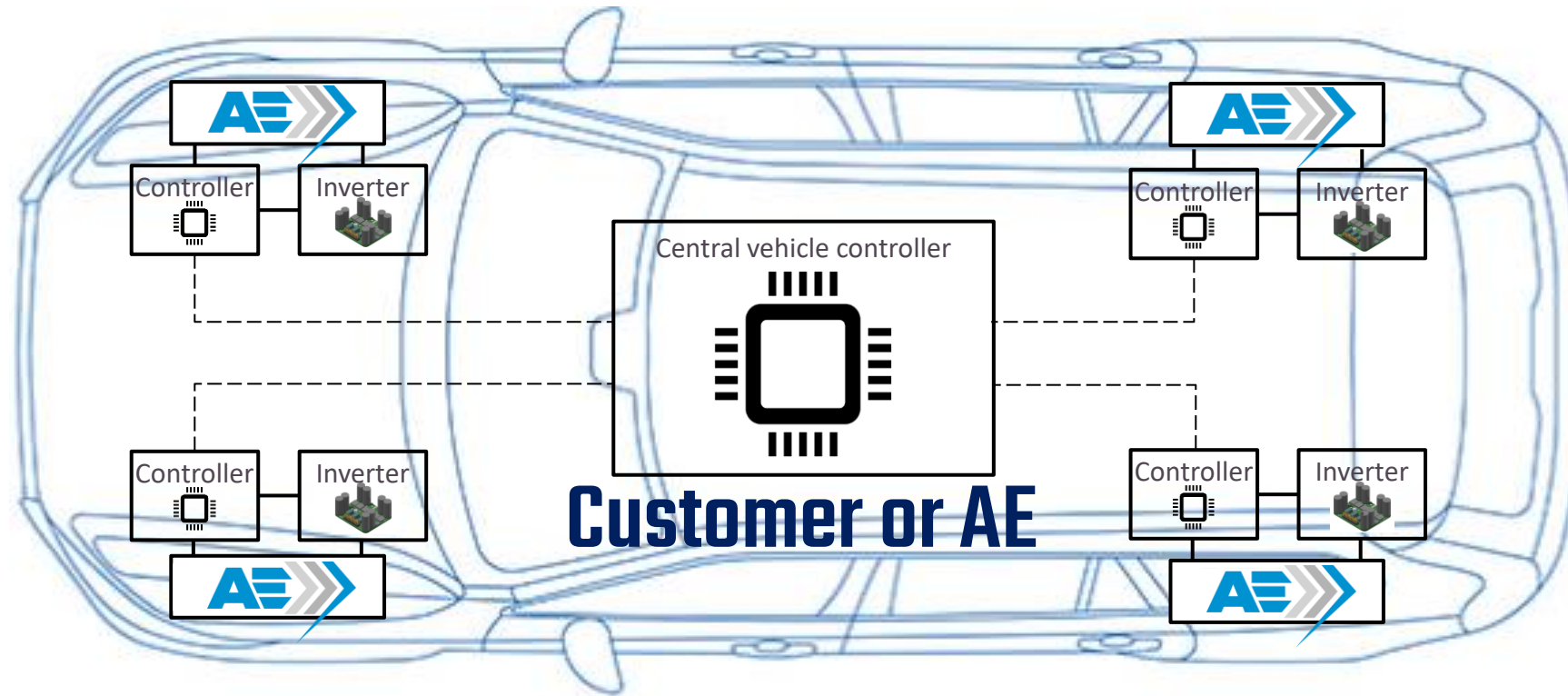






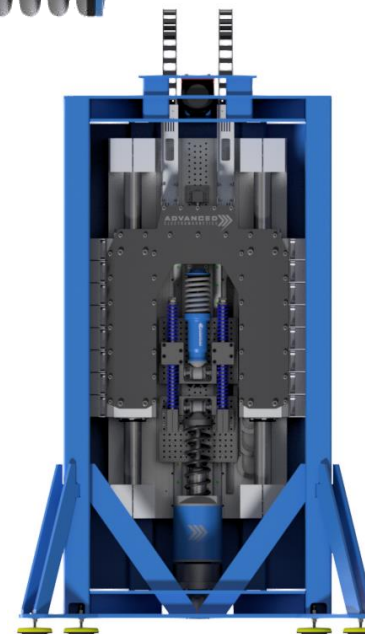
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