

## Preparation and characterisation

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Characterisation

x-ray diffraction imaging techniques (SEM, AFM, MFM) differential scanning calorimetry

Preparation (included in Nanostructured Hard Magnets)

sintering hydrogen-assisted methods (HD, HDDR) melt spinning mechanical alloying hot deformation





## Characterisation methods



# Characterisation methods

-X-ray diffraction (XRD)

Crystalline solid screen

------ Spot from incident beam

Spots from diffracted X-rays

> Photographic plate



## X-ray diffraction (XRD)



$$2d_{hkl}\sin\theta = n\lambda$$



Constructive interference  $\rightarrow$  the path length difference = whole number of  $\lambda$ 

**Properties:** 

$$\checkmark \sin \theta = 1 \implies 2d_{hkl} = n\lambda \implies d_{hkl}^{min} = \lambda/2$$

 $\checkmark$  Diffraction pattern is obtained for

 $\theta$  = var,  $\lambda$  = const (powder diffraction, Debye-Scherrer, rotation, Kossel methods)

 $\theta$  = const,  $\lambda$  = var (Laue method)

 $\checkmark$  Positions of reflections are determined by the respective set of cell dimensions



## X-ray diffraction (XRD)

Diffraction  $\rightarrow$  a crystal placed in an incident beam of hard x-rays reflects this beam in many directions



http://itl.chem.ufl.edu/2041\_f97/matter/FG11\_039.GIF



## X-ray diffraction (XRD)



http://cristallo.epfl.ch/flash/crystal\_web\_6\_english.swf

## Structure factor: chemical ordering





## Phase identification

Qualitative  $\rightarrow$  comparison of the observed data with interplanar spacings *d* and relative intensities *I* of known phases

Quantitative  $\rightarrow$ 





#### Problem: overlapping diffraction lines!





## **Rietveld refinement**

Rietveld refinement  $\rightarrow$  a whole-pattern fitting with parameters of a model function depending on the crystallographic structure, instrument features and numerical parameters

Calculated intensity 
$$y_{ci} = y_{bi} + \sum_{p} s_{p} \sum_{k} I_{hkl} \phi(2\theta_{i} - 2\theta_{k})$$
  
background  $\downarrow$  profile function  
scale factor ~ vol. %  
Aim  $\rightarrow$  find a set of parameters ( $\xi$ )

=0

Aim  $\rightarrow$  find a set of parameters (  $\xi$  describing the observed pattern as good as possible

$$U(\xi) = \sum_{i} \frac{1}{y_{i}} (y_{i} - y_{ci})^{2} \qquad \frac{\partial U}{\partial \xi}$$

 $\xi$ : vol. %, lattice and profile parameters, site occupation, preferred orientation...

H. M. Rietveld, J. Appl. Cryst. 2 (1969) 65.



#### Even overlapping peaks contribute information about the structure!



Refined (obtained) parameters

global: background, sample shift

*structural*: phase fraction, lattice constants, profile parameters ( $\rightarrow$  grain size/strain)



## Phase identification: minority phases



Severe overlap of lines  $\rightarrow$  close cell dimensions line broadening due to nanocrystallinity

Lyubina et al., JAP 95 (2004) 7474.

#### Line broadening: grain size and lattice strain $2\theta_2$ Observed diffraction profile $h(2\theta)$ is $h(2\theta) = \int f(y)g(2\theta - y)dy$ a convolution of the physical $f(2\theta) \rightarrow \theta$ and instrumental $g(2\theta)$ profiles $2\theta_1$ $f_{\max_{f(y)}}$ Integral breadth $\int \phi(2\theta) \mathrm{d}(2\theta)$ *h*(2θ) $2\theta_2$ 2θ У *g*(2θ-у)

Separate  $f(2\theta)$  and  $g(2\theta)$  using e.g. integral breadth method

## Line broadening: grain size and lattice strain

Separation of  $f(2\theta)$  and  $g(2\theta)$  using integral breadth method

I) Measurement of a a Standard Reference Material SRM (e.g. LaB<sub>6</sub>)



II) Select the shape of the peak (e.g. pseudo-Voigt) IIIa) Interpolate the FWHM of the SRM | IIIb) De

$$\Gamma_{IRF}^{2} = U \tan^{2} \theta + V \tan \theta + W$$

IVa) Correct

$$\Gamma_{sample} = \sqrt{\Gamma_{measured}^2 - \Gamma_{IRF}^2}$$

IIIb) Decompose it into Lorenzian and Gaussian and correct the integral breadths as

$$\beta_{\rm L}^f = \beta_{\rm L}^h - \beta_{\rm L}^g$$

$$(\beta_{\rm G}^{f})^{2} = (\beta_{\rm G}^{h})^{2} - (\beta_{\rm G}^{g})^{2}$$



### "Average size-strain" method





## Diffraction from amorphous materials

Amorphous materials  $\rightarrow$  the atoms has permanent neighbours, but there is no repeating structure (short range order).

![](_page_15_Figure_2.jpeg)

#### Ball-milled Nd-Fe-B

![](_page_16_Picture_0.jpeg)

## Diffraction from amorphous materials

![](_page_16_Figure_2.jpeg)

![](_page_17_Picture_0.jpeg)

### Properties of neutrons

- Behave either as particels or as waves
- Wavelength varies depending on the source temp.: hot (0.2-1 Å), thermal (1-4 Å), cold (3-30 Å)

![](_page_17_Picture_4.jpeg)

interaction with the nucleus via strong nuclear force  $\rightarrow$  crystal structure determination from diffraction experiments

![](_page_17_Figure_6.jpeg)

#### Magnetic scattering

The neutron possesses a spin  $\rightarrow$  can be scattered from variations in magnetic field via the electromagnetic interaction  $\rightarrow$  magn. structure probe

http://www.ill.fr/index\_ill.html

![](_page_18_Picture_0.jpeg)

![](_page_18_Picture_1.jpeg)

Structure factor

$$|\mathbf{F}_{hkl}|^2 = \left[\sum_{j=1}^{N} f_j \, e^{2\pi i (hx_j + ky_j + lz_j)}\right]^2 \sim \mathbf{I}_{int}$$

**X-rays** 

 $f_{\rm i}$  - atomic form factor

X-rays interact with  $e^{-}$  cloud  $\Rightarrow f_{i} \sim z$  Neutrons

 $f_{\rm i}(b_{\rm i})$  - neutron coherent scattering length

Neutrons interact with the nucleus  $\Rightarrow$ 

 $b_j = \forall$ 

ightarrow Weak absorption  $\Rightarrow$  large penetration depth

Or Possibility to locate light atoms or distinguish neighbouring atoms in the periodic table

් Magnetic structure probe

Example: L1<sub>0</sub> FePt

$$z_{\text{Pt}} (= 78) \gg z_{\text{Fe}} (= 26)$$
$$\Rightarrow f_{\text{Pt}} \gg f_{\text{Fe}} \text{ BUT } b_{\text{Pt}} \approx b_{\text{Fe}}$$

Site occupation (and order parameter S) determination is possible with x-rays, not with neutrons

 $F_{ss} = 2S(f_{Pt} - f_{Fe})$  h+k even

## Magnetic structure by neutron diffraction

![](_page_19_Figure_1.jpeg)

Neutron coherent scattering length  $b_{Pt} \approx b_{Fe}$ 

- Magnetic reflections evolve on cooling around 725 K
- Int. intensity ~ (magnetic structure factor)<sup>2</sup> ~ (projection of m  $\perp \mathbf{k}$ )<sup>2</sup>

APL 89 (2006) 032506

![](_page_20_Picture_0.jpeg)

## **Characterisation methods**

## Scanning electron microscopy (SEM)

# Electron microscopy: interaction of e<sup>-</sup> with matter

![](_page_21_Figure_1.jpeg)

![](_page_22_Figure_0.jpeg)

![](_page_23_Picture_0.jpeg)

## Scanning electron microscopy (SEM)

![](_page_23_Figure_2.jpeg)

Resolution depends on spot size. Resolution in SE better than in BSE ~ several nanometers!

![](_page_23_Picture_4.jpeg)

Sr-Fe-O, courtesy of K. Khlopkov

Secondary electrons (SE)

- low energy ( $\sim 10 \text{ eV}$ )
- surface topographical image
- production is mostly independent of z

#### Backscattered electrons (BSE)

- high energy (> 50 eV)
- large width of escape depth
- heavy elements produce more BSE
  - $\Rightarrow$  atomic number contrast

![](_page_24_Picture_0.jpeg)

## SEM: SE and BSE contrast

#### Secondary electrons (SE)

![](_page_24_Picture_3.jpeg)

#### Backscattered electrons (BSE)

![](_page_24_Picture_5.jpeg)

Sintered Nd-Fe-B magnet, courtesy of K. Khlopkov

#### Surface topography image

Some atomic contrast: BSE produce SE  $\Rightarrow$  heavier elements tend to produce more SE

#### **Compositional contrast**

The higher the atomic number z, the brighter is the contrast

![](_page_25_Figure_0.jpeg)

## Texture analysis

![](_page_26_Figure_1.jpeg)

V. Randle and O. Engler, Introduction to texture analysis, 2000.

![](_page_27_Picture_0.jpeg)

## Texture analysis: XRD

Usual way  $\rightarrow$  pole figure measurements (the statistical directional distribution of poles to a specific lattice plane in a polycrystalline aggregate).

![](_page_27_Figure_3.jpeg)

Y.R. Wang et al., JAP 81 (1997)

![](_page_27_Figure_5.jpeg)

A detector is positioned on the centre of a diffraction peak *hkl* and the sample is rotated  $I_{hkl} \sim$  number of lattice planes

#### **Problems:**

- time consuming (need several reflections for ODF construction)
- complicated in case of low symmetry, peak overlap

### Texture analysis: XRD/Rietveld

![](_page_28_Figure_1.jpeg)

![](_page_29_Figure_0.jpeg)

![](_page_30_Picture_0.jpeg)

## Texture analysis: EBSD

 $Microtexture \rightarrow$  orientation statistics of individual grains and their spatial location

![](_page_30_Figure_3.jpeg)

![](_page_31_Picture_0.jpeg)

## Texture analysis: EBSD

 $Microtexture \rightarrow$  orientation statistics of individual grains and their spatial location

![](_page_31_Figure_3.jpeg)

![](_page_32_Figure_0.jpeg)

![](_page_33_Picture_0.jpeg)

#### Courtesy of N. Scheerbaum

 SEMMar #378.832
 -20µm

p=0.1 µm. EideS74408

#### Black lines: (110) 87°

Resolution:  $1 \ \mu m$ 

![](_page_34_Picture_0.jpeg)

## Texture analysis: EBSD

![](_page_34_Figure_2.jpeg)

![](_page_34_Figure_3.jpeg)

Orientation map from the surface of an isotropic Nd-Fe-B magnet

Resolution here  $\approx$  50 nm

Possible resolution 10-20 nm!

#### Misorientation angle distribution

(probability of each of the possible grain orientations with respect to the sample coordinates)

#### ODF (x-rays/neutrons) → averaged over many grains

![](_page_35_Picture_0.jpeg)

## **Characterisation methods**

# Atomic force microscopy (AFM) and

magnetic force microscopy (MFM)

## AFM

![](_page_36_Figure_1.jpeg)

Forces measured: mechanical contact, Van der Waals, chemical bonding, electrostatic, magnetic...

#### **Operation modes:**

#### Static (contact and non-contact)

Cantilever is continuously contacting (surface damage) or is held above the sample surface (low resolution)

Dynamic (low amplitude and tapping) the cantilever is oscillated close to its resonance frequency; amplitude, phase and resonance frequency is modified by tip-sample interaction

#### Advantages ( $\Leftrightarrow$ SEM)

- true 3D surface profile
- non-conducting samples
- can work under ambient conditions (biology etc.)
- atomic resolution under UHV

Disadvantages ( $\Leftrightarrow$  SEM)

- maximum scanning area ~ 150 $\times$ 150  $\mu$ m
- slow scanning

![](_page_37_Picture_0.jpeg)

### MFM

## Tapping/Lift mode $\rightarrow$ magnetic and topographic data are separated by scanning twice for each scan line

![](_page_37_Picture_3.jpeg)

Magnetic Fields

1<sup>st</sup> scan *tapping mode* AFM (sample topography) → close to the sample surface with a constant amplitude of 5-50 nm; bump/*depression*: less/*more* room to oscillate – amplitude decreases/increases

 $2^{nd}$  scan *lift mode* MFM (magnetic force gradient)  $\rightarrow$  follows the recorded topography, but at an increased scan height to avoid the van der Waals forces that provided the topographic data

![](_page_38_Picture_0.jpeg)

### MFM

#### Imaging high anisotropy materials

- high coercivity tips are required (e.g. CoCr coating  $H_c \approx 4$  kOe)
- for high resolution (limited to  $\approx$  50 nm due to dipole-dipole inter.)
  - small tip radius
  - lift height: 100 nm (restricted by large magn. forces)

![](_page_38_Picture_7.jpeg)

![](_page_38_Picture_8.jpeg)

nominal tip radius of curvature: 40-65 nm

![](_page_39_Figure_0.jpeg)

![](_page_40_Picture_0.jpeg)

## Characterisation methods

## Differential scanning calorimetry (DSC)

![](_page_41_Picture_0.jpeg)

## Thermal analysis: definitions

Differential thermal analysis (DTA)  $\rightarrow$  the temperature difference between a sample and a reference,  $\Delta T$ , is measured as both are subjected to identical heat treatments

Calorimeter  $\rightarrow$  measures heat absorbed or evolved during heating or cooling

**Differential calorimeter**  $\rightarrow$  measures heat ... relative to a reference

Differential scanning calorimeter (DSC)  $\rightarrow$  does the above + ramps the temp. up or down

![](_page_41_Figure_6.jpeg)

$$\Delta \mathsf{T} = \mathsf{T}_{\mathsf{S}} - \mathsf{T}_{\mathsf{R}}$$

"Calorimetric" DTA or heat-flux DSC

![](_page_41_Figure_9.jpeg)

The sample and the reference are maintained at the **same temp.!** 

![](_page_42_Picture_0.jpeg)

## DSC: measurement principles

#### Heat-flux DSC

![](_page_42_Figure_3.jpeg)

#### Power-compensated DSC

![](_page_42_Figure_5.jpeg)

Basis: a homogeneous temperature field in the furnace

Basis: the system is maintained at a "thermal null" state at all times

Heat absorption or loss due to a transition in the sample, difference in  $c_{\rm p}$  between the reference and sample

 $\Rightarrow$  temperature gradients at the thermal resistances of the sensor

 $\Rightarrow$  power (energy) is applied to or removed from the calorimeter to compensate for the sample energy

## **Output signal**

![](_page_43_Figure_1.jpeg)

![](_page_44_Picture_0.jpeg)

## Characteristics of a DSC curve

![](_page_44_Figure_2.jpeg)

Zero line: empty instrument or empty crucibles

Baseline: connects the curve before and after the peak

Peak temperatures:

initial  $T_i$ ; onset  $T_o$ ; peak maximum  $T_m$ ; completion  $T_e$ ; final  $T_f$ 

M.E. Brown, Introduction to thermal analysis (Kluwer Academic, 2001).

![](_page_45_Picture_0.jpeg)

## Characteristics of a DSC curve

![](_page_45_Figure_2.jpeg)

## Zero line: empty instrument or empty crucibles

Baseline: connects the curve before and after the peak

Peak temperatures:

initial  $T_{i}$  ; onset  $T_{o}$  ; peak maximum  $T_{m}$  ; completion  $T_{e}$  ; final  $T_{f}$ 

#### Enthalpy change: $\Delta H = A \times K/m$

**A** – area, **m** – sample mass, **K** – calibration factor (A  $\Leftrightarrow \Delta H$  by melting of a pure metal)

Heat capacity 
$$\mathbf{c_p}$$
:  $\Delta \mathbf{H} = \int_{T_1}^{T_2} \mathbf{c_p} \, \mathbf{dT}$ 

M.E. Brown, Introduction to thermal analysis (Kluwer Academic, 2001).

## What can be measured in DSC?

Exothermic events crystallisation solid-solid transitions decomposition ordering chemical reactions

Endothermic events melting sublimation solid-solid transitions disordering chemical reactions

2<sup>nd</sup> order-type transitions (c<sub>p</sub> change) glass transition Curie point

![](_page_46_Figure_4.jpeg)

## What can be measured in DSC?

![](_page_47_Figure_1.jpeg)

 $\begin{array}{l} \mbox{Exothermic signal} \rightarrow \mbox{healing out of} \\ \mbox{crystal defects} \end{array}$ 

## Interpretation of DSC data $\rightarrow$ use of additional techniques! XRD, microscopy, spectroscopy...

## Effect of heating rate

Kinetically controlled transitions (diffusion, crystallisation, ordering etc.) shift to higher temp. with increasing heating rate

The total heat flow increases linearly with heating rate due to  $c_p$  of the sample

↑ heating rate ↑ sensitivity; ↓ heating rate ↑ resolution DSC /(mW/mg) 5 K/min T<sub>m</sub> ↓ exo 0 -0.2 10 K/min -0.4 -0.6 20 K/min -0.8 -1.0 -1.2 -1.4 40 K/min -1.6 500 200 250 300 350 400 450 Temperature /°C

For obtaining values close to true thermodynamic slow heating rates (1-5 K/min) should be used

## **Kinetics**

![](_page_49_Picture_1.jpeg)

#### Isothermal mode

 $d\alpha/dt = A \exp(-E_{\rm a}/k_{\rm B}T)f(\alpha)$ 

Temperature T = const

Procedure:

- measure transformed fraction  $\alpha(t)$
- plot  $d\alpha/dt = f(t \text{ or } \alpha)$
- determine linearity of  $(d\alpha/dt)$  vs.  $f(\alpha)$

 $f(\alpha)$  - conversion function used for the interpretation of reaction mechanism (KJMA kinetics etc.)

-  $d\alpha/dt = Kf(\alpha) \rightarrow K$  used in Arrhenius plot to calculate activation energy  $E_a$ and Arrhenius parameter A Dynamic (nonisothermal) mode

$$\ln(T_{\rm m}^2 / \beta) = E_{\rm a} / k_{\rm B} T_{\rm m}$$

Heating rate  $\beta = d T/dt = const$ 

![](_page_49_Figure_14.jpeg)

Scr. Mater. 53 (2005) 469; JAP 100 (2006) 94308.

#### Hyper DSC

- a modification of the power-compensated DSC
- very fast scans up to 500 K/min (helps mimic process conditions)

### StepScan DSC

- modulated temperature power-compensated DSC (short interval heating and isothermal-hold steps)

- separates reversible and irreversible effects
- more accurate heat-capacity results since  $C_p$  measurements are generated over short-interval temperature segments

Total heat flow  $dQ/dt = C_p \cdot dT/dt + f(t,T) \rightarrow \text{non-reversing signal}$ (kinetic component)

reversing signal heat flow resulting from temp. modulation ( $c_p$  component)

Simultaneous analysis techniques: DSC-TG, DSC-XRD...

![](_page_51_Picture_0.jpeg)

# Questions?

![](_page_52_Picture_0.jpeg)

![](_page_52_Figure_1.jpeg)

определить невозможно.

 $I_{coh}(Q)$  — интенсивность рассеянного излучения, которую можно измерить экспериментально. Если определить интерференционную функцию S(Q) как

$$S(Q) = I_{coh}(Q)/N b^{2},$$
 (3.17)

то из (3.16) можно получить

$$S(Q) = 1 + \int_{0}^{\infty} 4\pi r^{2} \rho_{0} \{g(r) - 1\} \frac{\sin Q r}{Qr} dr.$$
(3.18)

терференционную функцию S(Q) с парной функцией распределения g(r). Функцию S(Q) часто также называют структурным фактором. Реально сначала определяют функцию S(Q), по которой измеряемую непосредственно в дифракционных экспериментах ин-Равенство (3.18) является основной формулой, связывающей можно затем различным образом найти g(r):

$$g(r) = 1 + \frac{1}{2\pi^2} \int_{0}^{\infty} \{S(Q) - 1\} Q \sin Q r dr.$$
 (3.19)

Представим атом, находящийся в некоторой начальной точке, сферой радиусом r, ведя отсчет от ее геометрического центра. Распределение плотности атомов, находящихся на внешней поверхности этой сферы, определяется как функция радиального распределения ( $\Phi$ PP) и равно  $4\pi r^2 \rho_0 g(r)$ .