

Spin Torque Oscillator from micromagnetic point of view

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Modeling & simulation

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- # What is a spin torque oscillator?
- # Why we are interested in ST oscillator?
- # Which are the modeling tools to describe them?
- # Out-of-plane precision (OPP)
- # In-plane precision (IPP)

The magnetization acts on the current



**GMR / TMR
phenomena**

Action-reaction principle:

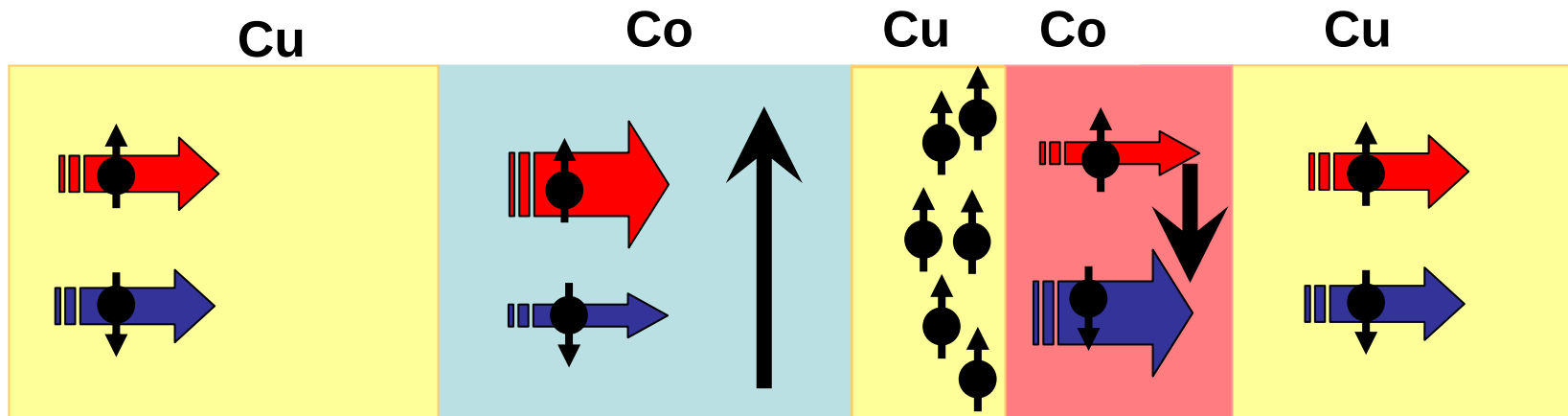
"Every action has an equal and opposite reaction."

The polarized current acts
on the magnetization



**Spin torque
phenomena**

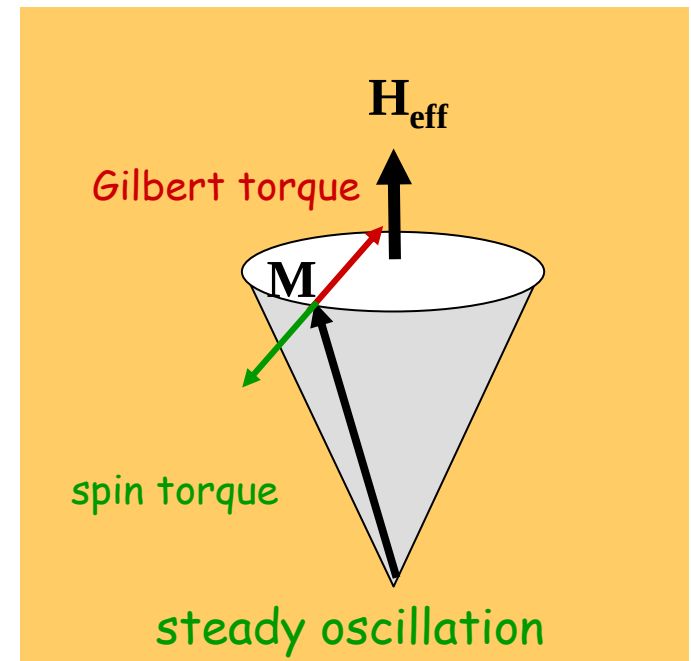
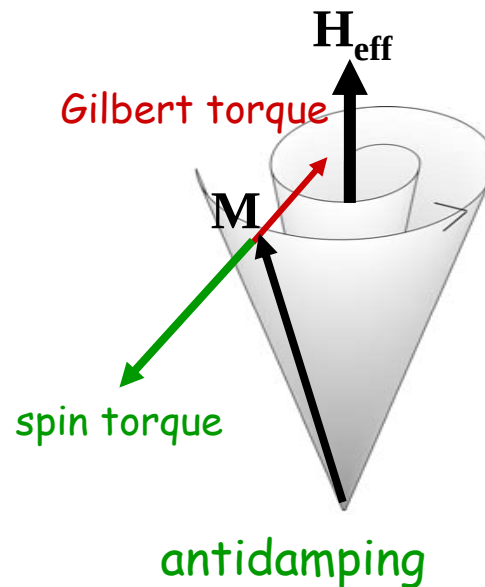
Basic picture ... ($J < 0$)



Exchange interaction between injected polarized $e^- \uparrow$ and local magnetization causes the magnetization switching in the direction parallel to the spin of the injected e^-

Landau-Lifshitz-Gilbert equation + polarized current

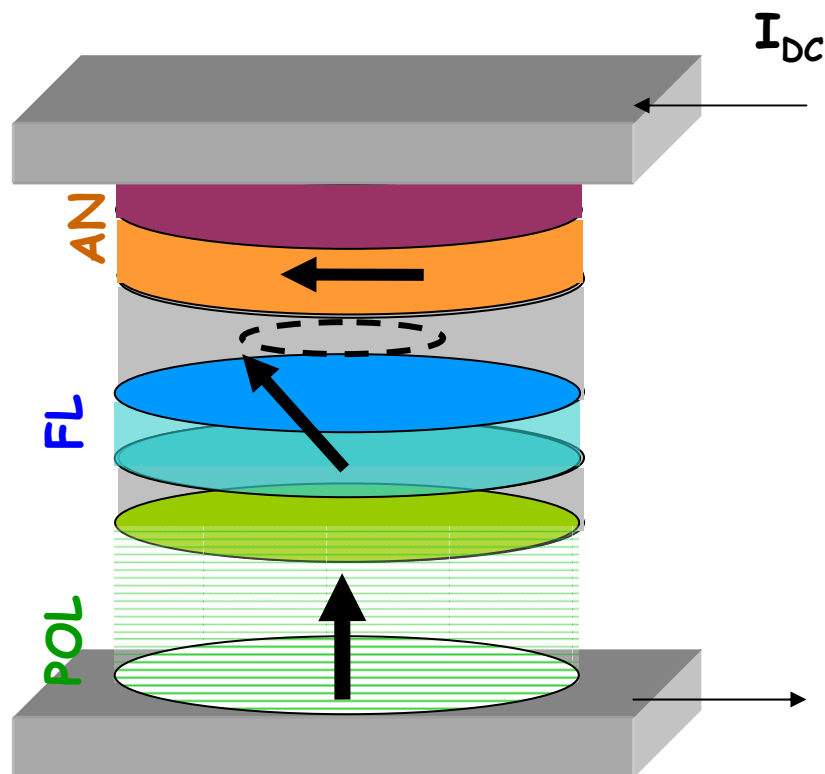
$$\begin{cases} \frac{\partial \mathbf{M}}{\partial t} = -\gamma_0 [\mathbf{M} \times \mathbf{H}_{\text{eff}}] + \alpha \left(\mathbf{M} \times \frac{\partial \mathbf{M}}{\partial t} \right) + \left(\frac{\partial \mathbf{M}}{\partial t} \right)_{ST} \\ \mathbf{M}^2 = 1 \end{cases}$$



Perpendicular spin torque oscillator

Main goal → generate steady oscillations without applying field

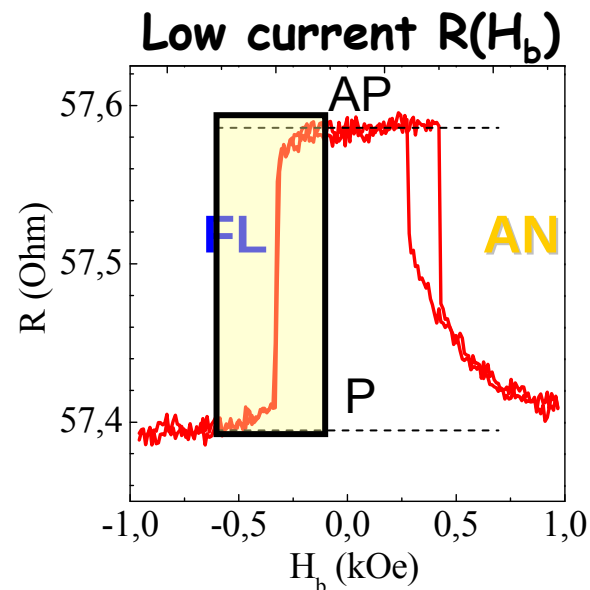
Pt / (Co/Pt)/PEL / Cu/Py/Cu/Co/IrMn



J. C. Slonczewski US5695864

K. J. Lee APL 86 (2005)

O. Redon US6,532,164 B2



Ellipse of 60x70 nm²

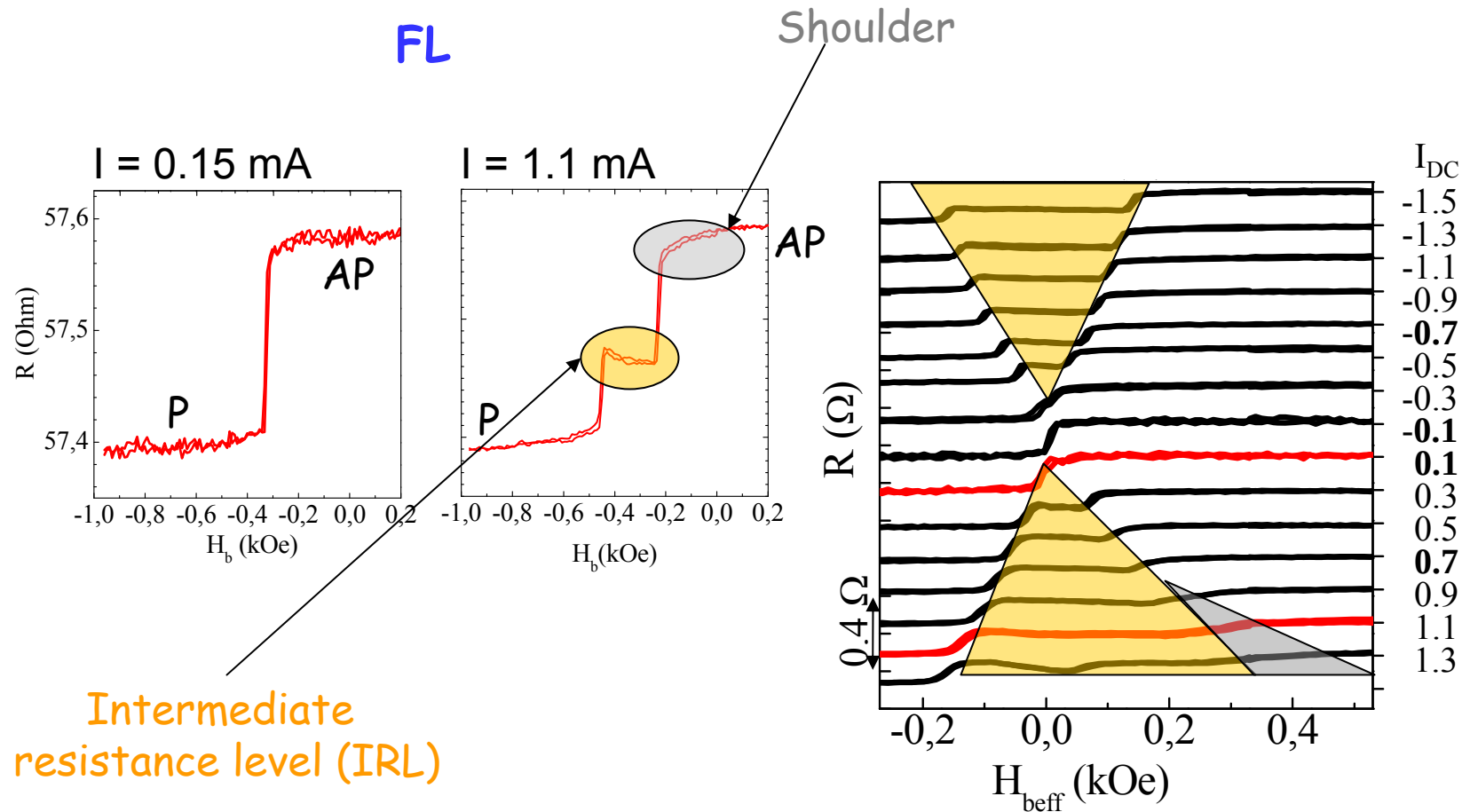
$I_{DC} = 0.15$ mA

$\Delta R = 0.19\Omega$

MR=0.3%

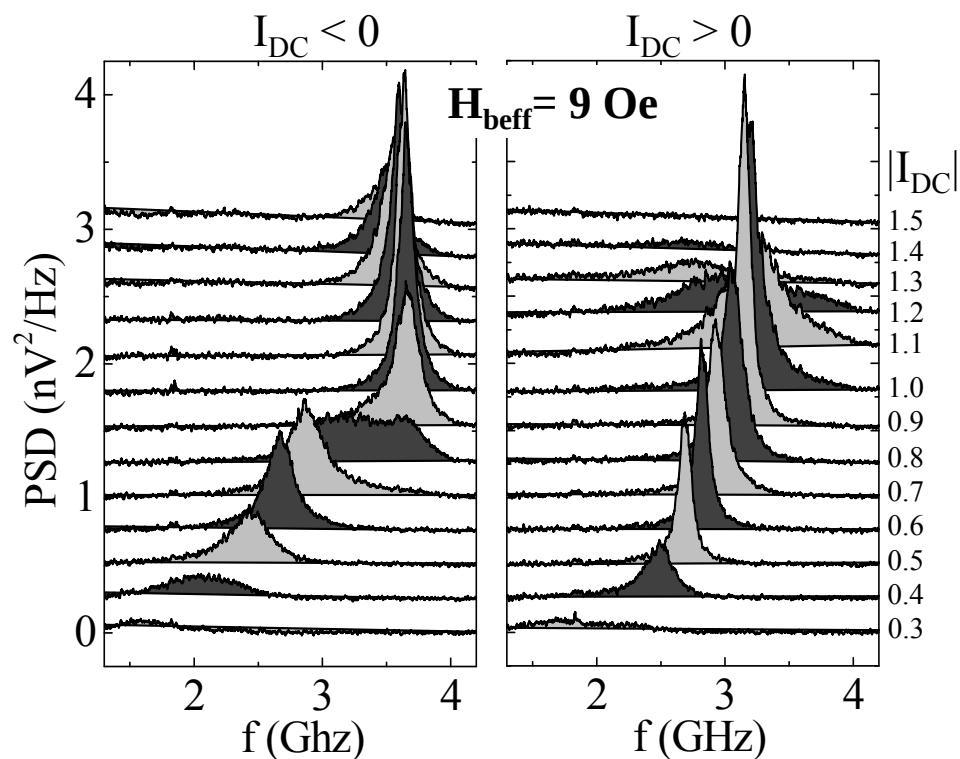
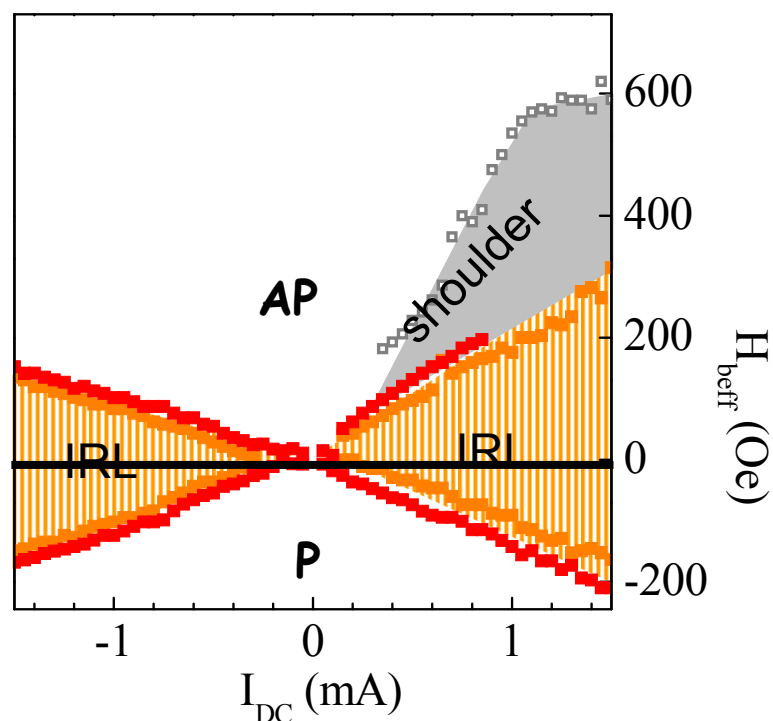
Houssameddine et al. Nat. Mat. 6, 447 (2007)

Perpendicular spin torque oscillator



→ There are two magnetoresistive states Houssameddine et al. Nat. Mat. 6, 447 (2007)

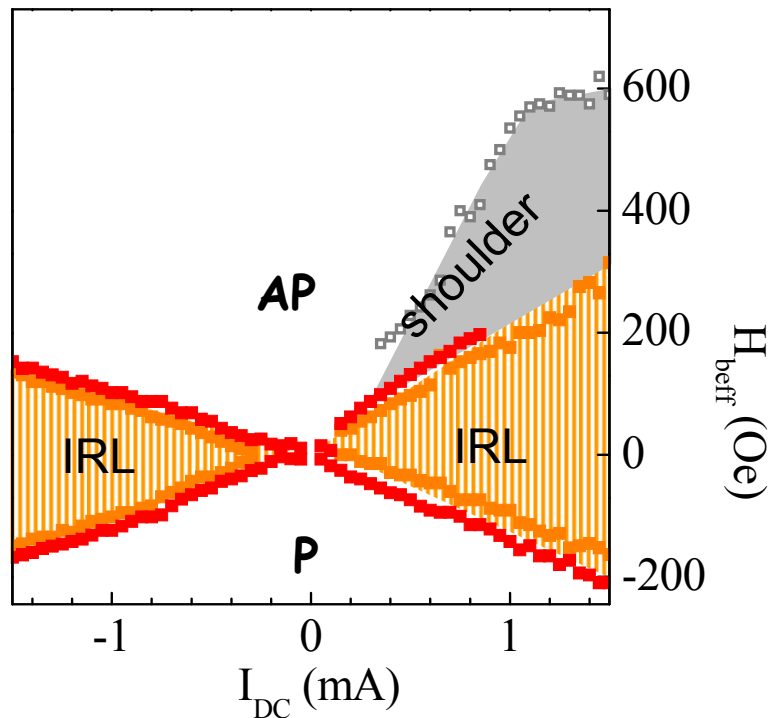
Static current- field diagram



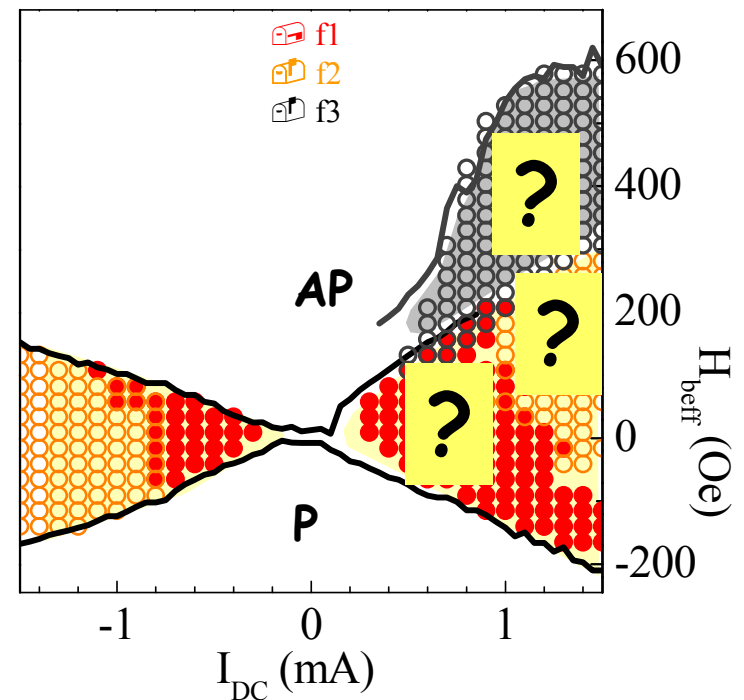
Houssameddine et al. Nat. Mat. 6, 447 (2007)

Perpendicular spin torque oscillator

Static current- field diagram



Dynamic current- field diagram



Houssameddine et al. Nat. Mat. 6, 447 (2007)

➤ Full 3D integration of

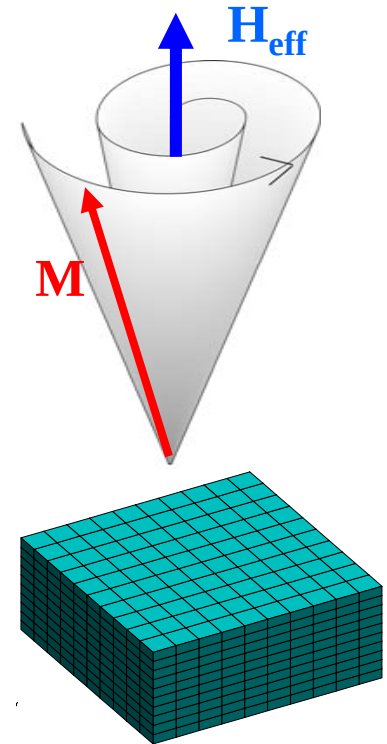
a) the Landau-Lifshitz-Gilbert (LLG) equation

$$\frac{\partial \mathbf{M}}{\partial t} = -\gamma_0 [\mathbf{M} \times \mathbf{H}_{\text{eff}}] + \alpha \left(\mathbf{M} \times \frac{\partial \mathbf{M}}{\partial t} \right)$$

$$\mathbf{M}^2 = 1$$

$$\mathbf{H}_{\text{eff}} = -\frac{1}{\mu_0 M_s} \frac{\delta E}{\delta \mathbf{M}}$$

$$E = E_{\text{ex}} + E_{\text{anis}} + E_{\text{dem}} + E_{\text{app}}$$



b) the magnetostatic equations

$$\mathbf{H}_{\text{dem}}(\mathbf{r}) = -\int_V \nabla G(\mathbf{r} - \mathbf{r}') \rho_m(\mathbf{r}') dV' - \oint_S \nabla G(\mathbf{r} - \mathbf{r}') \sigma_m(\mathbf{r}') dS'$$

c) Addition term due to the spin torque transfer

$$\begin{cases} \frac{\partial \mathbf{M}}{\partial t} = -\gamma_0 [\mathbf{M} \times \mathbf{H}_{\text{eff}}] + \alpha \left(\mathbf{M} \times \frac{\partial \mathbf{M}}{\partial t} \right) + \left(\frac{\partial \mathbf{M}}{\partial t} \right)_{ST} \\ \mathbf{M}^2 = 1 \end{cases}$$

$$\left(\frac{\partial \mathbf{M}}{\partial t} \right)_{ST} = -\gamma_0 a_J [\mathbf{M} \times (\mathbf{M} \times \mathbf{m}_{\text{PL}})]$$



J. C. Slonczewski
JMMM. 159, L1 (1996)

« ballistic transport model »

ST-GLFFT

$$\left(\frac{\partial \mathbf{M}}{\partial t} \right)_{ST} = c_0 [\mathbf{m} \times \mathbf{M}]$$



A. Vedyeyev, D. Gusakova

« diffusive transport model »

LLG_SA

➤ Transport equation

$$\frac{\partial \mathbf{j}^m}{\partial z} + \frac{J_{sd}}{\eta} \mathbf{m} \times \mathbf{M} + \frac{\mathbf{m}}{\tau_{sf}} = 0$$

electron current

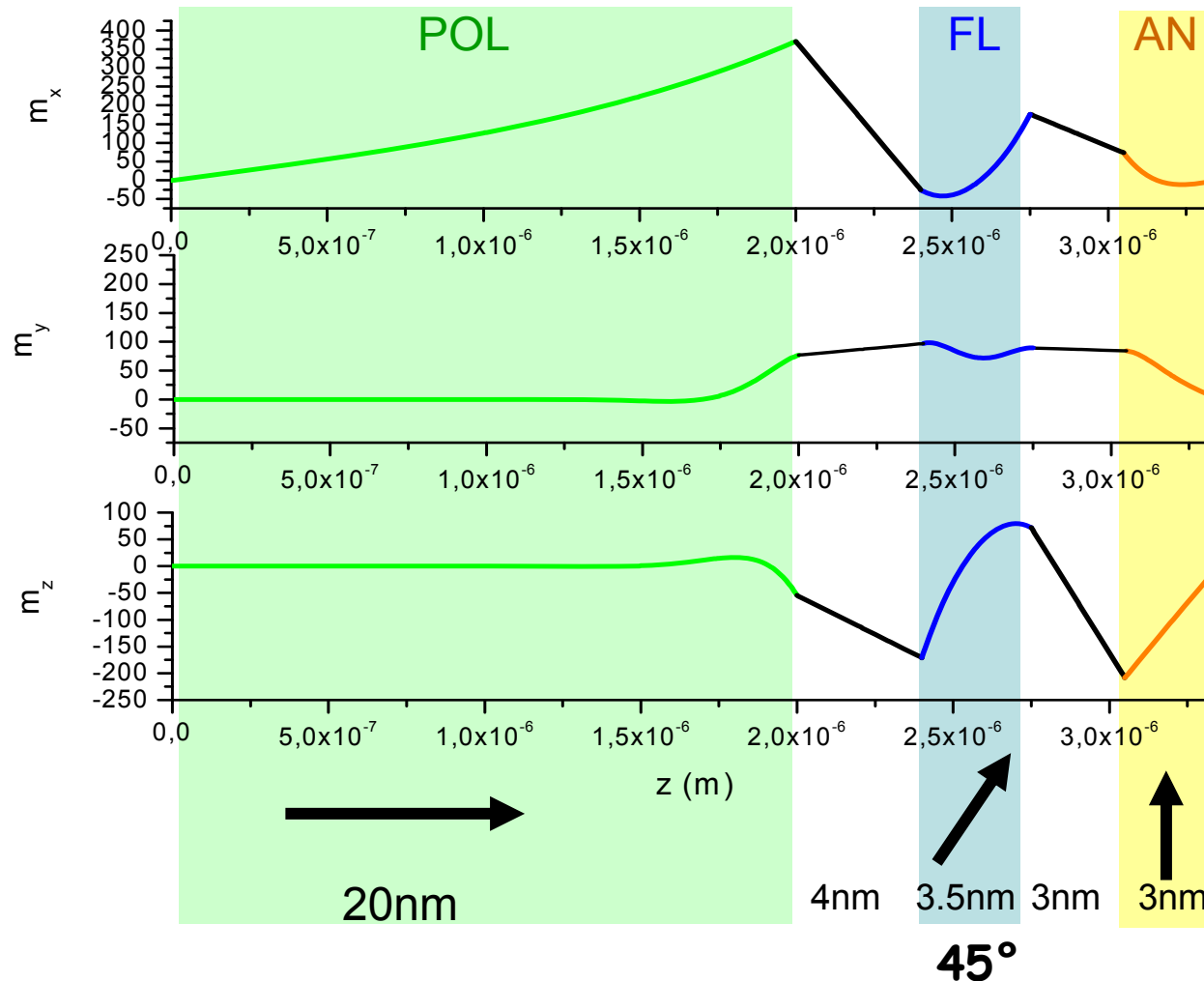
$$\mathbf{j}^e = \mathbf{j}^{\uparrow} + \mathbf{j}^{\downarrow} = \sigma_0 E_z - D_0 \partial_z n - D_0 \beta' (\mathbf{M} \cdot \partial_z \mathbf{m})$$

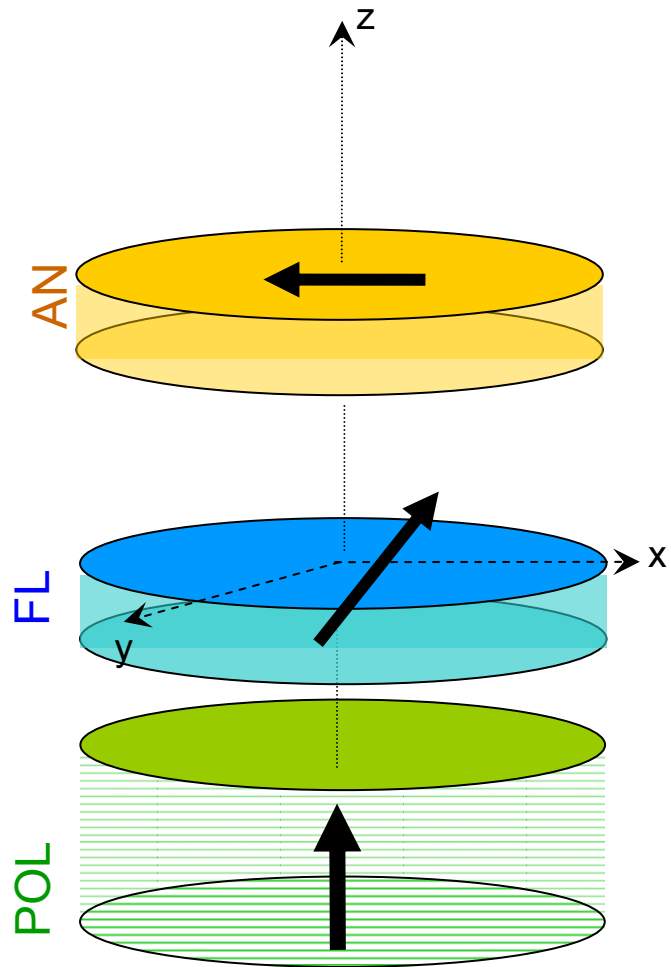
spin current

$$\mathbf{j}^m \Rightarrow \mathbf{j}^{\uparrow} - \mathbf{j}^{\downarrow} = \sigma_0 E_z \beta \mathbf{M} - D_0 \partial_z \mathbf{m} - D_0 \beta' \mathbf{M} \partial_z n$$

$$\left(\frac{\partial \mathbf{M}}{\partial t} \right)_{ST} = \frac{J_{sf}}{\mu_B} \mathbf{m} \times \mathbf{M}$$

➤ Transport equation





Micromagnetic parameters

Fixed layer

circular disk 60nm, thickness 3.5nm

$$M_s = 866 \text{ kA/m}$$

$$K_u = 664.5 \text{ J/m}^3 \parallel Ox \quad (H_u = 150 \text{ Oe})$$

$$A_{ex} = 2 \cdot 10^{-11} \text{ J/m}$$

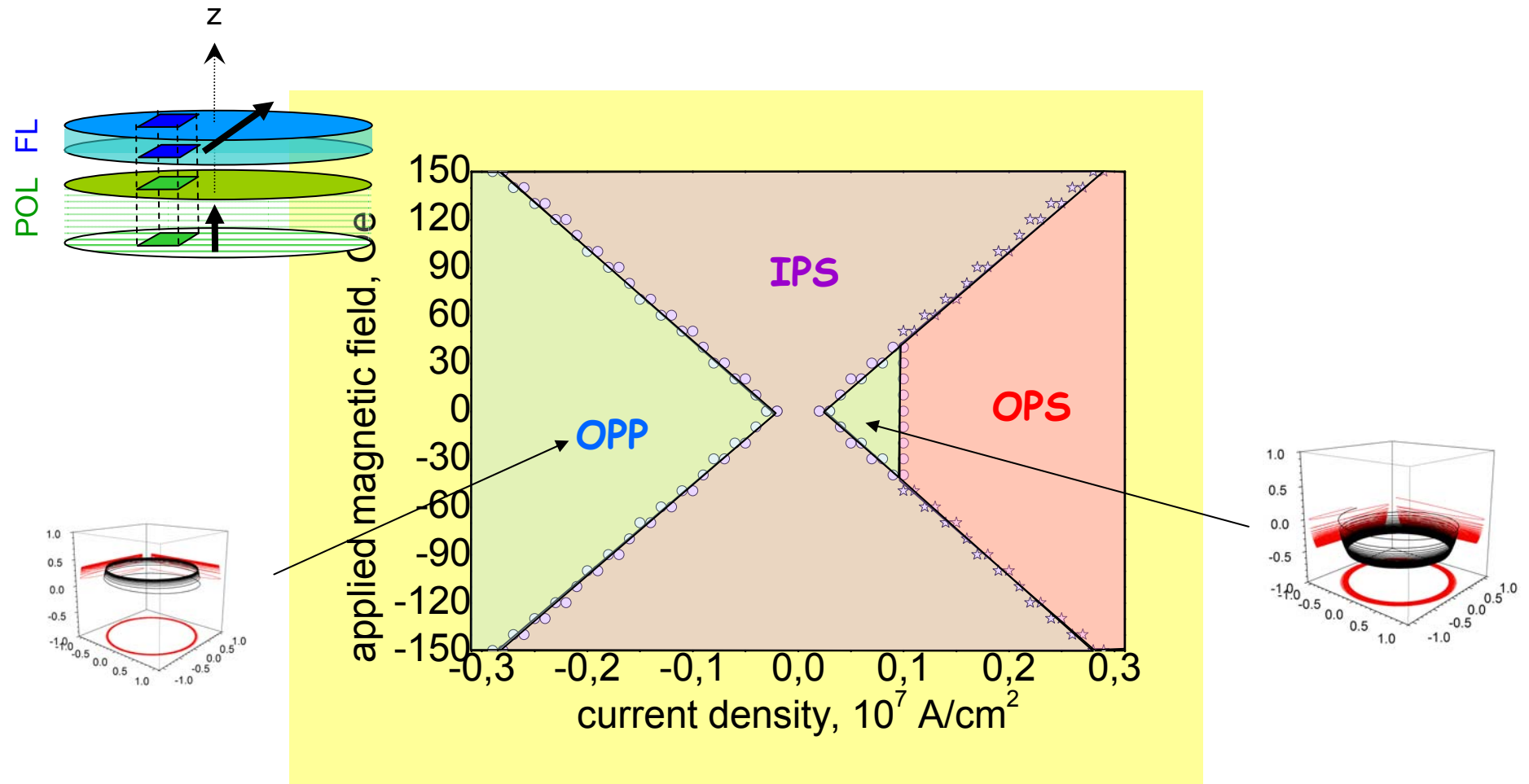
$$\alpha = 0.01$$

$$\text{Mesh size } 2 \times 2 \times 3.5 \text{ nm}^3$$

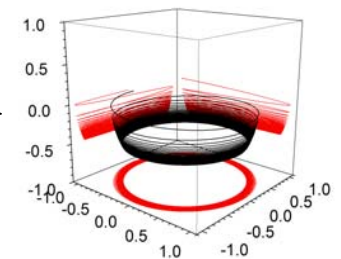
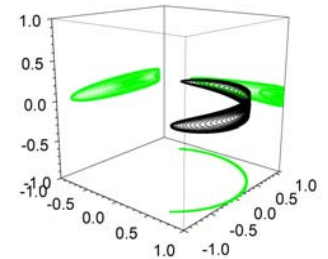
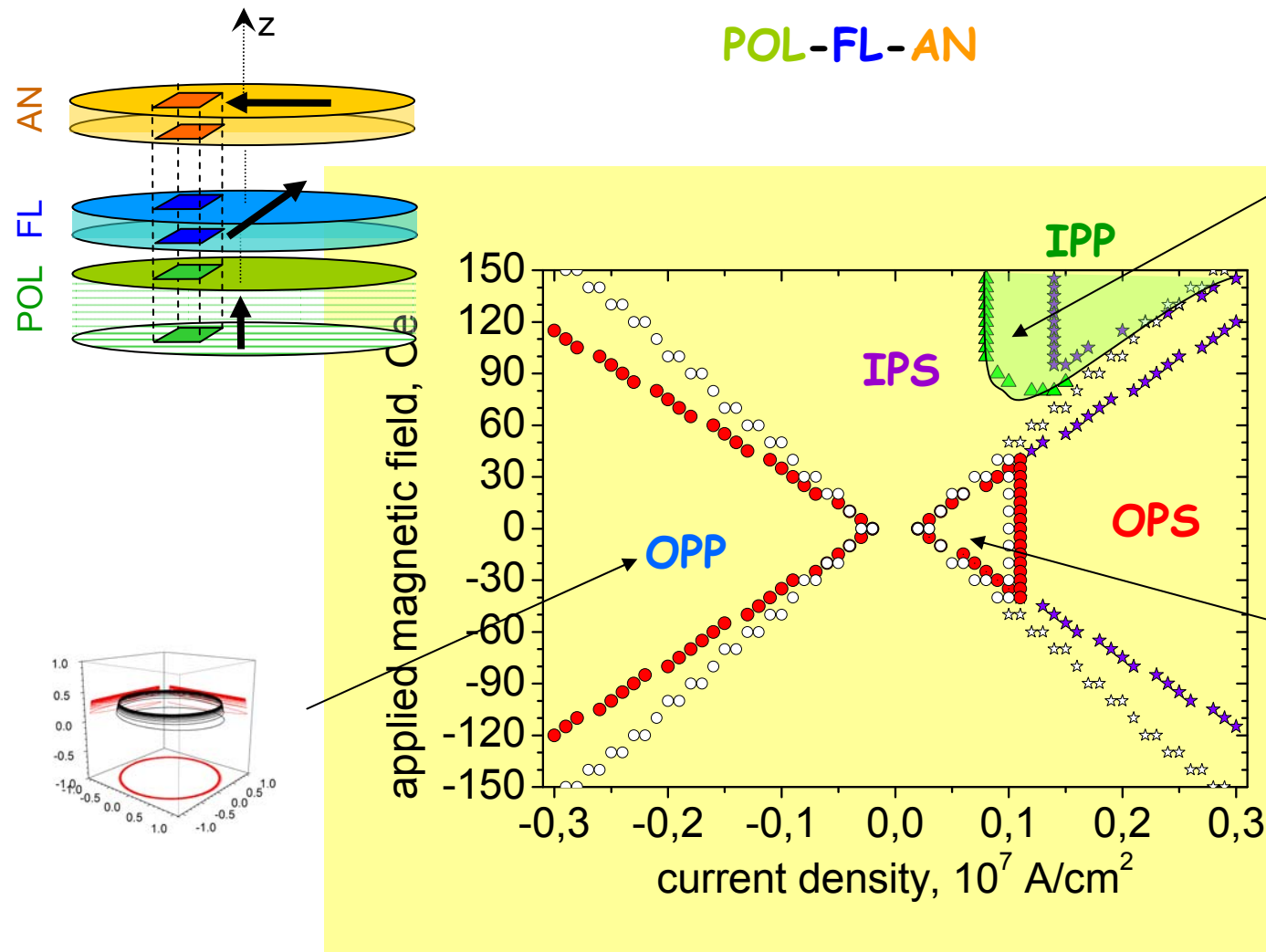
Fixed layer

Macrospin current-field diagram

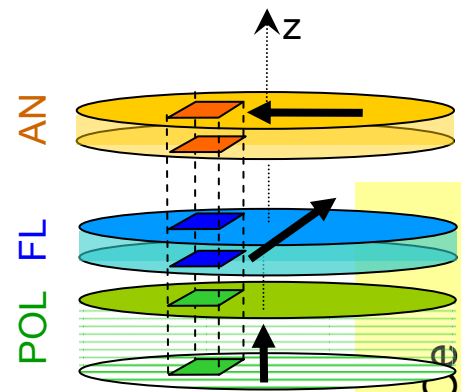
POL-FL



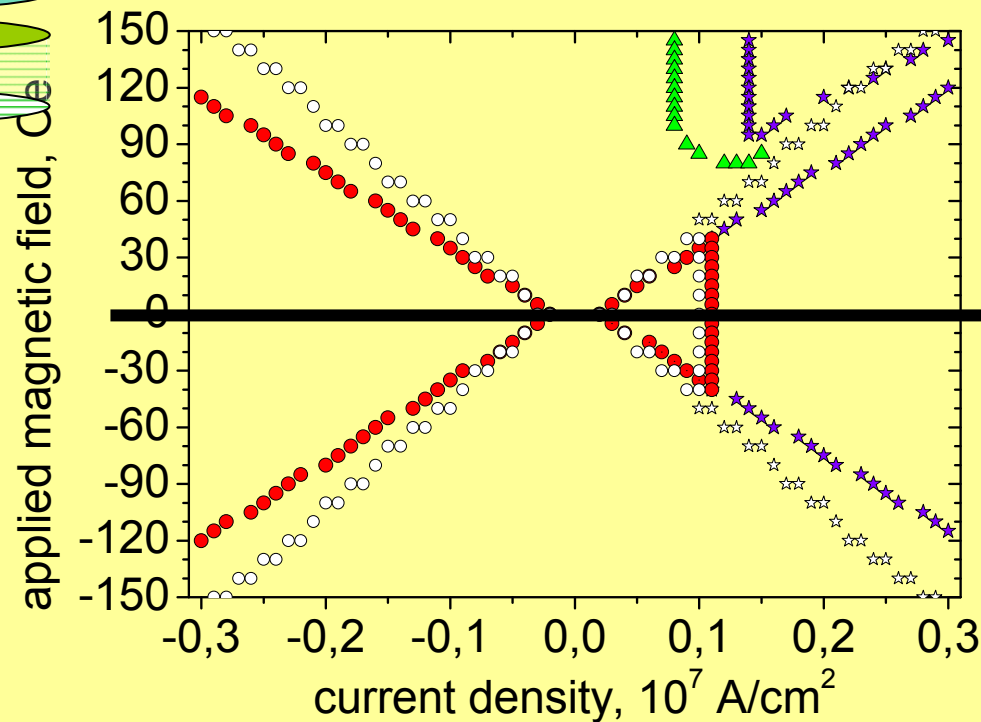
Macrospin current-field diagram



Macrospin current-field diagram

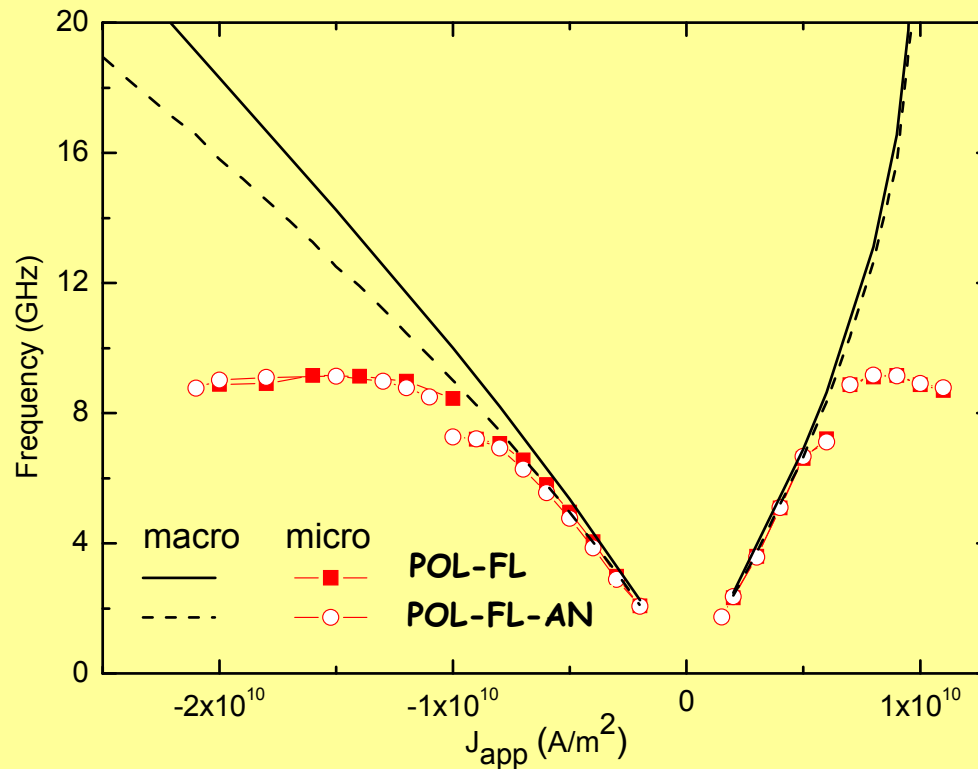


POL-FL-AN



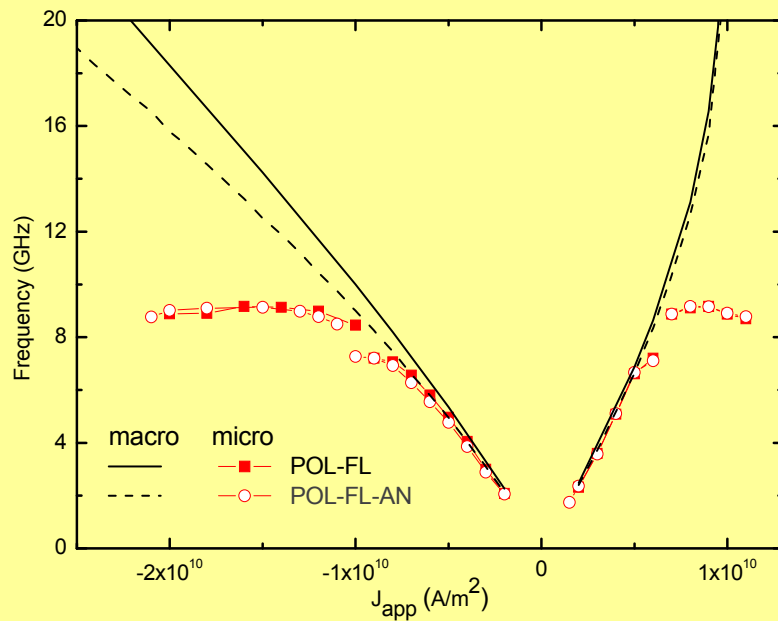
$H_{\text{app}}=0$

No applied field

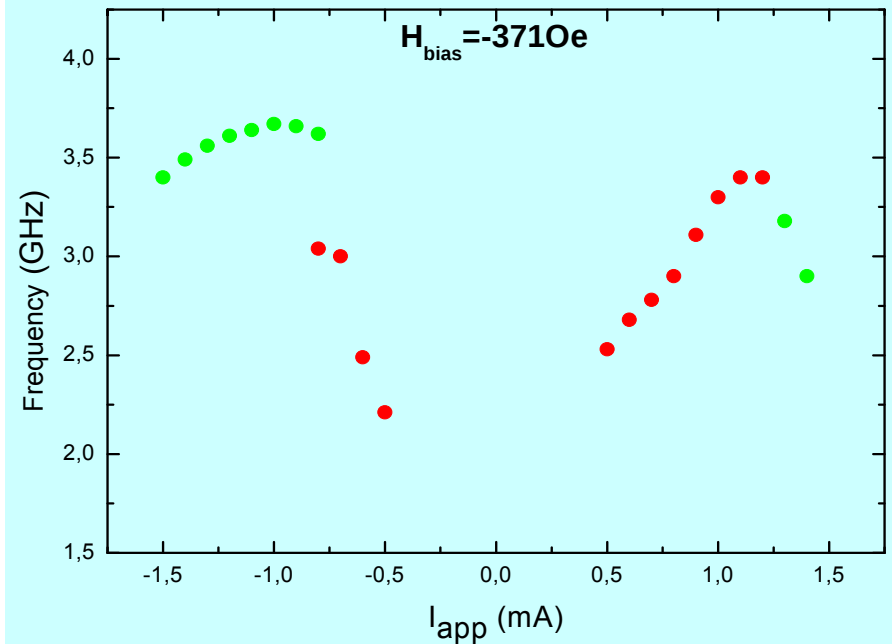


No applied field

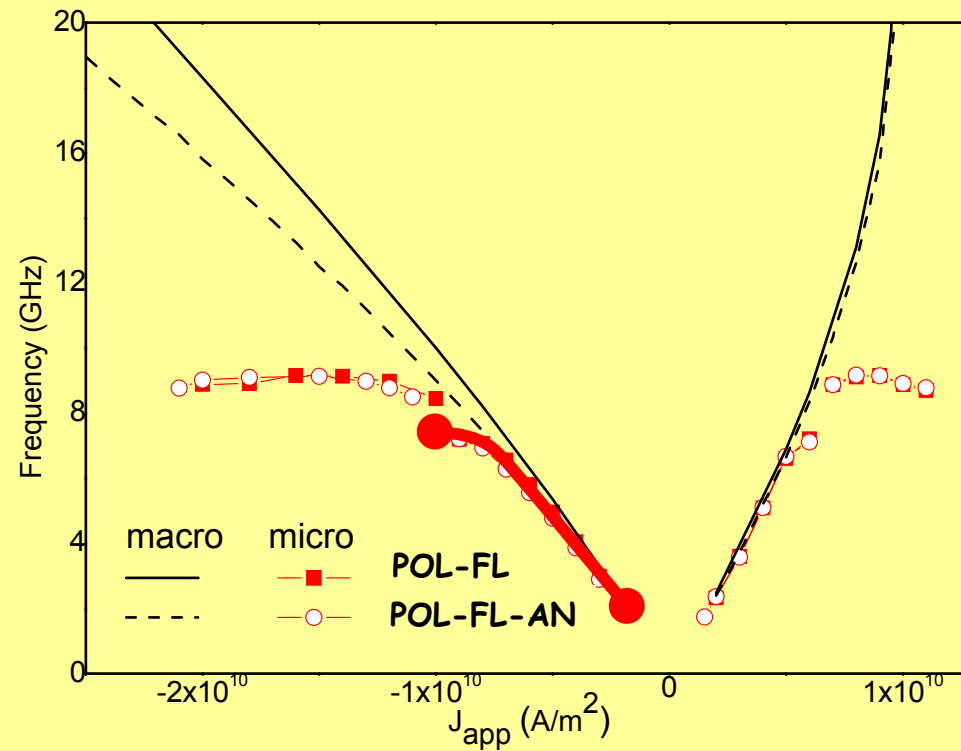
→ μ mag simulation



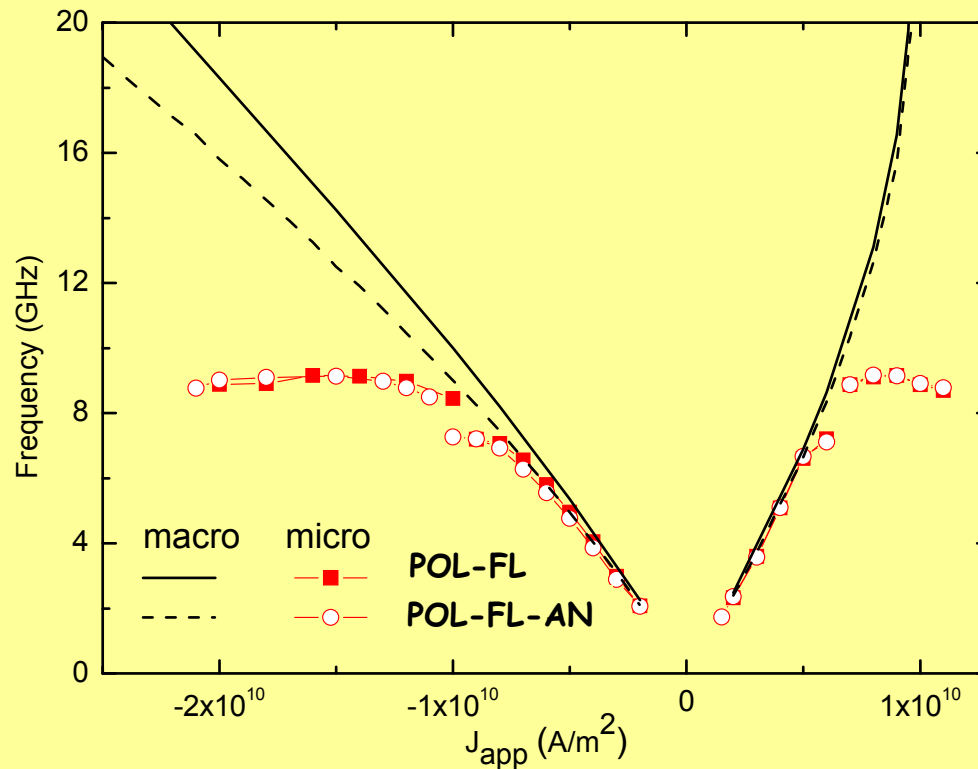
→ experimental data



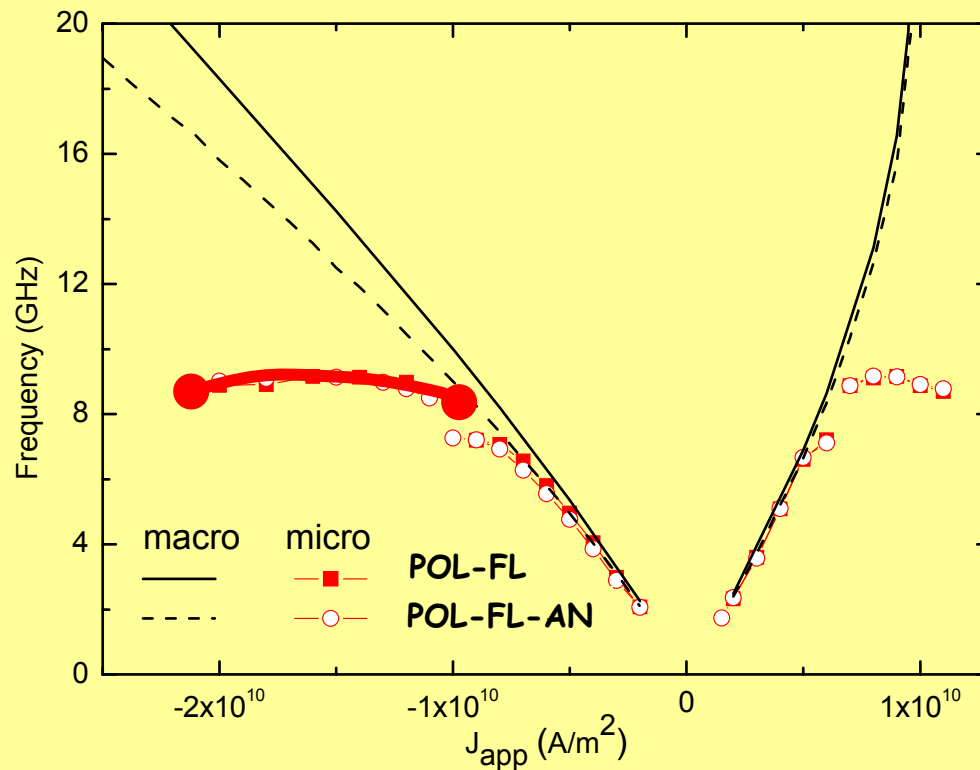
No applied field



No applied field

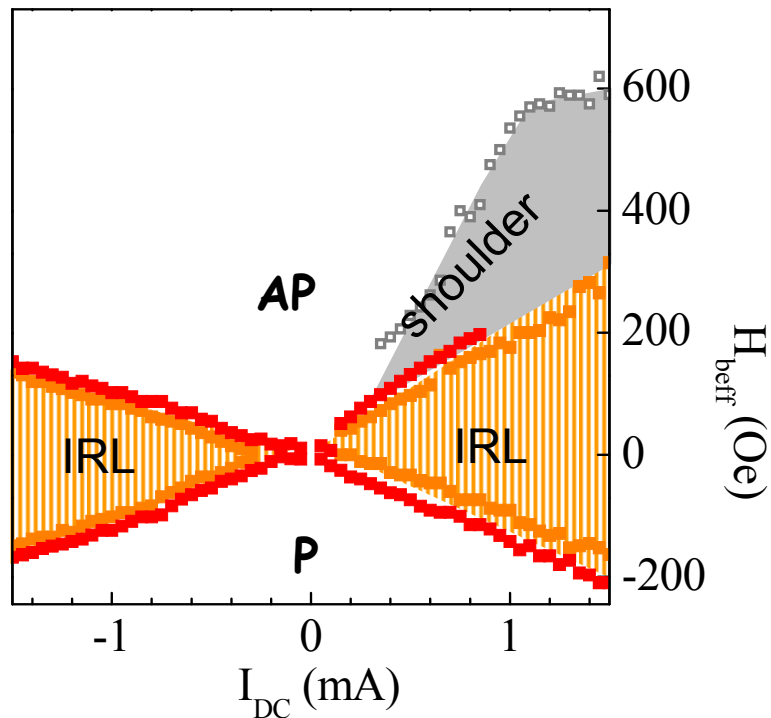


No applied field

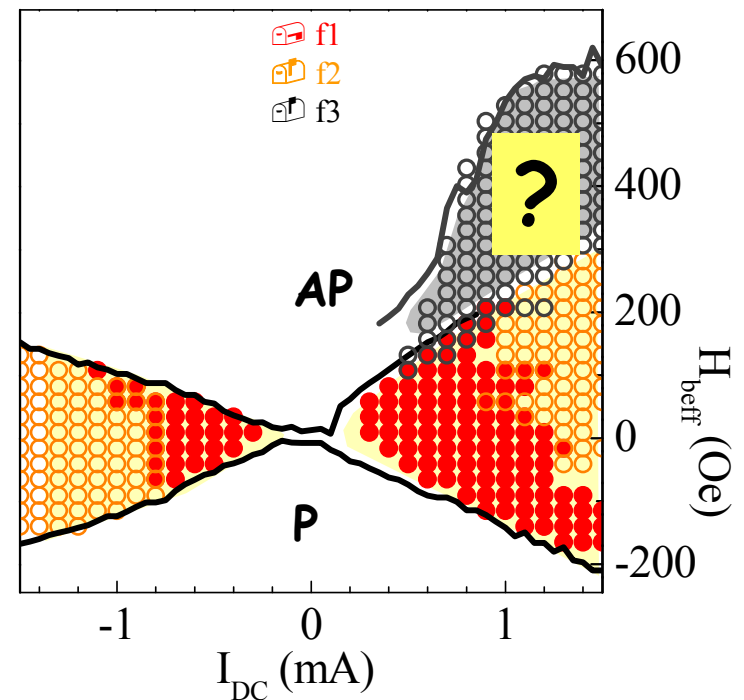


Perpendicular spin torque oscillator

Static current- field diagram

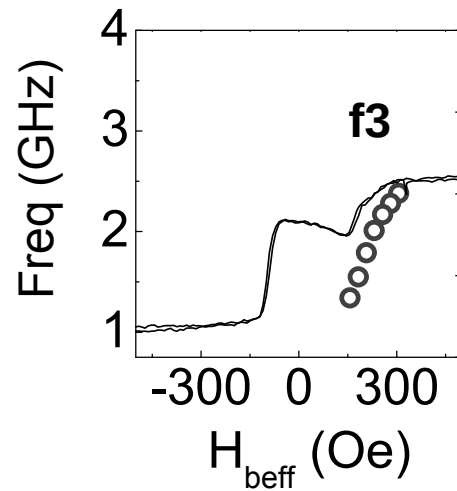
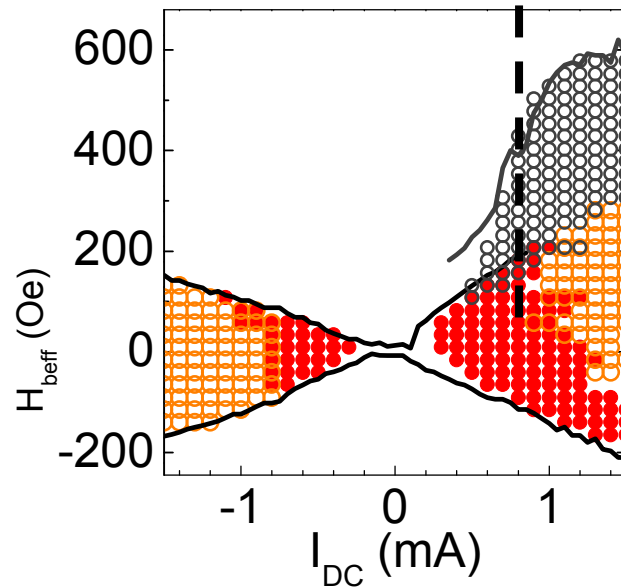


Dynamic current- field diagram

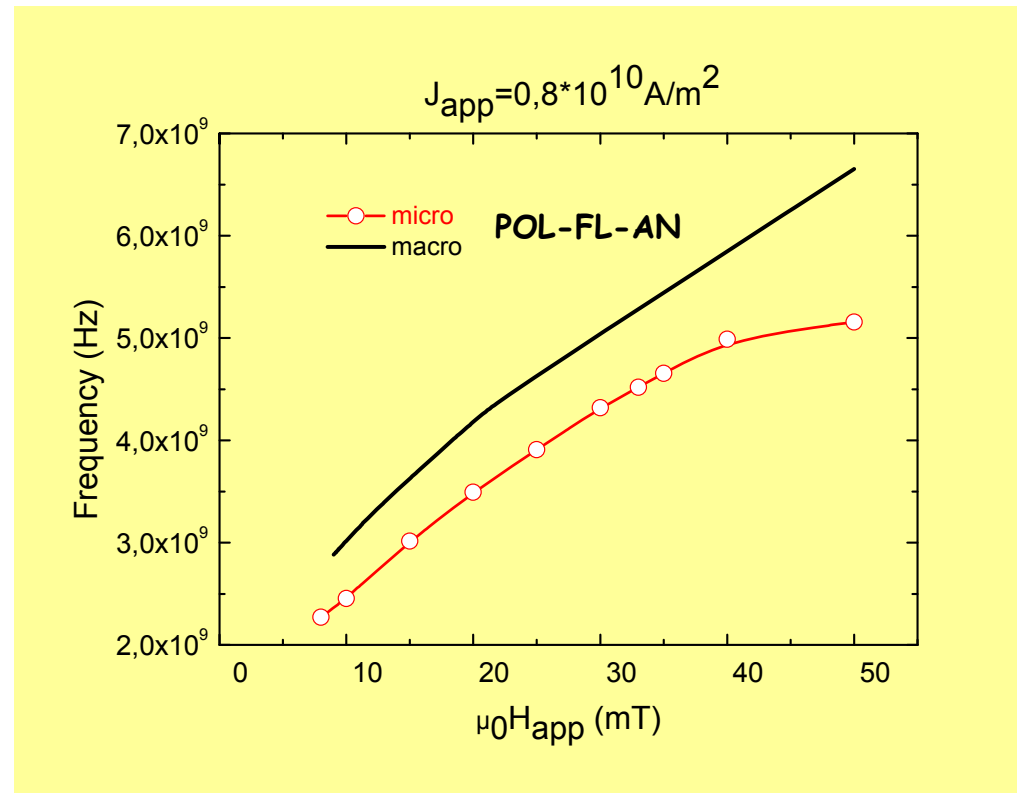


Houssameddine et al. accepted Nat. Mat.

→ experimental data



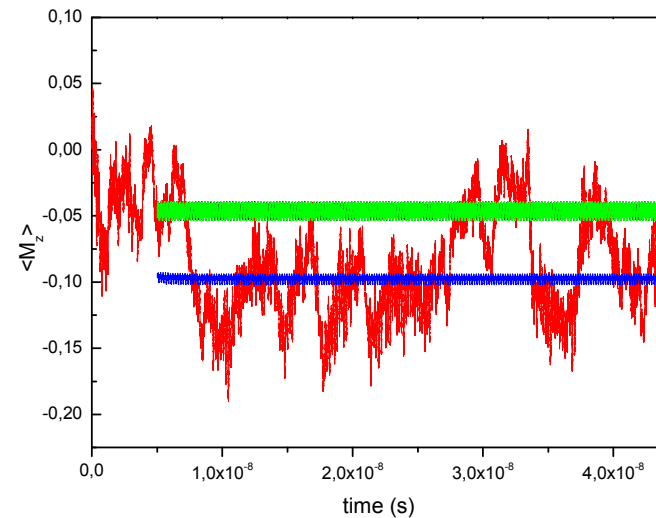
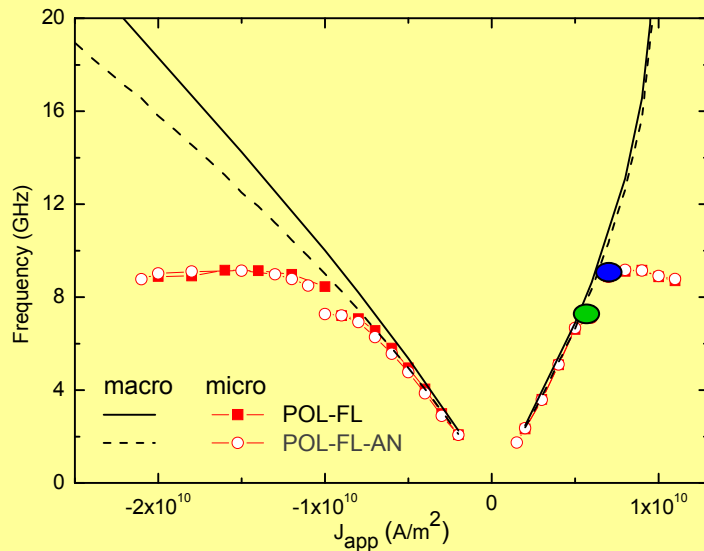
→ μmag simulation



Temperature effects

No applied field

→ μ mag simulation



before jump

after jump

T=400K

Solving self-consistently the LLG equation and the spin dependant transport equation:

- a) accurate investigation of structures with 2, 3 or more coupled magnetic layers
- b) qualitative good agreement with the experimental data
- c) "A toy" dedicated to the ST oscillator optimization for future device integration