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# Domains and domain walls

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**ETH** zürich

# References

*On the theory of the dispersion of magnetic permeability in ferromagnetic bodies*

L.D. Landau and E. Lifshitz

Phys. Z. Sowjet. 8, 153 (1935); Collected papers of L.D. Landau, pp.101-114

*Physical theory of ferromagnetic domains*

C. Kittel

Rev. Mod. Phys. 21, 541 (1949)

*Magnetic domains: the analysis of magnetic microstructures*

A. Hubert and R. Schafer (Springer, Berlin, 1998)

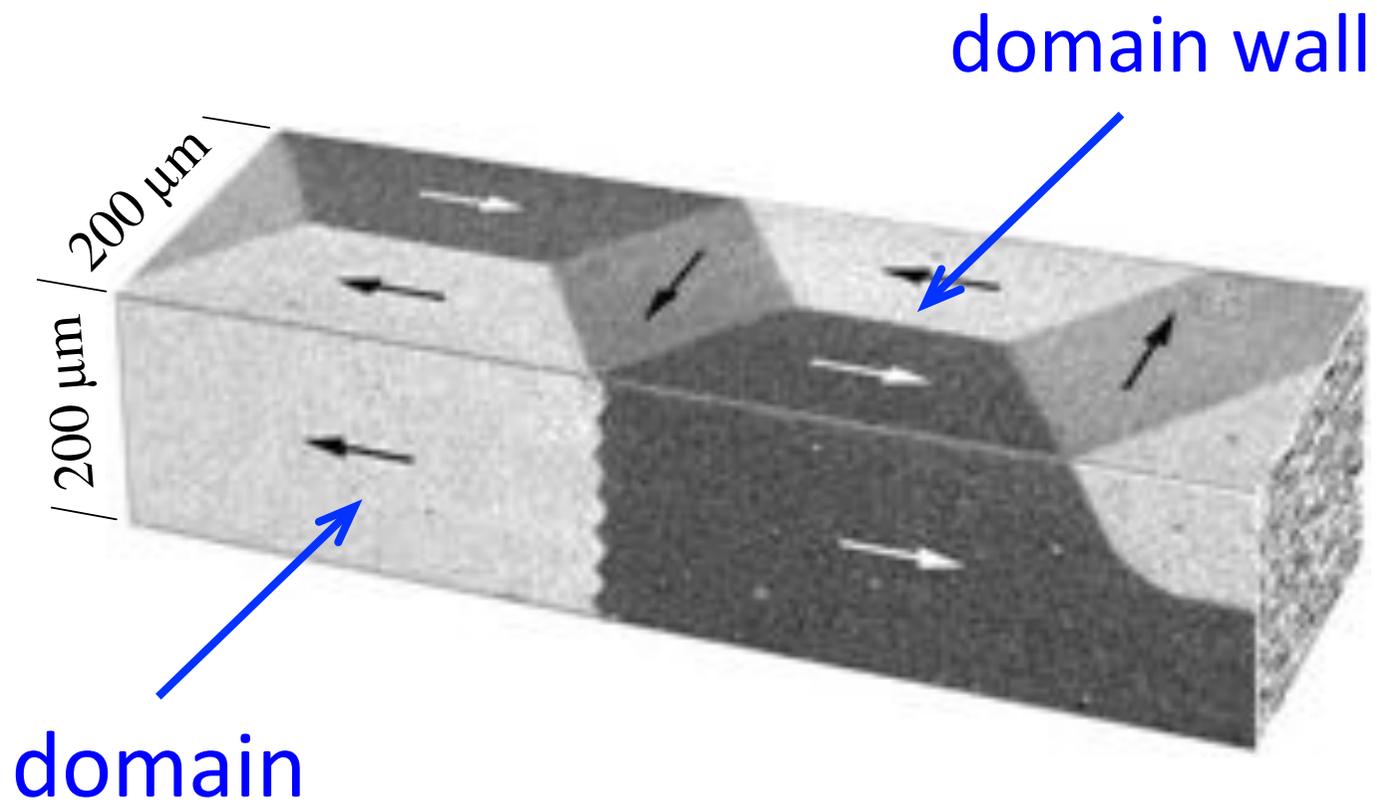
*Microscopic approach to current-driven domain wall dynamics*

G. Tatara, H. Kohno, J. Shibata

Physics Reports 468, 213 (2008)

# Outline

- 1. History & motivation**
- 2. Observation techniques**
- 3. The origin of domains**
- 4. Domain walls**
- 5. Domain wall motion**



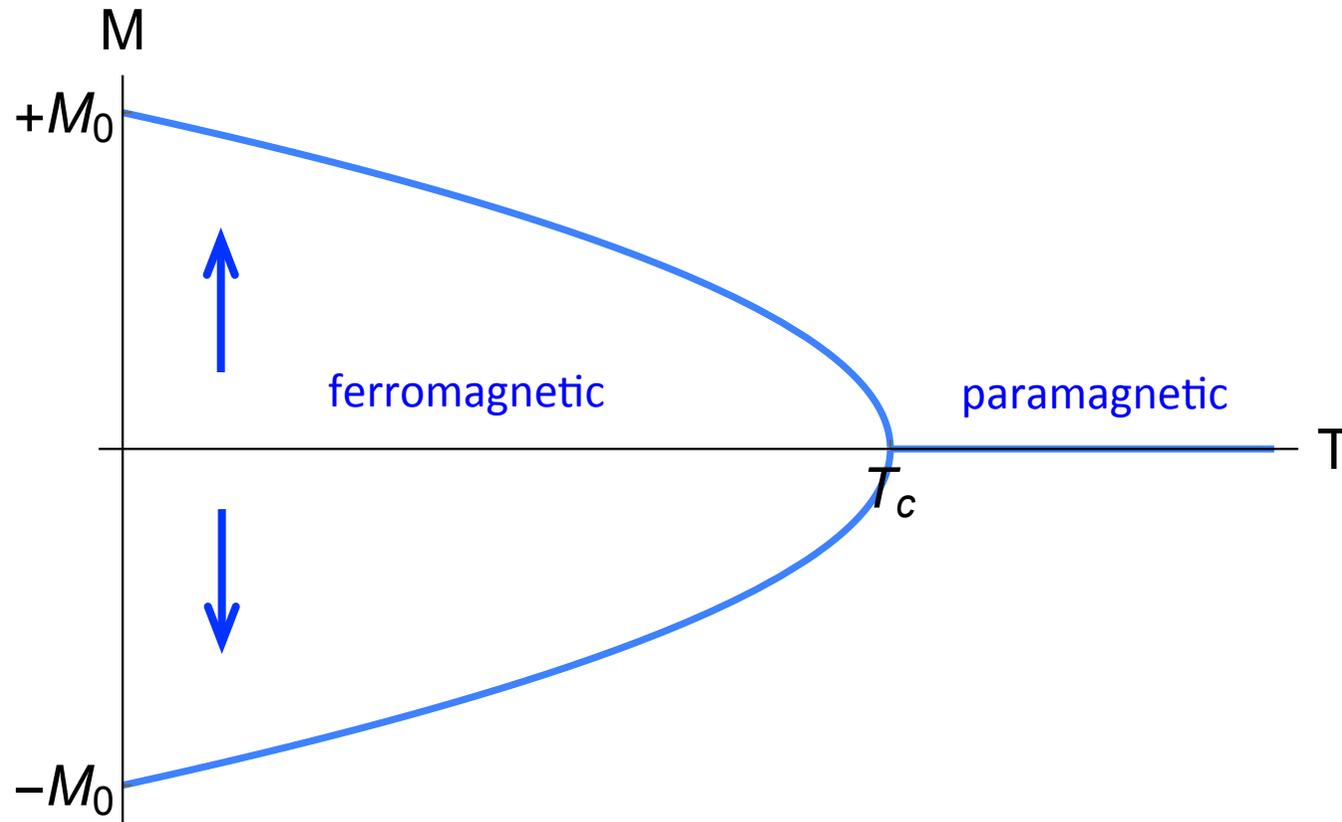
The concept of **domain**:



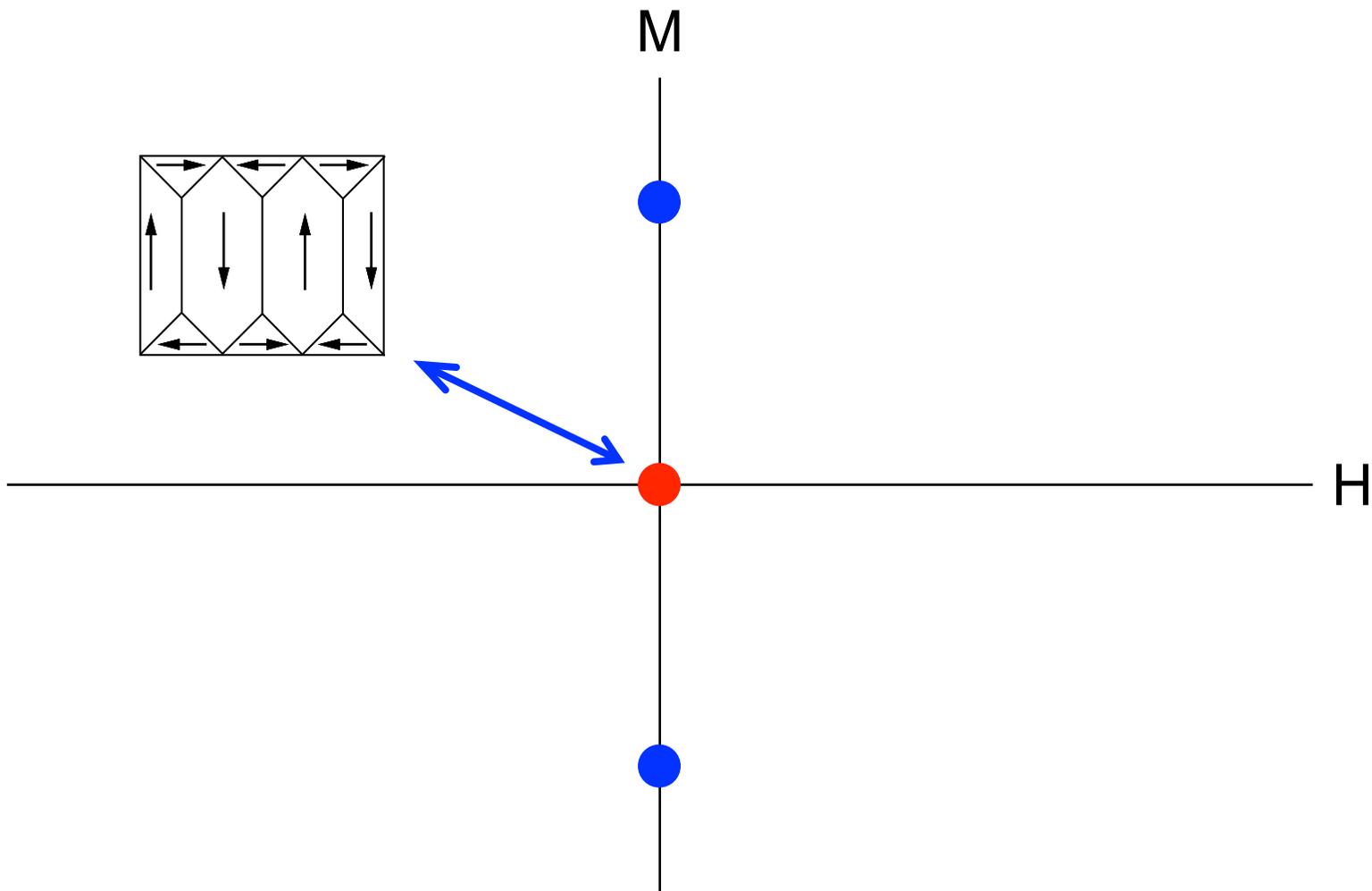
Postulated by Pierre Weiss in 1907 to explain why ferromagnetic bodies can appear non-magnetic.

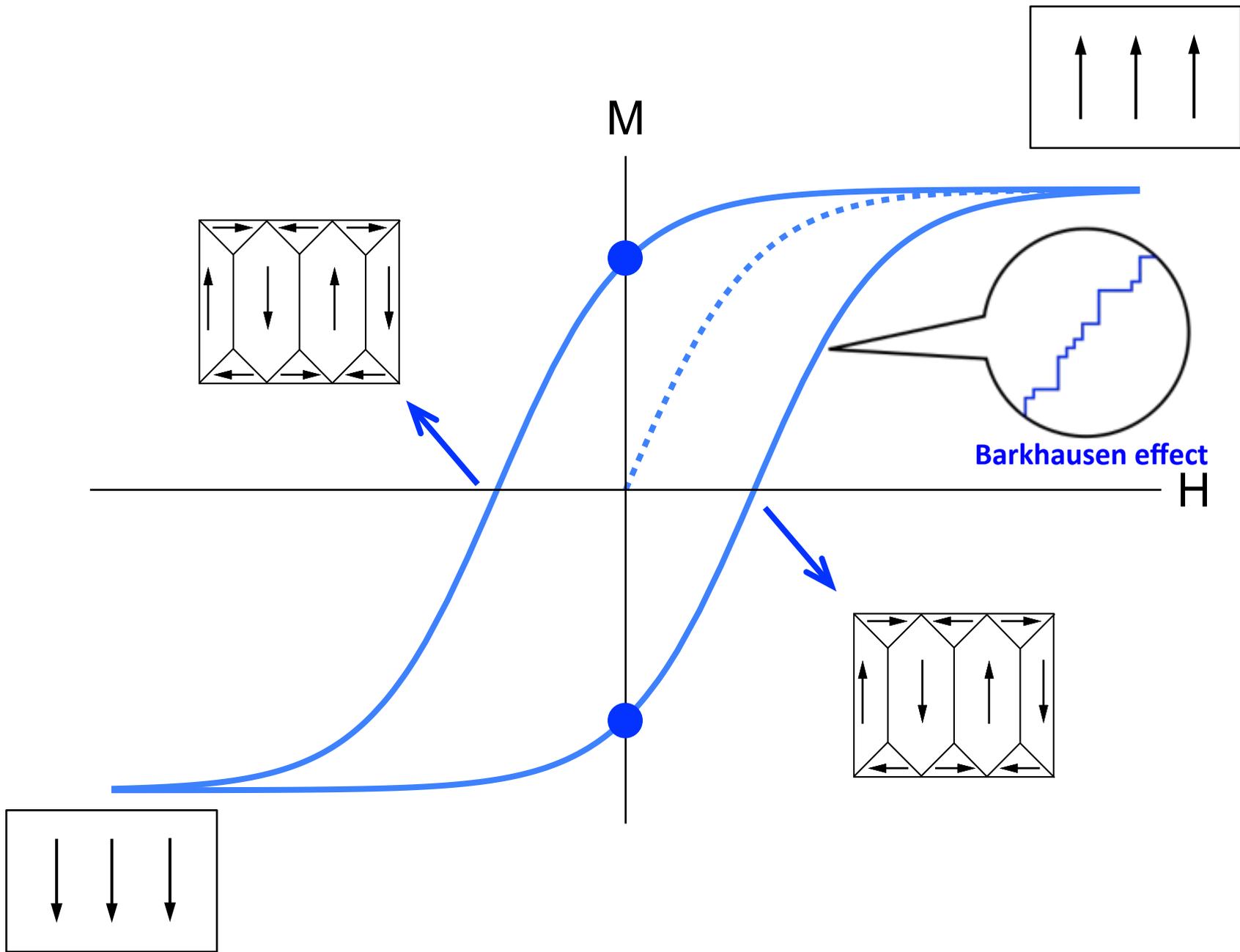
**110 anniversary!**

$$F = a(T - T_c)M^2 + bM^4$$

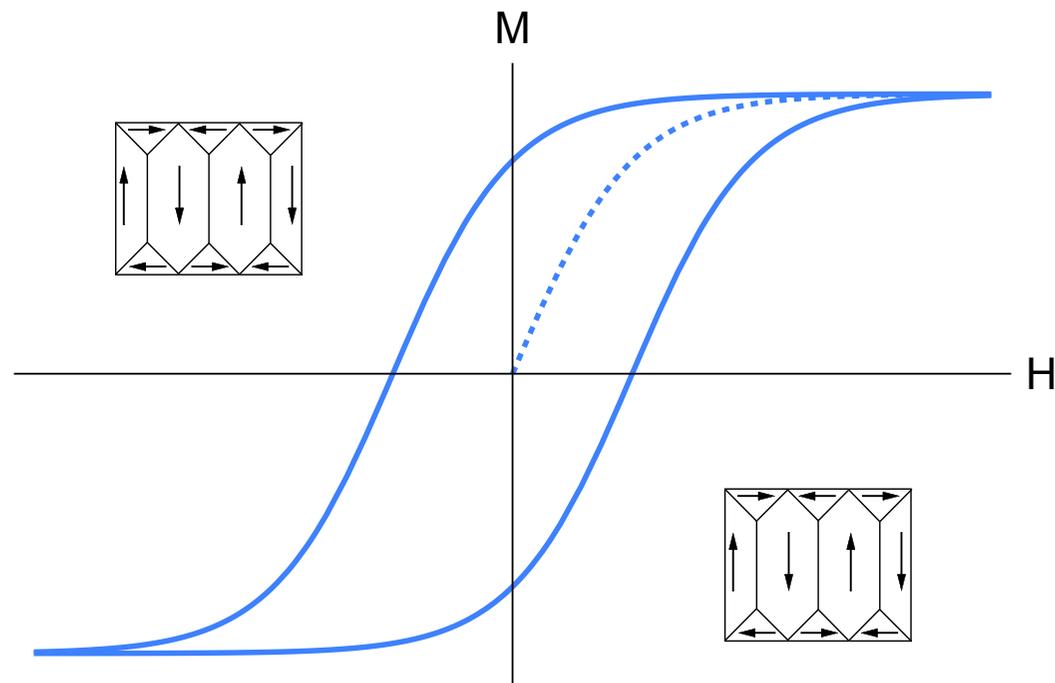


Two possible states below  $T_c$





The distinct response of ferromagnets is inherently related to domains (and domain walls)



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**2. Observation techniques**

3. The origin of domains

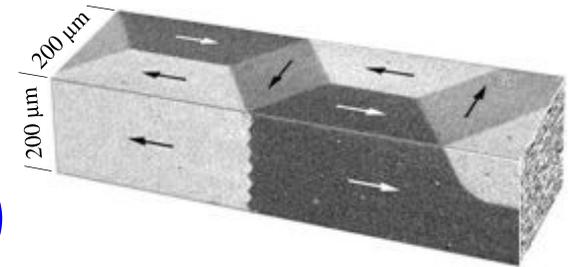
4. Domain walls

5. Domain wall motion

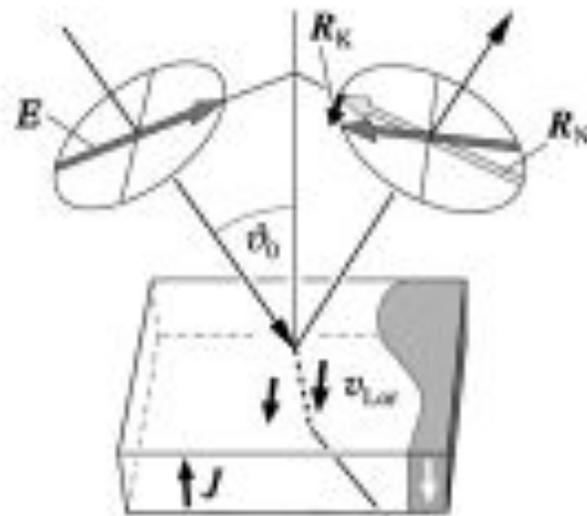
# Observation techniques

Magneto-optical Kerr effect (MOKE)

$$\mathbf{D} = \varepsilon(\mathbf{E} + iQ\mathbf{M} \times \mathbf{E})$$



weak (but detectable) dependence on the magnetization of the optical constants

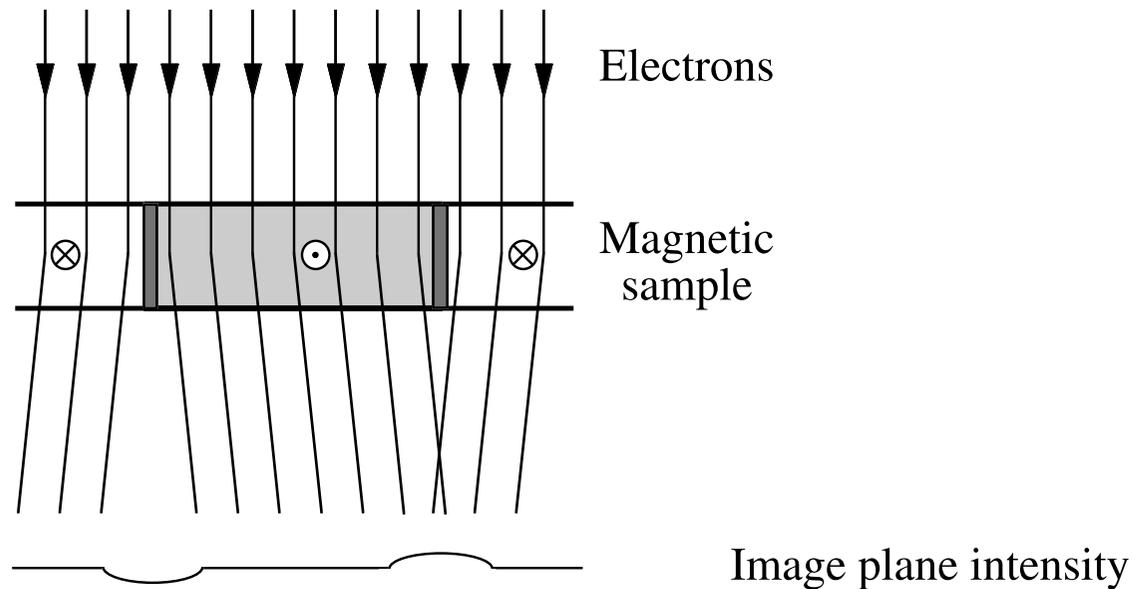


# Observation techniques

## Transmission Electron Microscopy (TEM)

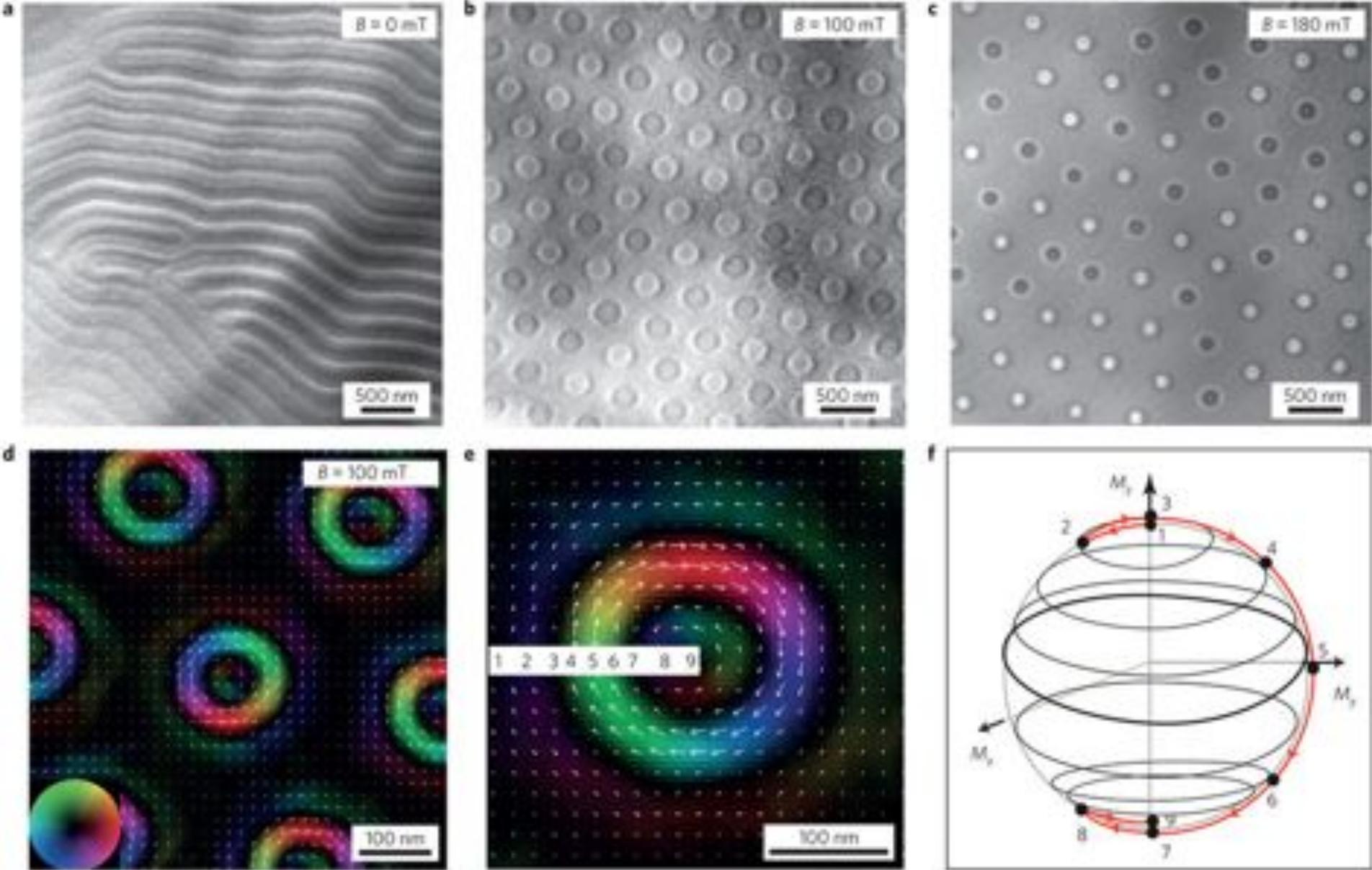
$$\mathbf{F}_{\text{Lorentz}} = q(\mathbf{v} \times \mathbf{B})$$

electrons are deflected by the Lorentz force



# Observation techniques

## Transmission Electron Microscopy (TEM)



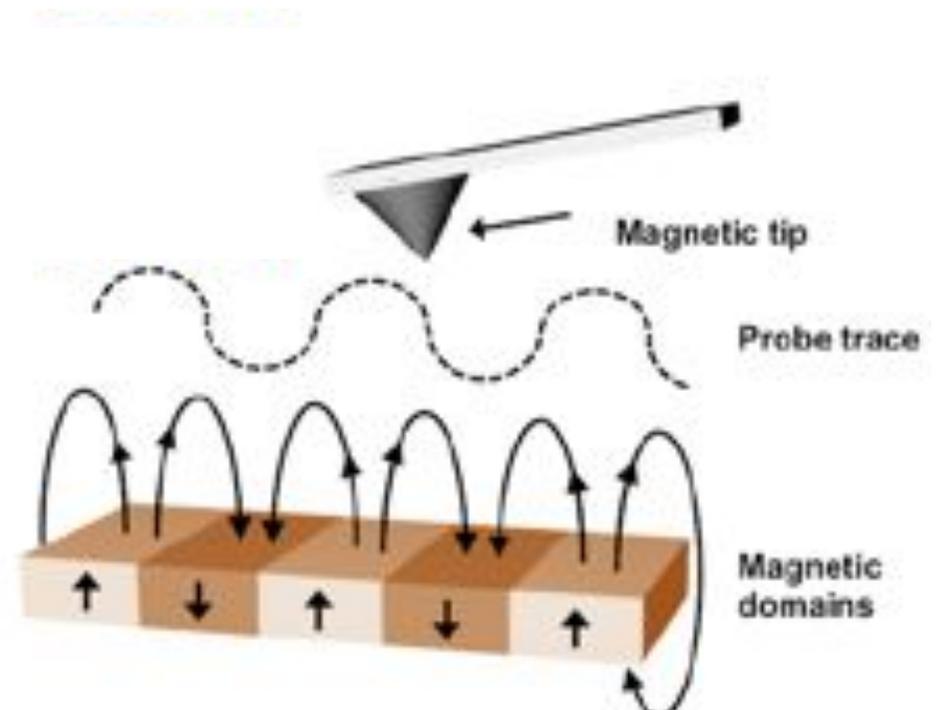
# Observation techniques

$$\overbrace{\nabla \cdot \mathbf{B} = 0} \\ \nabla \cdot \mathbf{H} = -\nabla \cdot \mathbf{M}$$

longitudinal variations of  $\mathbf{M}$  are a source of magnetic field (stray field)

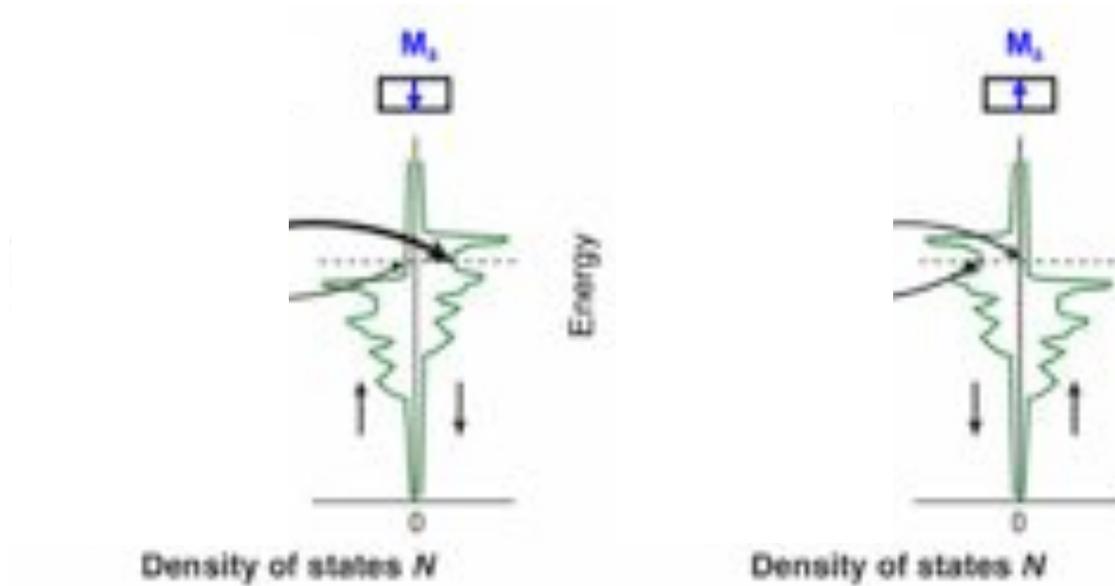
## Magnetic force microscopy (MFM)

$$\mathbf{F} = \mu_0 (\mathbf{m}_{\text{tip}} \cdot \nabla) \mathbf{H}_{\text{stray}}$$

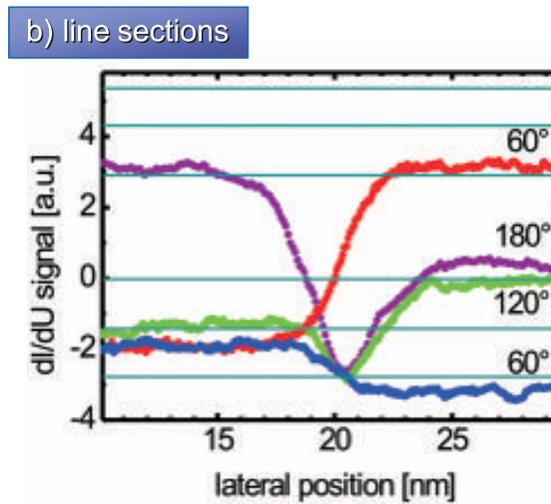
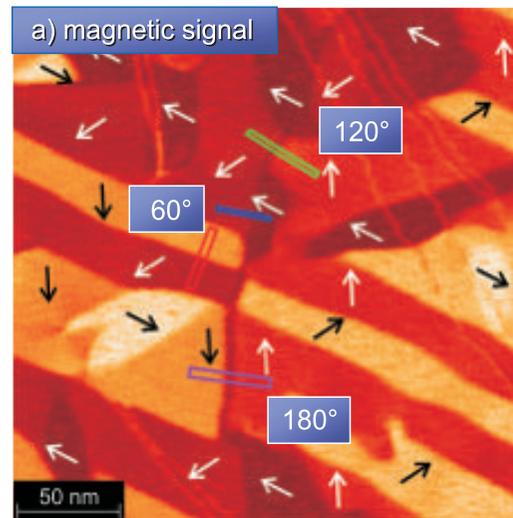


# Observation techniques

## Spin-polarized scanning-tunneling microscopy (SP-STM)

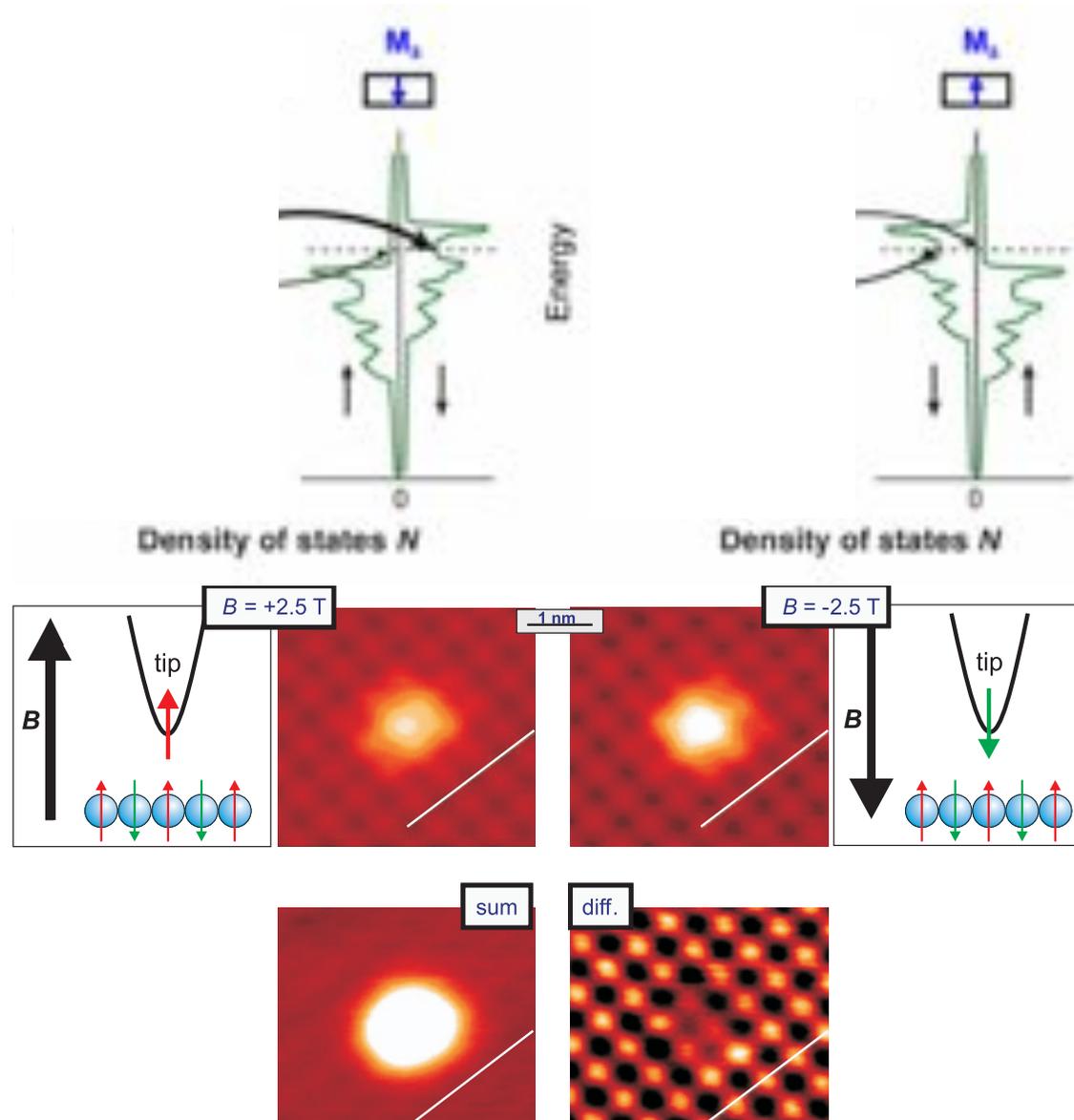


90ML Dy/W(110)

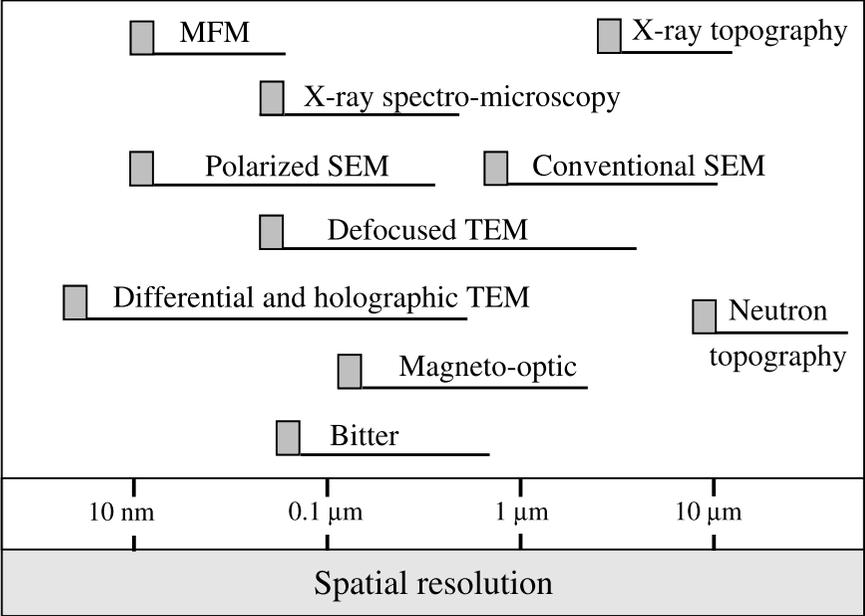


# Observation techniques

## Spin-polarized scanning-tunneling microscopy (SP-STM)



# Observation techniques



Method of domain observation	Sensitivity to small variations in magnetization	Evaluation of the magnetization vector	Allowed magnetic field range	Sample preparation quality requirements	Necessary capital investment
<i>Bitter</i>	very good	indirect	100 A/cm	moderate-low	low
<i>Magneto-optic</i>	fair	direct	any	high	moderate
<i>Digital MO</i>	good	quantitative	any	moderate	high
<i>Defocused TEM</i>	very good	indirect	3000 A/cm	high	high
<i>Differential TEM</i>	good	quantitative	1000 A/cm	high	very high
<i>Holograph. TEM</i>	good	quantitative	100 A/cm	very high	very high
<i>Secondary SEM</i>	poor	indirect	100 A/cm	low	high
<i>Backscatt. SEM</i>	poor	rather direct	300 A/cm	moderate-low	high
<i>Pol. SEM</i>	good	quantitative	100 A/cm	very high	very high
<i>X-Ray topography</i>	poor	indirect	any	moderate	extremely high
<i>Neutron</i>	poor	indirect	any	low	extremely high
<i>MFM</i>	good	indirect	3000 A/cm	low	moderate

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- 3. The origin of domains**
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5. Domain wall motion

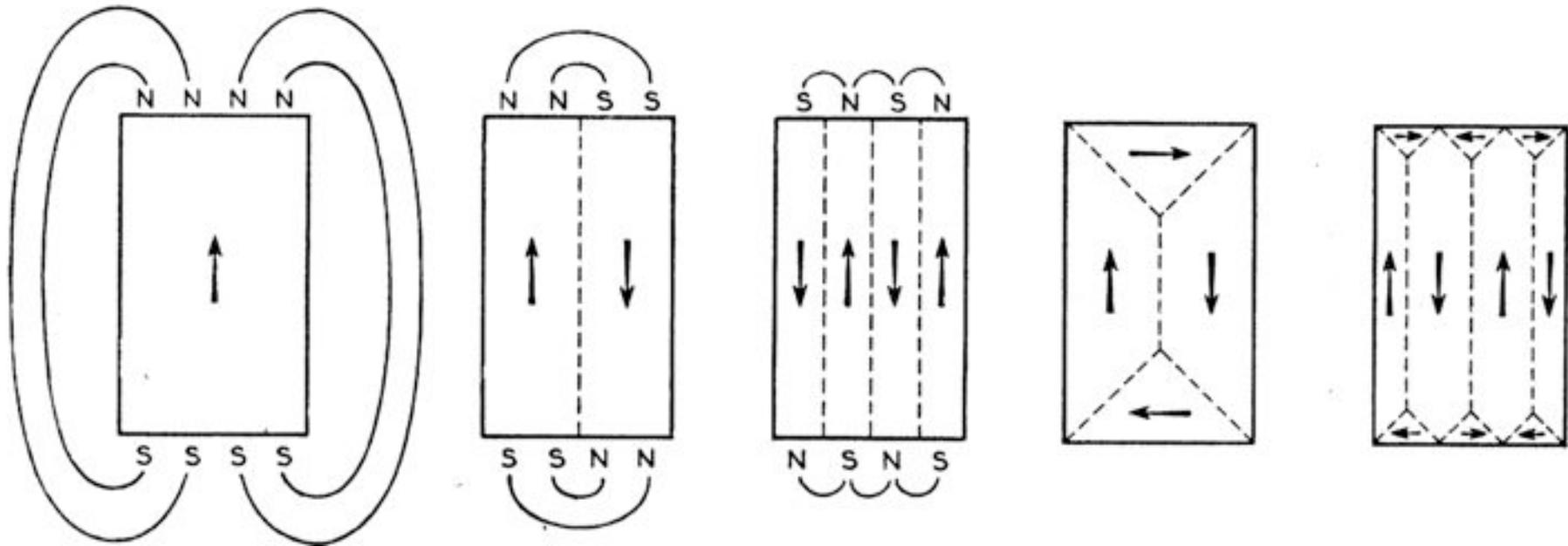
# The origin of domains



*On the theory of the dispersion of magnetic permeability in ferromagnetic bodies*  
Landau & Lifshitz, Phys. Z. Sowjet. 8, 153 (1935)

# The origin of domains

$$\nabla \cdot \mathbf{H} = -\nabla \cdot \mathbf{M} \quad \longrightarrow \quad E_{\text{magnetostatic}} = \frac{\mu_0}{2} \int H_d^2(\mathbf{M}) dV$$



domains form to minimize the magnetic energy

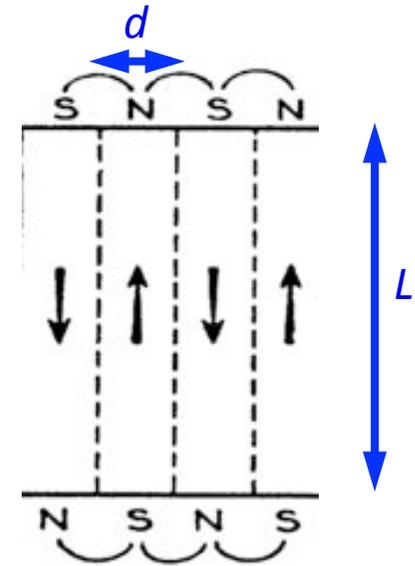
$$\nabla \cdot \mathbf{M} = 0$$

$$\hat{\mathbf{n}} \cdot \mathbf{M}|_{\text{surface}} = 0$$

# Size of domains ( $d$ )

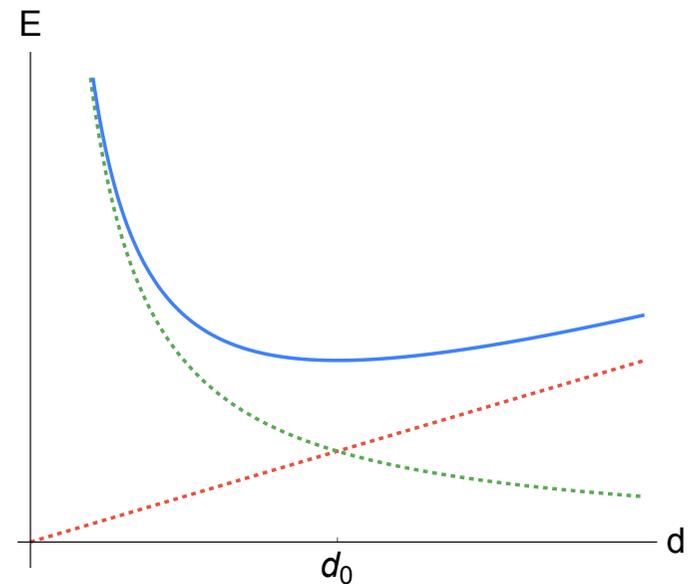
$$E(d, L) \implies \left. \frac{\partial E(d, L)}{\partial d} \right|_{d_0} = 0$$

**strategy:** compute the total magnetic energy of the system and determine  $d$  from the principle of minimum energy



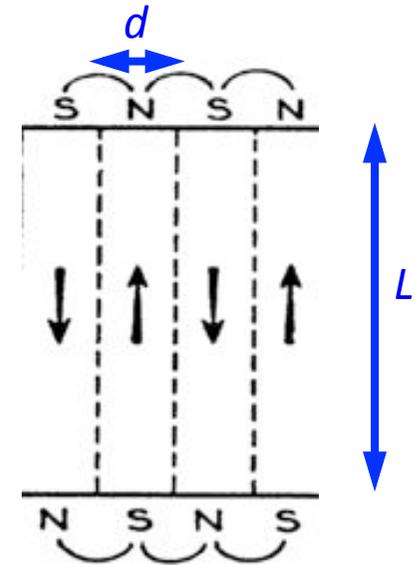
$$E(d, L) = \underbrace{1.7M^2d}_{\text{magnetostatic}} + \underbrace{\varepsilon_{\text{dw}}(L/d)}_{\text{domain wall}}$$

$$d_0 \sim L^{1/2} \quad \text{Kittel's law}$$

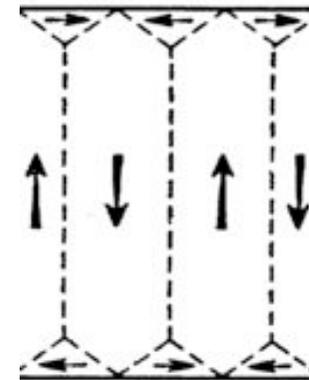


## Size of domains ( $d$ )

$$E_{\text{stripe}}(d, L) = \underbrace{1.7M^2d}_{\text{magnetostatic}} + \underbrace{\varepsilon_{\text{dw}}(L/d)}_{\text{domain wall}}$$



$$E_{\text{flux closure}}(d, L) = \underbrace{\frac{K}{2}M^2d}_{\text{anisotropy}} + \underbrace{\varepsilon_{\text{dw}}(L/d)}_{\text{domain wall}}$$



$$d_0 \sim L^{1/2} \quad \text{Kittel's law}$$

To know the actual size of the domains we need to determine the **energy of the domain walls**

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# Domain walls

## Micromagnetic formalism

$$\overbrace{\mathbf{S}_i = \mathbf{S}(\mathbf{r}_i)}^{\text{discrete}} \longrightarrow \overbrace{\mathbf{S}(\mathbf{r}) = \mathbf{M}(\mathbf{r})/M_s}^{\text{continuous}}$$

$$\mathbf{S}(\mathbf{r}_i) \cdot \mathbf{S}(\mathbf{r}_i + \Delta\mathbf{r}_i) \longrightarrow 1 - \frac{1}{2}(\Delta\mathbf{r}_i \cdot \nabla\mathbf{S}|_{\mathbf{r}=\mathbf{r}_i})^2$$

$$H_{\text{ex}} = - \sum_{ij} J_{ij} \mathbf{S}_i \cdot \mathbf{S}_j \longrightarrow \int A \left[ \nabla \left( \frac{\mathbf{M}(\mathbf{r})}{M_s} \right) \right]^2 dv \quad (A \sim J/a)$$

# Domain walls

Uniaxial ferromagnet ( $\mathbf{m} = \mathbf{M}/M_s$ )

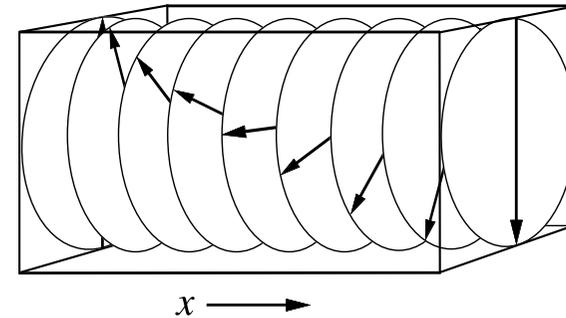
$$E = \int \left\{ \underbrace{A(\nabla \mathbf{m})^2}_{\text{exchange}} + \underbrace{K(m_x^2 + m_y^2)}_{\text{anisotropy}} - \underbrace{\frac{\mu_0}{2} \mathbf{M} \cdot \mathbf{H}_d(\mathbf{M})}_{\text{stray field}} \right\} dv$$

$$\mathbf{m} = (0, \sin \theta(x), \cos \theta(x))$$

$$\varepsilon_{dw} = \int_{-\infty}^{\infty} (A\theta'^2 + K \sin^2 \theta) dx$$

$$A\theta'' - K \sin \theta \cos \theta = 0$$

**Bloch wall** ( $\nabla \cdot \mathbf{M} = 0$ )



$$\frac{d}{dx} \left[ A \left( \frac{d\theta}{dx} \right)^2 + K \cos^2 \theta \right] = 0$$

$$\ddot{\theta} - \frac{g}{l} \sin \theta \cos \theta = 0 \quad \frac{A}{K} \left( \frac{d\theta}{dx} \right)^2 + \cos^2 \theta = 1$$

$$\pm \sqrt{\frac{A}{K} \frac{d\theta}{dx}} = \sqrt{1 - \cos^2 \theta} = \sin \theta$$

$$\frac{d\theta}{\sin \theta} = \pm \sqrt{\frac{K}{A}} dx \quad \rightarrow \quad \ln \tan \frac{\theta}{2} = \sqrt{\frac{K}{A}} (x - X)$$

# Domain walls

Uniaxial ferromagnet ( $\mathbf{m} = \mathbf{M}/M_s$ )

$$E = \int \left\{ \underbrace{A(\nabla \mathbf{m})^2}_{\text{exchange}} + \underbrace{K(m_x^2 + m_y^2)}_{\text{anisotropy}} - \underbrace{\frac{\mu_0}{2} \mathbf{M} \cdot \mathbf{H}_d(\mathbf{M})}_{\text{stray field}} \right\} dv$$

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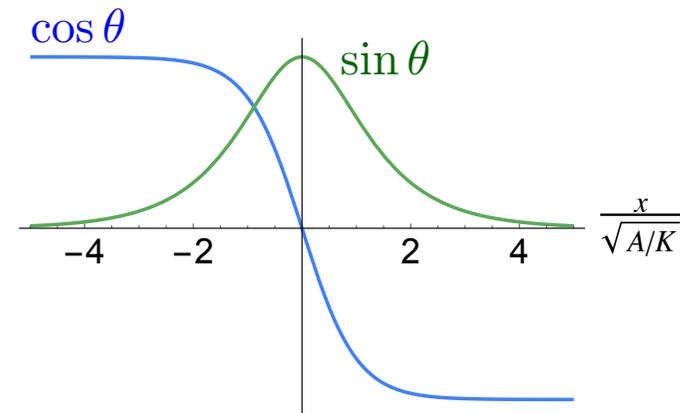
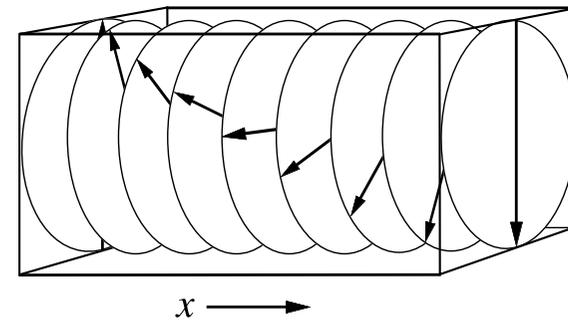
$$A\theta'' - K \sin \theta \cos \theta = 0$$

$$\theta(x) = 2 \arctan[\exp(x/w)]$$

$$w = \sqrt{A/K}$$

$$\varepsilon_{dw} = 4\sqrt{AK}$$

**Bloch wall** ( $\nabla \cdot \mathbf{M} = 0$ )



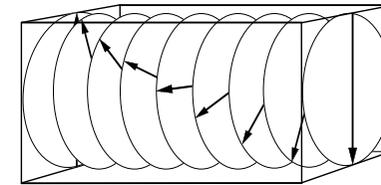
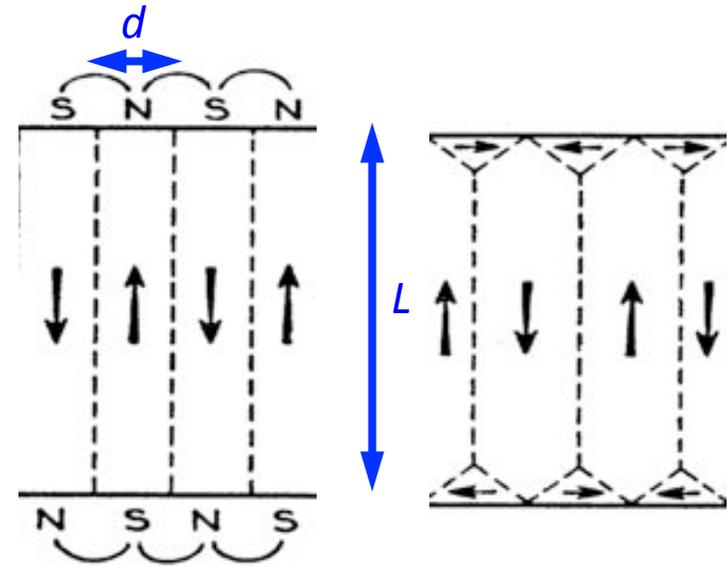
# Domains & domain walls

Fe, Ni

$$w \sim 10 \text{ nm}$$

$$d_0(L = 1 \text{ cm}) \sim 10 \text{ } \mu\text{m}$$

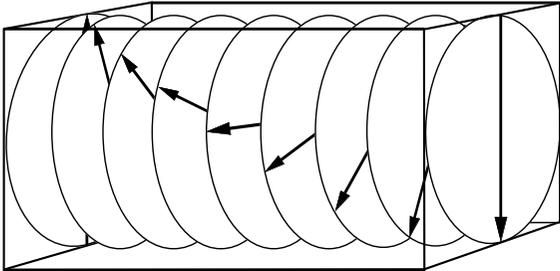
$$E_{dw}^{d=d_0} \sim E_{\text{magnetostatic}}^{d=d_0} \ll E_{\text{magnetostatic}}^{d \rightarrow \infty}$$



$$d_0 \sim (wL)^{1/2} \quad \longrightarrow \quad \text{single-domain state if } L \lesssim w$$

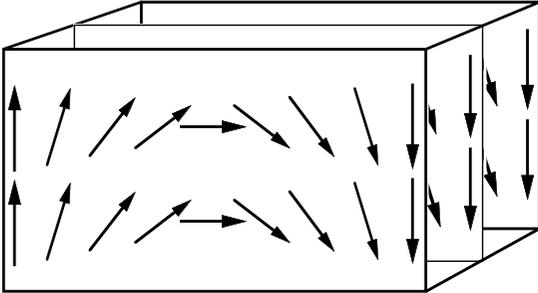
# Domain walls in thin films

Bloch wall



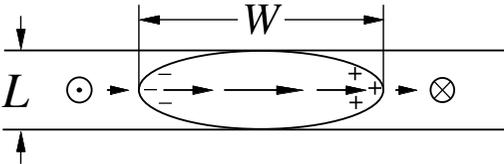
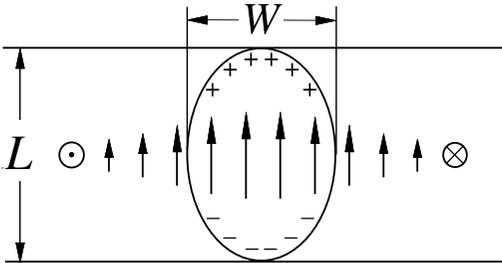
$$\nabla \cdot \mathbf{M} = 0$$

Neel wall



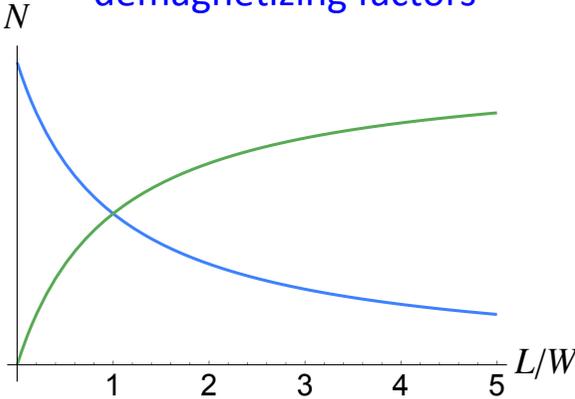
$$\nabla \cdot \mathbf{M} \neq 0$$

top view



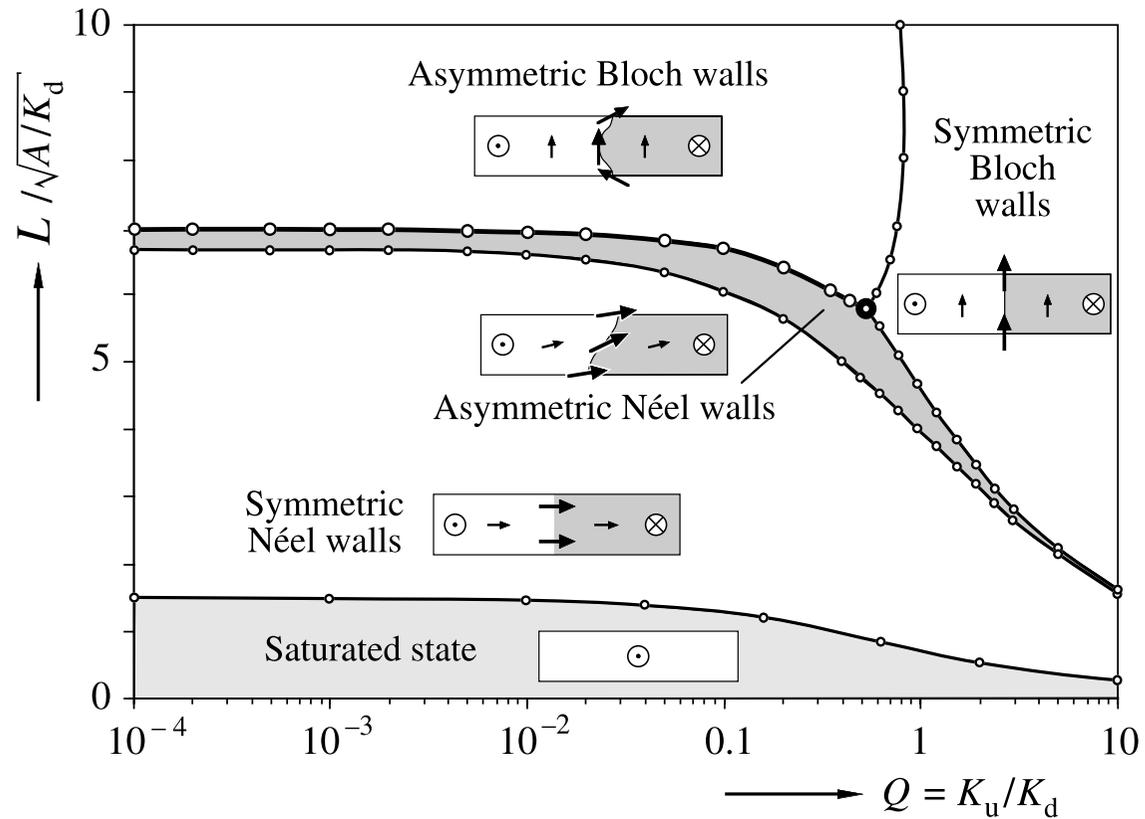
$$N_{\text{Bloch}} = \frac{W}{W + L}$$

demagnetizing factors



$$N_{\text{Néel}} = \frac{L}{W + L}$$

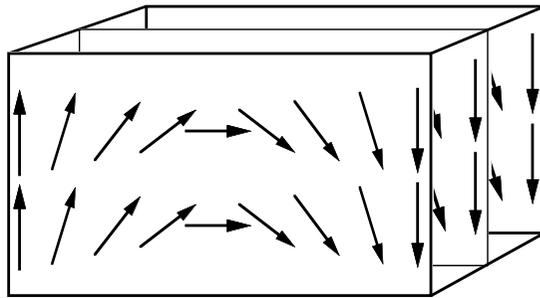
# Domain walls in thin films



- Multi-dimensional description due to the stray fields
- Additional length scales
- Analytical -> numerical calculations & ansatzs + variational procedures

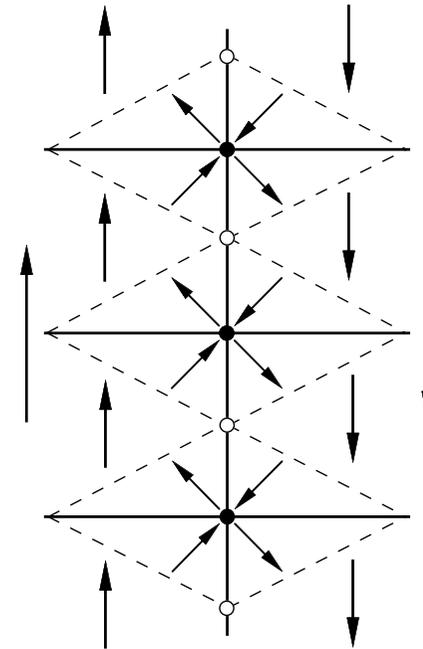
# Domain walls in thin films

Neel wall

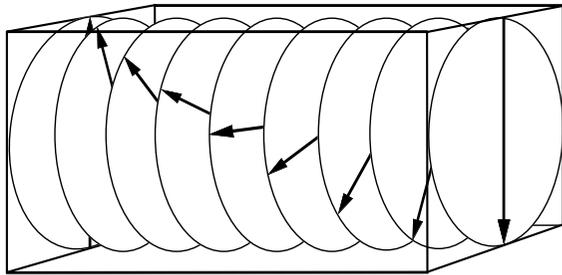


$$\nabla \cdot \mathbf{M} \neq 0$$

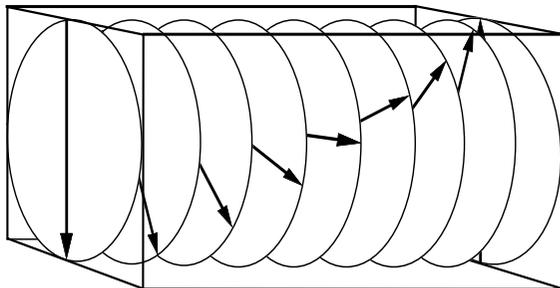
cross-tie wall



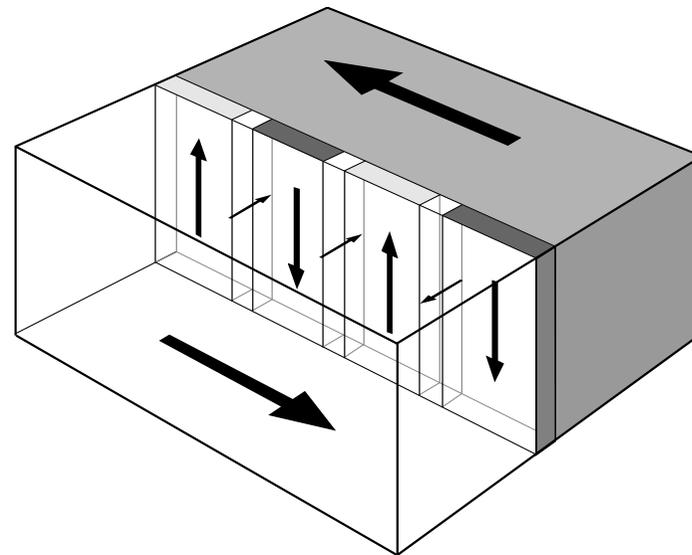
## Bloch walls



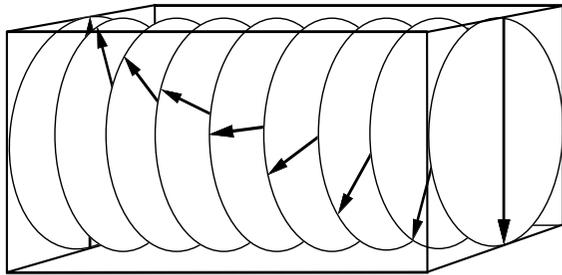
two (equivalent)  
rotation senses



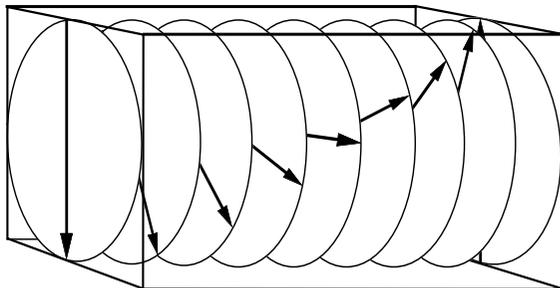
## Bloch lines & Bloch points



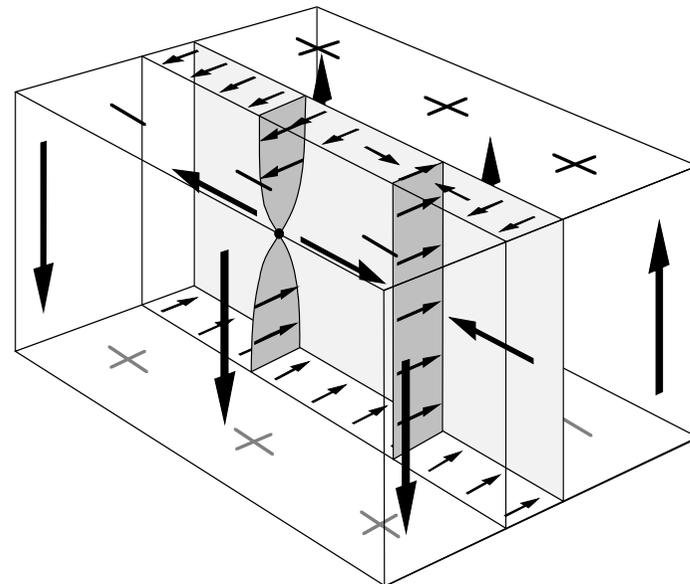
## Bloch walls



two (equivalent)  
rotation senses



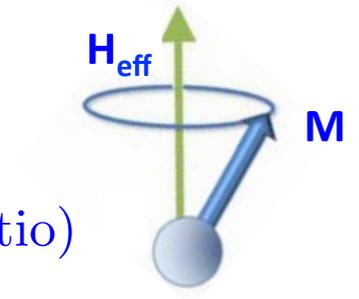
## Bloch lines & Bloch points



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# Domain wall motion



$$\dot{\mathbf{M}} = -\gamma \underbrace{\mathbf{M} \times \mathbf{H}_{\text{eff}}}_{\text{torque}} \quad \gamma = \frac{\mu_0 g e}{2m_e} \text{ (gyromagnetic ratio)}$$

$$E = \int [A(\nabla \mathbf{M})^2 - K M_z^2 - \mathbf{M} \cdot \mathbf{H}_{\text{tot}}] dv \quad \mathbf{H}_{\text{tot}} = \mathbf{H}_{\text{ext}} + \mathbf{H}_{\text{d}}$$

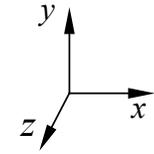
$$\delta E = \int \underbrace{[(A \nabla^2 \mathbf{M} + K M_z \hat{\mathbf{e}}_z + \mathbf{H}_{\text{tot}})]}_{\mathbf{H}_{\text{eff}}} \cdot \delta \mathbf{M} dv$$

Landau-Lifshitz-Gilbert equation:

$$\dot{\mathbf{M}} = -\gamma \underbrace{\mathbf{M} \times \mathbf{H}_{\text{eff}}}_{\text{torque}} - \underbrace{\alpha \mathbf{M} \times \dot{\mathbf{M}}}_{\text{damping}}$$

# Domain wall motion

$$\dot{\mathbf{m}} = -\gamma \mathbf{m} \times \mathbf{H}_{\text{eff}} - \alpha \mathbf{m} \times \dot{\mathbf{m}}$$



$$E = \int [A(\nabla \mathbf{m})^2 - Km_z^2 + \underbrace{K_d m_y^2}_{K_d = \frac{\mu_0}{2} M_s^2} - \mathbf{M} \cdot \mathbf{H}_{\text{ext}}] d^3x$$



$m_y = 0 \rightarrow$  stray-field-free wall

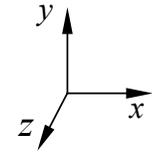
$$\mathbf{m} = -\gamma(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$$

$$\dot{\theta} - \alpha \dot{\phi} \sin \theta = \frac{2\gamma}{M_s} \left[ -\frac{A}{\sin \theta} \nabla \cdot (\sin^2 \theta \nabla \phi) + \frac{K_d}{2} \sin \theta \sin 2\phi \right]$$

$$\dot{\phi} \sin \theta + \alpha \dot{\theta} = \frac{2\gamma}{M_s} \left\{ A \left[ \nabla^2 \theta - \frac{1}{2} \sin 2\theta (\nabla \phi)^2 \right] - \frac{K + K_d \sin^2 \phi}{2} \sin 2\theta \right\} + \gamma H \sin \theta$$

# Domain wall motion

$$\dot{\mathbf{m}} = -\gamma \mathbf{m} \times \mathbf{H}_{\text{eff}} - \alpha \mathbf{m} \times \dot{\mathbf{m}}$$



$$E = \int [A(\nabla \mathbf{m})^2 - Km_z^2 + \underbrace{K_d m_y^2}_{K_d = \frac{\mu_0}{2} M_s^2} - \mathbf{M} \cdot \mathbf{H}_{\text{ext}}] d^3x$$



$m_y = 0 \rightarrow$  stray-field-free wall

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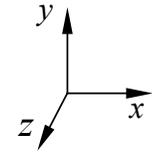
$$\dot{\theta} - \alpha \dot{\phi} \sin \theta = \frac{2\gamma}{M_s} \left[ -\frac{A}{\sin \theta} \nabla \cdot (\sin^2 \theta \nabla \phi) + \frac{K_d}{2} \sin \theta \sin 2\phi \right]$$

$$\dot{\phi} \sin \theta + \alpha \dot{\theta} = \frac{2\gamma}{M_s} \left\{ A \left[ \nabla^2 \theta - \frac{1}{2} \sin 2\theta (\nabla \phi)^2 \right] - \frac{K + K_d \sin^2 \phi}{2} \sin 2\theta \right\} + \gamma H \sin \theta$$

$\theta = \theta(x, t)$  and  $\phi = \text{const.}$

# Domain wall motion

$$\dot{\mathbf{m}} = -\gamma \mathbf{m} \times \mathbf{H}_{\text{eff}} - \alpha \mathbf{m} \times \dot{\mathbf{m}}$$



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$m_y = 0 \rightarrow$  stray-field-free wall

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$$\dot{\theta} - \alpha \dot{\phi} \sin \theta = \frac{2\gamma}{M_s} \left[ -\frac{A}{\sin \theta} \nabla \cdot (\sin^2 \theta \nabla \phi) + \frac{K_d}{2} \sin \theta \sin 2\phi \right]$$

$$\dot{\phi} \sin \theta + \alpha \dot{\theta} = \frac{2\gamma}{M_s} \left\{ A \left[ \nabla^2 \theta - \frac{1}{2} \sin 2\theta (\nabla \phi)^2 \right] - \frac{K + K_d \sin^2 \phi}{2} \sin 2\theta \right\} + \gamma H \sin \theta$$

$\theta = \theta(x, t)$  and  $\phi = \text{const.}$

$$\underbrace{\gamma \left( \frac{\alpha K_d}{M_s} \sin 2\phi - H \right) \sin \theta}_{=0} = \underbrace{\frac{2\gamma}{M_s} \left( A \partial_x^2 \theta - \frac{K + K_d \sin^2 \phi}{2} \sin 2\theta \right)}_{=0}$$

## Walker's solution

$$\theta(x, t) = 2 \arctan \{ \exp[\pm(x \pm vt)/w_*] \}, \quad \sin 2\phi = H/H_c$$

$$w_* = \sqrt{A/(K + K_d \sin^2 \phi)}, \quad H_c = \frac{\alpha}{2} M_s, \quad v = \frac{\gamma}{\alpha} w_* H$$

$$\mathbf{m} = \left( \frac{\cos \phi}{\cosh[(x - vt)/w_*]}, \frac{\sin \phi}{\cosh[(x - vt)/w_*]}, \pm \tanh[(x - vt)/w_*] \right)$$

# Domain wall motion

The wall moves at a constant speed ( $\sim H$  for low fields).

If the speed increases the angle increases  $\rightarrow$  stray field & wall narrowing.

There is a maximum velocity.

There is a critical field above which this solution is not valid.

## Walker's solution

$$\theta(x, t) = 2 \arctan\{\exp[\pm(x \pm vt)/w_*]\}, \quad \sin 2\phi = H/H_c$$

$$w_* = \sqrt{A/(K + K_d \sin^2 \phi)}, \quad H_c = \frac{\alpha}{2} M_s, \quad v = \frac{\gamma}{\alpha} w_* H$$

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# Domain wall motion

## Longitudinal susceptibility



$$v = \frac{\gamma}{\alpha} w_* H_\omega e^{i\omega t} \rightarrow \Delta x = \int_0^t v dt = \frac{\gamma}{\alpha} \frac{w_*}{i\omega} H_\omega e^{i\omega t} \rightarrow \Delta M_\omega = \frac{\gamma}{\alpha} \frac{w_*}{i\omega} H_\omega e^{i\omega t} \frac{L_z}{d} \times \text{Surface}$$

$$\chi_l(\omega) \equiv \frac{1}{V} \frac{\Delta M_\omega}{H_\omega e^{i\omega t}} = \frac{\gamma w_*}{i\omega \alpha d} \quad (\text{relaxation behavior with no resonance})$$

### Walker's solution

$$\theta(x, t) = 2 \arctan\{\exp[\pm(x \pm vt)/w_*]\}, \quad \sin 2\phi = H/H_c$$

$$w_* = \sqrt{A/(K + K_d \sin^2 \phi)}, \quad H_c = \frac{\alpha}{2} M_s, \quad v = \frac{\gamma}{\alpha} w_* H$$

$$\mathbf{m} = \left( \frac{\cos \phi}{\cosh[(x - vt)/w_*]}, \frac{\sin \phi}{\cosh[(x - vt)/w_*]}, \pm \tanh[(x - vt)/w_*] \right)$$

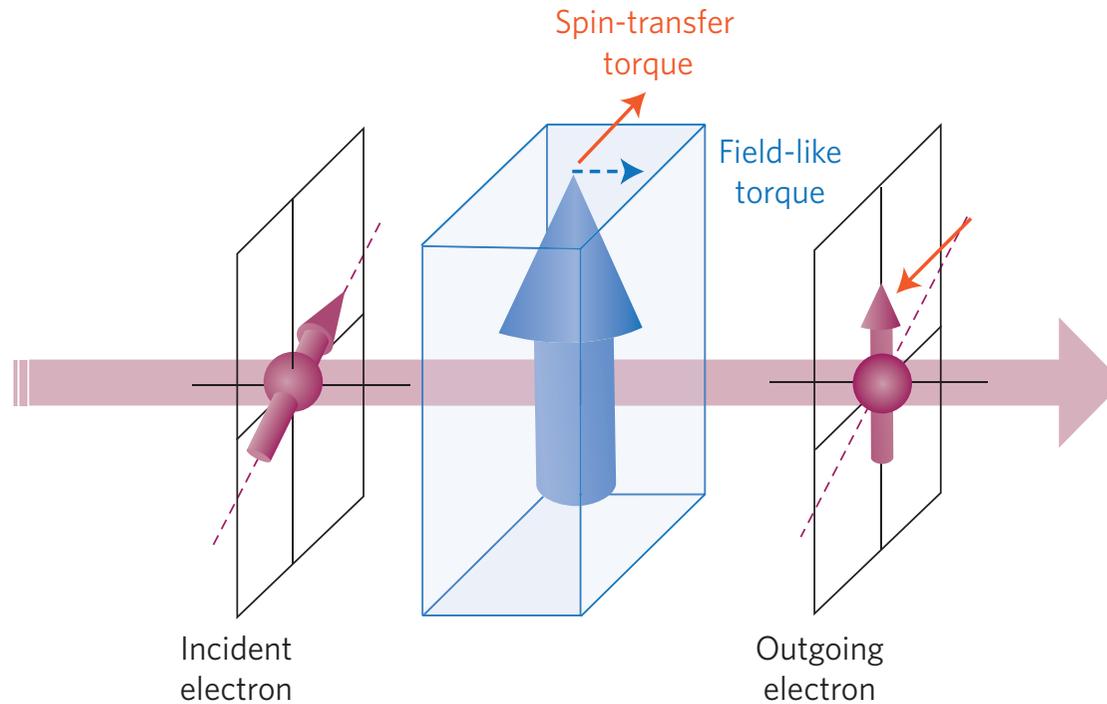
# Domain wall motion

Field- vs. current-induced motion

$$\mathbf{M} = -\frac{g\mu_B}{a^3}\mathbf{S} = -\frac{\hbar\gamma}{a^3}\mathbf{S}$$

$$\dot{\mathbf{S}} = -\gamma \mathbf{S} \times (\mathbf{H}_{\text{eff}} + \mathbf{H}_0) - \frac{\alpha}{S} \mathbf{S} \times \dot{\mathbf{S}} - \underbrace{\frac{a^3}{2eS} (\mathbf{j}_s \cdot \nabla) \mathbf{S}}_{\text{spin-transfer torque}} - \underbrace{\frac{a^3\beta}{2eS^2} [\mathbf{S} \times (\mathbf{j}_s \cdot \nabla) \mathbf{S}]}_{\text{field-like torque}}$$

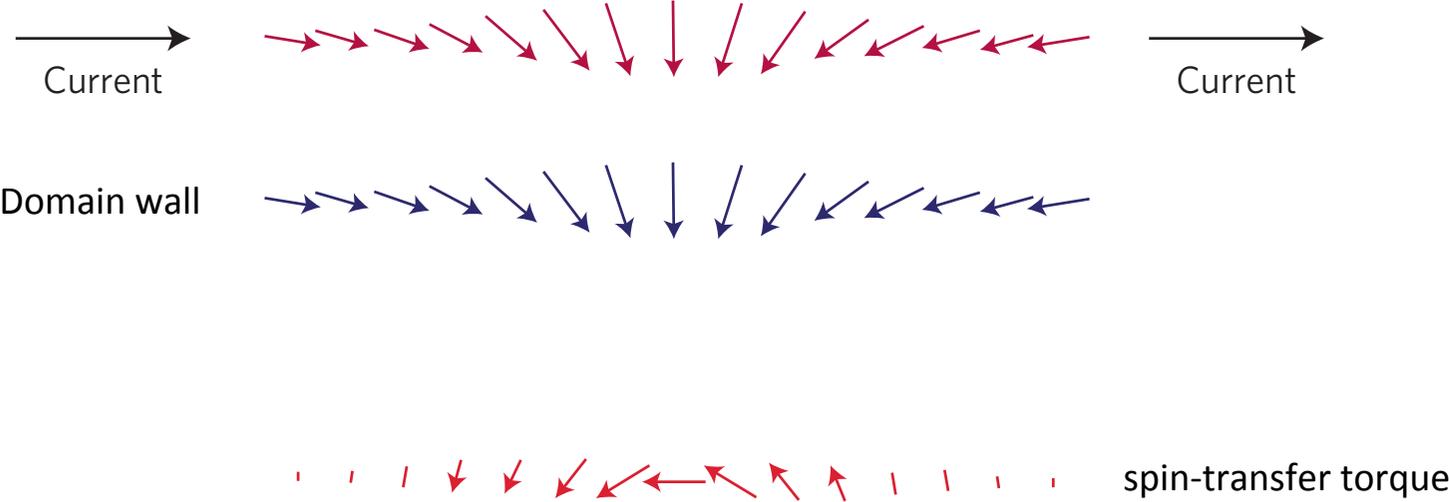
Exchange interaction between localized (3d) and itinerant spins  $H_{\text{int}} = -J_{s-d} \int d^3x \mathbf{S} \cdot \underbrace{(c^\dagger \boldsymbol{\sigma} c)}_{\mathbf{s}}$



# Domain wall motion

## Field- vs. current-induced motion

$$\dot{\mathbf{S}} = -\gamma \mathbf{S} \times (\mathbf{H}_{\text{eff}} + \mathbf{H}_0) - \frac{\alpha}{S} \mathbf{S} \times \dot{\mathbf{S}} - \underbrace{\frac{a^3}{2eS} (\mathbf{j}_s \cdot \nabla) \mathbf{S}}_{\text{spin-transfer torque}} - \underbrace{\frac{a^3 \beta}{2eS^2} [\mathbf{S} \times (\mathbf{j}_s \cdot \nabla) \mathbf{S}]}_{\text{field-like torque}}$$



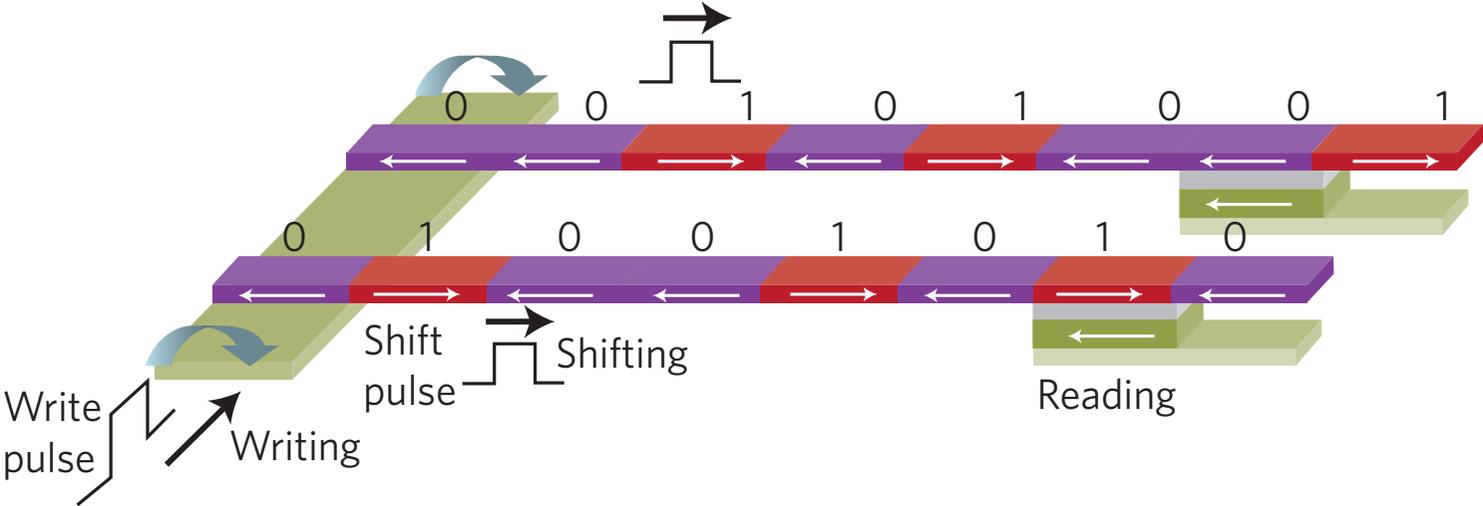
the angular momentum lost by the electrons is transferred to the domain wall

# Domain wall motion

## Field- vs. current-induced motion

$$\dot{\mathbf{S}} = -\gamma \mathbf{S} \times (\mathbf{H}_{\text{eff}} + \mathbf{H}_0) - \frac{\alpha}{S} \mathbf{S} \times \dot{\mathbf{S}} - \underbrace{\frac{a^3}{2eS} (\mathbf{j}_s \cdot \nabla) \mathbf{S}}_{\text{spin-transfer torque}} - \underbrace{\frac{a^3 \beta}{2eS^2} [\mathbf{S} \times (\mathbf{j}_s \cdot \nabla) \mathbf{S}]}_{\text{field-like torque}}$$

## racetrack-memory concept



# Domain wall motion

## Walker's solution

$$\theta = 2 \arctan \left[ \exp \left( \pm \frac{x \pm X(t)}{w_*} \right) \right]$$

$$\phi_0 = \text{constant}$$

$X(t)$  can be understood as the position of the wall

**What is the conjugate momentum?**

## Landau-Lifshitz-Gilbert equation $\leftrightarrow$ Euler-Lagrange equations

$$\frac{d}{dt} \frac{\partial L_S}{\partial \dot{q}} + \nabla \cdot \frac{\partial L_S}{\partial \nabla q} - \frac{\partial L_S}{\partial q} = - \frac{\partial W_S}{\partial q} \quad q = (\theta, \phi)$$

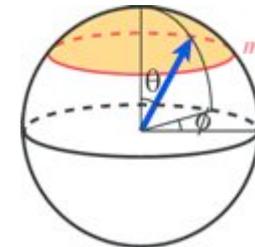
## Spin Lagrangian

$$L_S = L_B - H_S \quad (\mathbf{M} = -\gamma \frac{\hbar S}{a^3} \mathbf{n})$$

$$L_B = \int \frac{d^3x}{a^3} \hbar S \dot{\phi} (\cos \theta - 1)$$

$L_B$  is a spin Berry phase

$$H_S = \frac{S^2}{2} \int \frac{d^3x}{a^3} [J(\nabla \mathbf{n})^2 - K n_z^2 + K_{\perp} n_y^2 + \frac{2\gamma \hbar}{S} \mathbf{n} \cdot \mathbf{H}]$$



## Dissipation function

$$W_S = \frac{\alpha \hbar S}{2} \int \frac{d^3x}{a^3} \dot{\mathbf{n}} = \frac{\alpha \hbar S}{2} \int \frac{d^3x}{a^3} (\dot{\theta}^2 + \dot{\phi}^2 \sin \theta)$$

# Domain wall motion

## Walker's solution

$$\theta = 2 \arctan \left[ \exp \left( \pm \frac{x \pm X(t)}{w_*} \right) \right]$$

$$\phi_0 = \text{constant}$$

$X(t)$  can be understood as the position of the wall

**What is the conjugate momentum?**

## Spin Lagrangian & dissipation function

$$L_S = -\frac{\hbar NS}{w_*} \left( \dot{\phi}_0 X + \frac{K_{\perp} S w}{2\hbar} \sin^2 \phi_0 - \gamma X H \right)$$

$$W_S = \frac{\hbar NS}{w_*} \frac{\alpha w_*}{2} \left[ \left( \frac{\dot{X}}{w_*} \right)^2 + \dot{\phi}_0^2 \right]$$

**$X$  and  $\phi_0$  are conjugate variables**

non-linear relation due to internal  $\phi_0$  degree of freedom (even if the wall is rigid)

# Domain wall motion

## Spin Lagrangian & dissipation function

$$L_S = -\frac{\hbar NS}{w_*} \left( \dot{\phi}_0 X + \frac{K_{\perp} S w}{2\hbar} \sin^2 \phi_0 - \gamma X H \right)$$

$$W_S = \frac{\hbar NS}{w_*} \frac{\alpha w_*}{2} \left[ \left( \frac{\dot{X}}{w_*} \right)^2 + \dot{\phi}_0^2 \right]$$

## Equations of motion for the rigid wall

$$\frac{1}{w_*} \dot{X} - \alpha \dot{\phi}_0 = \kappa_{\perp} \sin 2\phi_0$$

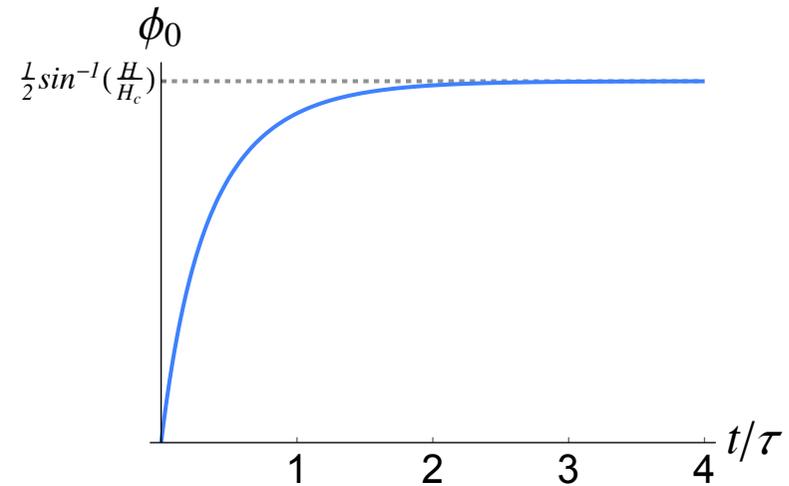
$$\dot{\phi}_0 + \frac{\alpha}{w_*} \dot{X} = \gamma H$$

## Transient behavior

$$\phi_0(t) = \arctan \left( \frac{D \tanh(t/\tau)}{\tau^{-1} + C \tanh(t/\tau)} \right)$$

$$\tau^{-1} = \frac{1}{1+\alpha^2} \sqrt{[\alpha K_{\perp} S / (2\hbar)]^2 - (\gamma H)^2}$$

$$D = \frac{\gamma H}{1+\alpha^2}, \quad C = \frac{\alpha K_{\perp} S / (2\hbar)}{1+\alpha^2}$$



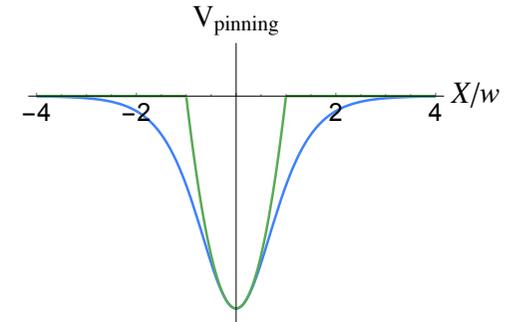
# Domain wall motion

## Pinning

$$V_{\text{pinning}} = - \int \frac{d^3x}{a^3} \Delta K \frac{(Sa)^3}{2} \delta(\mathbf{r}) \sin^2 \theta$$

local change of the easy-axis anisotropy

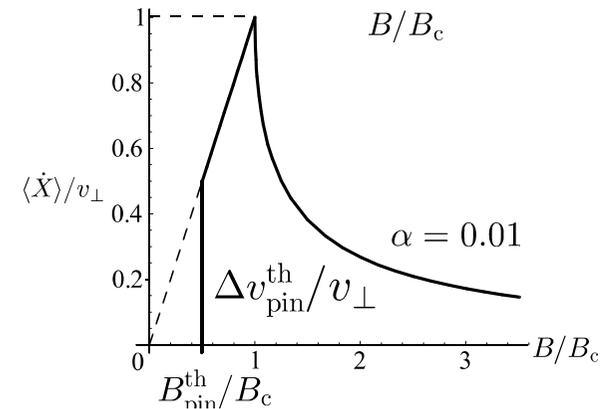
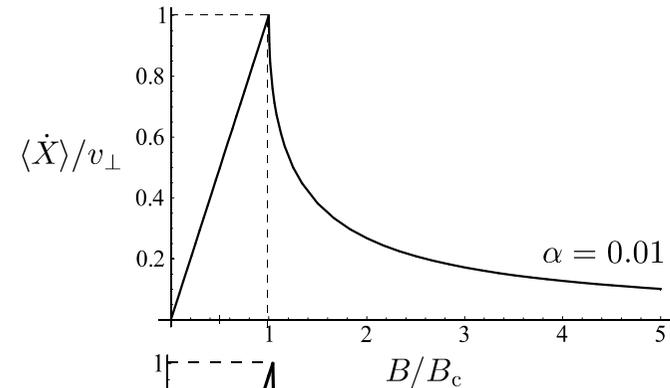
$$V_{\text{pinning}} = \frac{\Delta K S^2}{2} \frac{1}{\cosh^2(X/w)} \rightarrow \frac{M}{2} \Omega^2 (X^2 - w^2) \Theta(w - |X|)$$



## Equations of motion for the rigid wall

$$\frac{1}{w_*} \dot{X} - \alpha \dot{\phi}_0 = \kappa_{\perp} \sin 2\phi_0$$

$$\dot{\phi}_0 + \frac{\alpha}{w_*} \dot{X} = \gamma H - \underbrace{\nu_{\text{pin}} \frac{X}{w_*} \Theta(w - |X|)}_{F_{\text{pinning}}}$$



# Domain wall motion

## Equations of motion

$$\begin{aligned}\frac{1}{w_*} \dot{X} - \alpha \dot{\phi}_0 &= \kappa_{\perp} \sin 2\phi_0 \\ \dot{\phi}_0 + \frac{\alpha}{w_*} \dot{X} &= \gamma H - \underbrace{\nu_{\text{pin}} \frac{X}{w_*} \Theta(w - |X|)}_{F_{\text{pinning}}}\end{aligned}$$

### Linear regime

$$\ddot{X} + 2\alpha\kappa_{\perp}\dot{X} + 2\nu_{\text{pin}}\kappa_{\perp}X = 2\gamma\kappa_{\perp}w_*H$$

domain wall motion  $\rightarrow$  motion of an effective point particle